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AFAL-TR-76-33

INTERFEROMETRIC LENS TESTING

National Bureau of Standards
Washington, D.C.

September 1976

Technical Report AFAL-TR-76-33
Final Report for Period March 1971 - February 1973

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This report was prepared by National Bureau of Standards, Washington, D.C. The work was performed under Air Force Contract F33615-71-M-5007, Project 76460412. The program was under the technical direction of William C. Martin, AFAL/RWI, Air Force Avionics Laboratory, Wright-Patterson AFB, Ohio.

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In the present study, a wavefront shearing interferometer (WSI) is developed and applied to the on-axis testing of lenses. The simple cube interferometer has all the interferometric adjustments built in during assembly. In contrast to most interferometric test systems, the WSI is inexpensive, portable, relatively insensitive to vibration, does not need laser illumination, and requires only a minimum of experimental time and operational expertise.

Scanning the interferograms and subsequent data reduction are the major effort in testing with the WSI. A computer program for reducing input fringe data to the pupil function, OTF, and aberration coefficients is described; a program to plot the pupil function and OTF is included. Also, a computer program for deriving fringe locations from density data obtained with automatic scanning of the interferograms is described. Sample outputs of the computer programs are given.

Aberrations introduced by the cube interferometer, which is equivalent to a glass plate, are determined. Corrections are automatically made in the computer program for spherical aberration. Defocus can be compensated during testing. Asymmetrical aberrations for test systems greater than f/5 are less than 0.05 wavelength if the cube face is aligned normal to the test-system optical axis within 1/2°.

Results of testing two f/8.7 collimators and an f/8 OTF Standard Test Lens on the WSI are presented. These test results show that one collimator is highly aberrated and the other collimator is nearly diffraction limited. For the OTF Standard Test Lens, the WSI test results are compared with other published test results.

All of the present tests are on axis. Alignment of the lens is a critical factor in determining the on-axis performance and repeating test measurements. Present testing techniques have resulted in root-mean-square differences of less than 0.04 wavelength.

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PREFACE

This report describes a wavefront shearing interferometer system for testing lenses. In addition to the test system and representative data, a complete data-reduction procedure for the resulting interferograms is described. This system can be used to evaluate the in-situ performance of large diameter collimators located at Air Force facilities.

This effort was administered under direction of the Air Force Avionics Laboratory, Dayton, Ohio. The program monitor was Mr. William C. Martin.

Special acknowledgement is made to Richard E. Swing for technical consultation and to Geraldine Hailes for computer programming. The theoretical analysis and the development of algorithms used in computer programming were done by Diana Nyyssonen. The experimental portion of the program, the major part of the written draft, and program management were the responsibility of John M. Jerke.

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I. INTRODUCTION

Optical testing is a necessary step in the design, evaluation and acceptance of optical systems. As a major procurer of lenses, it is important that the sponsor have a viable technique for accurate testing. A standard approach to optical-systems evaluation is the measurement of the optical transfer function (OTF). Methods of measuring the OTF generally fall into one of the following categories [1,2,3]: (1) spatial-frequency analysis of the image of a target of known content; and (2) interferometric determination of the pupil function from which the OTF and spread function may be calculated.

Although most commercially available OTF equipment is based on the first method, the use of targets for frequency analysis is subject to numerous errors. These systems use edges, sine waves, square waves, or slits as either object or scanning aperture. The system is assumed to be incoherent and, therefore, the ratio of the frequency content of the image to that of the object for each frequency yields the modulation transfer function (MTF) of the system without ambiguity. The phase portion of the OTF, or phase transfer function (PTF), is generally determined by measurement of the shift of the image with respect to the object. The accuracy of this method depends on exact knowledge of the transmittance functions of the object and of the The accuracy also depends on the scanning aperture. relative incoherence of the system and, for determining the PTF, depends on the ability to accurately detect small image shifts. For frequencies under 100 cycles/mm, it is not difficult to meet these requirements; however, as the frequency increases, it becomes more difficult to meet As the targets of scanning apertures become smaller, analysis of their frequency content depends on microdensitometry. presently a very inexact method for determination of the transmittance function of small objects, due mainly to the nonlinear effects of the With increased frequency, the relative incoherence instrument [4]. (and linearity) of the system becomes more difficult to assure. Also, detection of small image shifts becomes more difficult when measuring the PTF. For these reasons, high-frequency system analysis favors the improved accuracy of interferometric measurement.

Interferometric testing basically measures the pupil function of the system. From the pupil function, a wealth of other information such as the aberration coefficients, the OTF and the spread function may be obtained to satisfy the particular interests of the systems user [4,5,6]. The pupil function, which cannot be extracted from frequency analysis of an object, is the fundamental quantity of interest when dealing with cascaded optical systems [7] as well as systems employing partially or fully coherent illumination [8]. Measurement of the pupil function is, therefore, necessary to properly evaluate systems of these types and to make accurate predictions of performance.

Most interferometric testing systems are expensive, time consuming and require operational expertise. The wavefront shearing interferometer (WSI) which was chosen for development under the present study eliminates some of the undesirable features of most interferometric testing systems. Since most of the interferometric adjustments are built in at manufacture, the WSI is easy to use with a comparatively short time required for experimental measurements. The WSI is also portable and may be set up quickly on most optical benches. It does not require laser illumination and is relatively insensitive to vibration. In addition, the WSI is inexpensive to manufacture and install.

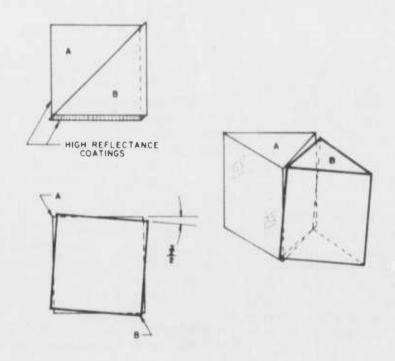
The WSI interferograms cannot be directly interpreted, upon simple inspection, in terms of wavefront aberrations [9]. Hence, the major portion of time and cost in routine operation of this system involves data reduction and analysis. However, with the availability of high-speed computers and fast methods of data accumulation and reduction, the WSI system becomes an inexpensive and reasonable choice for lens testing.

II. DESCRIPTION OF WSI

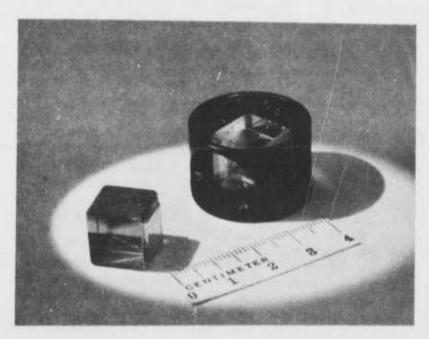
The major component of the wavefront shearing interferometer system described in this report is the cube interferometer of Saunders As shown in figure 1, this cube represents a compact form of a Michelson interferometer. Figure 1(a) and figure 1(b) show schematic and photograph of an assembled WSI cube. The cube consists of two identical 45°-90°-45° prisms cemented along their hypotenuse faces, one of which is coated to transmit and reflect partially. A beam entering the cube is amplitude-divided, and the angle between the axes of the two emerging beams is adjusted to a fixed value \$\Phi\$ by rotating one prism relative to the other about an axis normal to the This rotational adjustment is made when the beam-dividing face. prisms are cemented together. In addition, the zero-order fringe position is permanently adjusted to lie in the center of the cube, thereby assuring equal optical paths for the two beams in the interferometer. Equal light paths allow the use of relatively broadband spectral sources, rather than restricting the use of the WSI to lasers. A discussion of cube parameters is given in section VI.1, and the assembly and adjustment of the WSI cube are discussed in appendix Ε.

The WSI cube may be used for testing lenses at either finite or infinite conjugates as shown in figures 2 and 3, respectively, The test system shown in figure 2 is a single-pass system. For infinite-conjugate testing, the test system may be used in a single or double-pass mode as shown in figures 3(a) and 3(b), respectively. In the arrangements shown in figure 3, a high-quality collimator or mirror is used. If a nearly diffraction-limited collimator or mirror is not available, then the aberrations in the collimator or mirror must be measured and removed from the WSI test data. An alternative, which requires no additional optics, can be used for infinite-conjugate testing of lenses with relatively short focal lengths. In this alternate approach, the pinhole light source is located at a distance from the test lens greater than the lens hyperfocal distance (about twenty or more times the focal length); this test system is single pass.

In all the test systems, the WSI cube is placed in the beam near the image of the light source. Hence, the cube may be treated as an element of an image-forming system. The size of the point source is determined by the degree of coherence required to produce fringes of good contrast. Since coherence is also a function of the propagation distance, shorter-conjugate testing requires smaller light sources and vice versa. For recording the interferogram, an auxiliary lens relays the interference pattern onto the film plane. A stable optical bench forms the basis of the test system; one right-angle arm is required for a single-pass system, two are required for a double-pass system. All elements of the test



(a) Schematic of cube; A and B are 45° - 90° - 45° prisms and Φ is shear angle.



(b) Photograph of assembled cube and cube in holder.

Figure 1. - WSI cube.

system are standard optical equipment with the exception of the cube interferometer and the test-lens nodal slide that has a 90° rotation adjustment about the test-lens optical axis. An alternate procedure to rotating the test lens is to rotate the cube, auxiliary lens, and film plane as a unit about the test-system optical axis. This alternative requires a suitable rotating fixture.

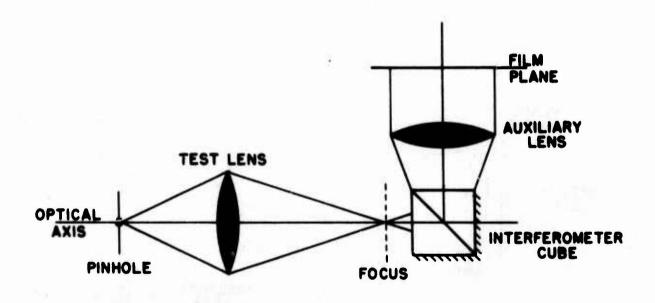
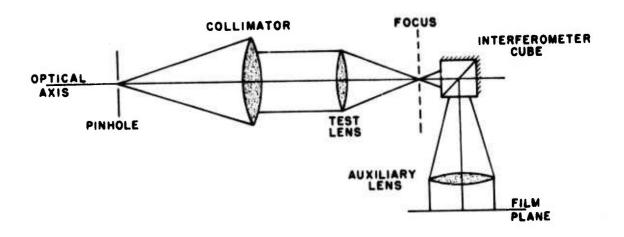
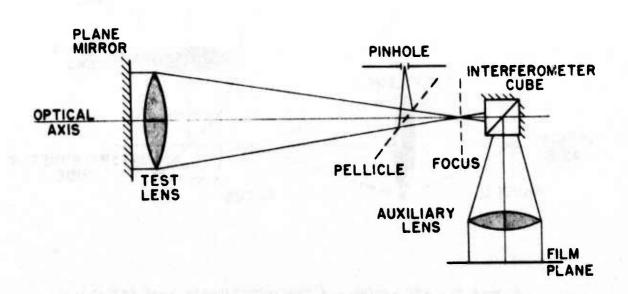


Figure 2. - WSI system for finite-conjugate lens testing.



(a) Single-pass mode.



(b) Double-pass mode.

Figure 3. - WSI system for infinite-conjugate lens testing.

III. ANALYSIS OF OPERATION

As noted earlier, the cube interferometer operates by amplitude dividing the incoming wavefront into two equal parts and introducing a small angular shear Φ (approximately 4 to 40 mrad) into one of the beams. For a cube consisting of $45^{\circ}-90^{\circ}-45^{\circ}$ prisms, the pivot points of the rotation lies in the plane of the back face of the cube as shown in figure 4. With the cube placed near the focus of a converging beam, a small amount of lateral shear $\ell\Phi$ is also introduced. Only for short focal length lenses, however, does the lateral shear become a significant portion of the total shear $\ell\Phi + z_2\Phi$.

Let the wavefront at the exit pupil of the test lens be given by

$$F(x,y) \exp \left\{-ik \left[\left(\frac{x^2+y^2}{2x_2}\right) + \varphi(x,y)\right]\right\}$$
 (1)

where x and y are Cartesian coordinates in the exit pupil, z_2 is the radius of the reference sphere [11], F(x,y) is the amplitude transmittance of the exit pupil, $\varphi(x,y)$ is the aberration function or deviations of the wavefront from the reference sphere, and $k = 2\pi/\lambda$. The pupil function is defined as the complex quantity obtained by removing the reference sphere from equation (1), viz

$$F(x,y) \exp \left[-ik \varphi(x,y)\right]. \tag{2}$$

In the present investigation, the amplitude transmittance is considered to have a constant value of unity over the exit pupil. Pupil functions with nonuniform amplitude can also be treated using the methods of the present investigation; only minor changes in the computation scheme for the pupil function and OTF would be necessary. However, in most cases of practical interest, the variation of the amplitude is very small and can be considered constant.

The WSI interference pattern, as seen in the exit pupil of the test lens, has the form

$$L(x,y) = |F(x,y)|^{2} + |F(x-\ell\phi-z_{2}^{\phi}, y)|^{2} + 2|F(x,y)F(x-\ell\phi-z_{2}^{\phi}, y)|$$

$$\times \gamma_{12}(\tau) \cos \left[\frac{k\ell\phi x}{x_{2}} - \frac{k(\ell\phi)^{2}}{2x_{2}} + k\varphi(x,y) - k\varphi(x-\ell\phi-z_{2}^{\phi}, y) \right]$$
(3)

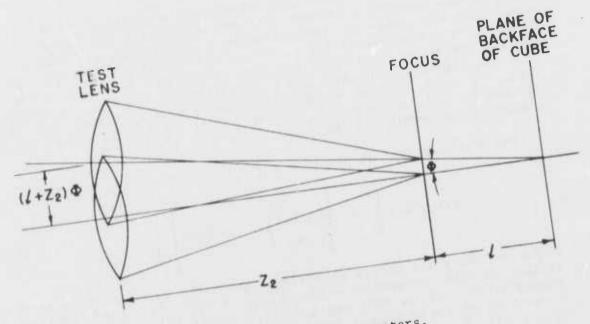


Figure 4. - WSI system parameters.



Figure 5. - Typical WSI interferogram.

where $\gamma_{12}(\tau)$ is the degree of coherence [12] between points on the overlapping wavefronts, and ℓ , Φ , and z_2 are parameters of the system as shown in figure 4. This form of the interference pattern was derived in previous reports [13,14] and is given here in the more general form to account for variations in the amplitude of the pupil function. The interference pattern consists of straight-line reference fringes of frequency $k\ell\Phi/z_2$ with local displacements of $\varphi(x,y)-\varphi(x-\ell\Phi-z_2\Phi,y)$ where the shear has been taken in the positive x-direction and the displacement of one wavefront with respect to the other is $\ell\Phi+x_2\Phi$ (shear distance). A photograph of a typical WSI interferogram is shown in figure 5. Since a single interferogram yields information only in the direction of shear, two interferograms are required with shear in orthogonal directions in order to determine the phase of the pupil function $\varphi(x,y)$.

IV. DATA REDUCTION

The basic data from the WSI system are contained in the two film transparencies of the interference patterns which result from shearing the test-lens wavefront in each of two mutually perpendicular directions. In the present study, these interferograms are enlargements of the fringe patterns photographed with a 35-mm camera in the test set-up. In processing and exposing the enlargements, an effort is made to preserve the maximum detail in the film-density variation at the fringe peaks to permit a more accurate determination of their position. A detailed discussion of interferogram quality is given in section VIII.3.

The interferograms were scanned to locate the fringe peaks either manually using a Grant Comparator or automatically with an Optronics Photoscan P-1000 microdensitometer [15]; one of these automatic digital microdensitometers has also been installed at the sponsor's facilities. When scanned automatically, additional data reduction is required as described in section IX.3 and appendix C. The fringes are, therefore, described by an array of numbers (p_{1j}, x_{1j}, y_{1j}) where p_{1j} is the integer order of interference associated with the fringe peak located at (x_{1j}, y_{1j}) in the scanning-device coordinate system.

The two interferograms, or frames, representing the wavefront sheared in orthogonal directions must be oriented in the scanner so that the resulting fringe-peak data can eventually be registered in a common coordinate system. The direction of scanning is generally along the shear direction, and, therefore, the fringe-peak coordinates in one frame must undergo a coordinate transformation to account for a 90° lens rotation or a 90° cube rotation. Fiducial marks must be used to either align the interferograms for scanning or to correct the resulting scan data, thereby reducing registration errors. A discussion or registration errors is presented in section VIII.3, and a technique for registration is given in appendix D.

Given the fringe-peak location array (p_{ij}, x_{ij}, y_{ij}) , computation of the pupil function is based on equation (2). If we set the argument of the cosine equal to the order of interference p(x) for any point in the aperture, we get

$$\frac{k\ell\Phi x}{z_{2}} - \frac{k(\ell\Phi)^{2}}{2z_{\pi}} + k (x,y) - k (x-\ell\Phi - z_{2}\Phi, y) = 2\pi p(x)$$
 (4)

with a similar equation for the y-sheared interferogram. In order to solve for $\varphi(x,y)$, a set of such equations must be generated for a

regular array of points (Xm, Yn) as shown in figure 6. Since only fringe peaks can be located accurately, this requirement necessitates fringe-order values p(x) to be interpolated at the selected coordinates $(X_m,\ Y_n)$. Using the available data for fringe peaks corresponding to integral order numbers, an interpolation scheme based on a spline fit [16], which fits a changing third-degree polynomial to adjacent data points, was chosen. This interpolation method is analogous to reading points from a smoothed curve drawn with a draftman's spline passing through adjacent data points. Because a spline fit makes the first and second derivatives continuous as well as the function, this interpolation is more satisfactory than a linear or second-order interpolation technique whenever the pupil-function variations are large compared to the data-sampling interval. When the variations are small, these methods produce equivalent results. Since do not occur in the lune area of the interferogram, interpolated fringe orders are not available for grid points common to the lens aperture and the lune area; rather than extrapolating fringe orders into the lune area, the calculated pupil function is eventually extrapolated into a small portion of this area where values are not available from solution of the following equations.

If we let the spacing of the grid points be equal to the shear distance $\ell \Phi + z_2 \Phi$ and

$$X_{m} = x/(\ell \Phi + z_{2}\Phi) = m + constant$$
 and
$$Y_{n} = y/(\ell \Phi + z_{2}\Phi) = n + constant$$
 (5)

where m an n are integers, then equation (4) reduces to

$$\left(\frac{\ell\phi}{\lambda z_2}\right)_{m}(\ell\phi + z_2\phi) + \text{constant} + \varphi(X_m, Y_n)/\lambda - \varphi(X_{m-1}, Y_n)/\lambda = p(X_m). \quad (6)$$

If we denote the ratio of shear distance to reference fringe spacing as

$$R = \frac{(\ell + z_2 + 1)}{\left(\frac{\lambda z_2}{\ell + 1}\right)}$$
 (7)

Equation (6) reduces to

$$\varphi(X_m, Y_n)/\lambda - \varphi(X_{m-1}, y_n)/\lambda = p(X_m) - Rm + constant.$$
 (8)

A similar equation results for the same grid points in the y-sheared interferogram. If we define $p(X_m)$ - Rm as the interpolated fringe-

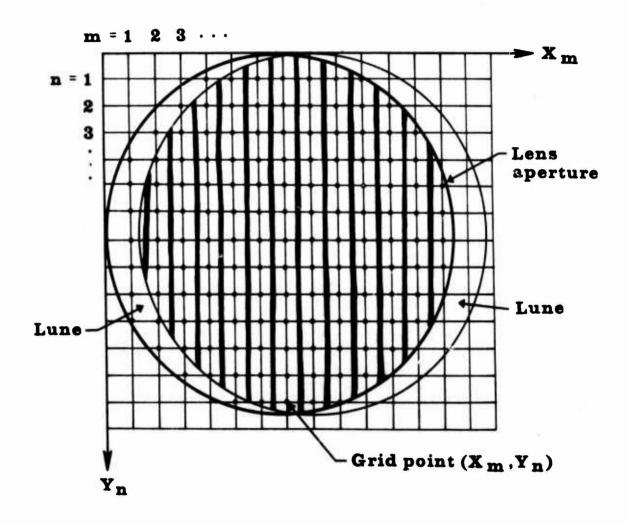


Figure 6.- Grid for interpolated fringe-order array.

order deviations $Q_{m,n}$ for the grid points $(X_m,\,Y_n)$ and similarly define $p(Y_n)$ - Rn as $S_{m,n}$ for the y-sheared interferogram, we have a set of equations

$$\varphi(X_{m}, Y_{n})/\lambda - (X_{m-1}, Y_{n})/\lambda = Q_{m,n} + K_{x}$$

$$\varphi(X_{m}, Y_{n})/\lambda - (X_{n}, Y_{n-1})/\lambda = S_{m,n} + K_{y}$$
(9)

for each grid point with two unknown constants K_X and K_Y for the whole array. For most grid points, a pair of such difference equations exists, always resulting in more than enough equations to solve for $\varphi(X_m, Y_n)$; where more than one equation applies to a grid point, the equations are summed so that all data are used.

The set of difference equations is solved by first assuming that the pupil-function phase is zero at some grid point, preferably near the center of the aperture. The equation for each grid point is then solved successively from this point outward; the unknown constants $K_{\mathbf{x}}$ and Ky will introduce a linear phase term if the solution path is outward from a point in the aperture. For computation of the OTF, a linear phase term will not affect the results [17]. However, if the $\varphi(X_m, Y_n)$ is expanded in a ploynomial with terms corresponding to common lens aberrations, the linear phase term will automatically be isolated and may be removed from a plot of the wavefront. This method of solution was adopted after it was shown that iterative techniques such as that used by Saunders and Bruening [18] did not converage properly near the edges of the exit Combining the set of equations as in equation (9) results in far fewer equations than unknowns and, thus, requires more boundary conditions than the single, zero-value reference point used in the present investigation.

The lens aberrations are determined by least-squares fitting the polynomial containing the appropriate aberration coefficients to the computed $\varphi(X_m, Y_n)$. The least-squares fitting requires the minimization of the square of the difference between the input wavefront based on interferometric data and the analytic wavefront described by the twenty-three term polynominal in X and y, viz,

$$b_{n} \left\{ \sum_{i}^{\infty} \left[\varphi_{i}(x,y) - \sum_{n=1}^{23} b_{n} P_{n}(x,y)_{i} \right]^{2} \right\} = 0 \quad (10)$$

where P(x,y) is the set of polynomials describing the aberrations, and b 's are constant coefficients. In the present investigations, the pupil-function values that were determined by

setting $(X_m, Y_n) = 0$ for one grid point and successively solving equation (9) were then substituted into equation (10). Various polynomials may be used, including a power series in Cartersian coordinates or polar coordinates [19]. The terms in the series are frequently grouped so that they may be identified with particular aberrations. The series used here is similar to that of reference 20 and for axial images contains the terms shown in table 1(a). An alternate polynomial of the form

$$\sum_{m} \sum_{n} c_{m,n} x^{n} y^{m}$$

may be used as in the current USAF Lens Design Program FROLIC. The equivalent relationships between these coefficients and those used on the present study are given in table 1(b). Although these twenty-three terms do not include all the terms resulting from a general eight-order power-series expansion of the wavefront, the terms corresponding to third and fifth-order aberrations such as coma, astigmatism and seventh-order spherical aberrations, which are commonly treated in lens design, have been included. After determining the b_n 's of the aberration coefficients from equation (10) by use of matrix theory, the resulting analytic wavefront or pupil function expressed in actual lens coordinates can be written as

$$\varphi(x,y) = \sum_{n=1}^{23} b_n P_n(x,y)$$
 (11)

from which the constant term b_1 , the x-tilt term b_2x , and the y-tilt term b_3y are subtracted to give the pupil function with respect to the exit-pupil plane. This data reduction is performed by the computer program described in appendix A.

TABLE 1. - ABERRATION TERMS FOR WSI DATA REDUCTION AND COMPARISON WITH TERMS IN USAF LENS DESIGN PROGRAM FROLIC

(a) ABERRATION TERMS

n	$F_{n}(r,\theta)$	$F_n(x,y)$	Type
1	constant	constant	constant
2	r cos θ	х	x tilt
3	r sin θ	У	y tilt
4	r^2	$x^2 + y^2$	focus
5	r^2 cos 20	$x^2 - y^2$	0° astigmatism (3rd)
6	r² sin 2θ	2xy	45° astigmatism (3rd)
7	$r^3 \cos \theta$	$x(x^2 + y^2)$	x coma (3rd)
8	r^3 sin θ	$y(x^2 + y^2)$	y coma (3rd)
9	$r^3 \cos 3\theta$	$x(x^2 - 3y^2)$	x clover (3rd)
10	$r^3 \sin 3\theta$	$y(3x^2 - y^2)$	y clover (3rd)
11	r ⁴	$(x^2 + y^2)^2$	3rd spherical
12	r ⁴ cos 2θ	$x^4 - y^4$	0° astigmatism (5th)
13	r ⁴ sin 20	$2xy(x^2 + y^2)$	45° astigmatism (5th)
14	r ² cos 40	$x^4 - 6x^2y^2 + y^4$	
15	r4 sin 40	$4xy(x^2 - y^2)$	
16	$r^5 \cos \theta$	$x(x^2 + y^2)^2$	x coma (5th)
17	$r^5 \sin \theta$	$y(x^2 + y^2)^2$	y coma (5th)
18	r ⁵ cos 30	$x^5 - 2x^3y^2 - 3xy^4$	x clover (5th)
19	r ⁵ sin 30	$3x^4y + 2x^2y^3 - y^5$	y clover (5th)
20	$r^5 \cos 5\theta$	$x^5 - 10x^3y^2 + 5xy^4$	=
21	r ⁵ sin 50	$5x^4y - 10x^2y^3 + y^5$	
22	r ⁶	$(x^2 + y^2)^3$	5th spherical
23	r ⁸	$(x^2 + y^2)^4$	7th spherical

TABLE 1. - CONTINUED

(b) COMPARISON OF COEFFICIENTS FOR FROLIC AND WSI

Polynomial term	FROLIC coefficient, c _{m,n}	WSI coefficient, b _n
1	°0,0	b ₁
х	c _{1,0}	b ₂
x ²	c _{2,0}	b ₄ + b ₅
x ³	°3,0	b ₇ + b ₉
\mathbf{x}_{t}	°и,0	b ₁₁ + b ₁₂ + b ₁₄
x ⁵	c _{5,0}	b ₁₆ + b ₁₈ + b ₂₀
x ⁶	c _{6,0}	b ₂₂
x ^ε	c8,0	b ₂₃
У	°0,1	b ₃
хy	c _{1,1}	²⁶ 6
x ² y	c _{2,1}	b ₈ + 3b ₁₀
x ³ y	^c 3,1 =	^{2b} 13 + ^{4b} 15
x ⁴ y	c _{4,1}	b ₁₇ + 3b ₁₉ + 5b ₂₁
y ²	c _{0,2}	b ₄ - b ₅
xy ²	c _{1,2}	b ₇ - 3b ₉
x ² y ²	c _{2,2}	26 ₁₁ - 66 ₁₄
x^3y^2	°3,2	2b ₁₆ - 2b ₁₈ - 10b ₂₀
x^4y^2	c _{4,2}	3b ₂₂
x^6y^2	c _{6,2}	4b ₂₃
y ³	°0,3	b ₈ - b ₁₀
xy ³	c _{1,3}	2b ₁₃ - 4b ₁₅
x ² y ³	c _{2,3}	2b ₁₇ + 2b ₁₉ - 10b ₂₁

TABLE 1. - CONCLUDED

(b) CONCLUDED

Polynomial term	FROLIC coefficient, c _{m,n}	WSI coefficient, b _n
y ^l 4	°0,4	b ₁₁ - b ₁₂ + b ₁₄
xy ⁴	°1,4	b ₁₆ - 3b ₁₈ + 5b ₂₀
x ² y ⁴	°2,4	3b ₂₂
x ⁴ y ⁴	c ₄ ,4	^{6b} 23
y ⁵	°0,5	b ₁₇ - b ₁₉ + b ₂₁
y ⁶	^c 0,6	p ⁵⁵
x ² y ⁶	c _{2,6}	^{4b} 23
y ⁸	c _{0,8}	_p 53

V. OPTICAL TRANSFER FUNCTION

V.1. Computation

The two-dimensional optical transfer function (OTF) of a lens can be written as the autocorrelation of the pupil function, viz,

$$OTF(k_{x},k_{y}) = \frac{1}{A} \iint_{\Omega} exp \left\{ -\frac{2\pi i}{\lambda} \left[\varphi \left(x + k_{x}, y + k_{y} \right) - \varphi(x,y) \right] \right\} dxdy \qquad (12)$$

where k_x and k_y are reduced spatial frequencies, σ is the region of integration defined by the convolved aperture, and A is the area of the exit pupil. In the present case, the phase of the pupil function $\varphi(x,y)$ is determined for grid points with a spacing of Δx and Δy ; therefore the reduced spatial frequency coordinates will be given by

$$k_{x} = m \Delta x$$

$$k_{y} = n \Delta y$$
(13)

where Δx and Δy were both chosen equal to the shear distance, and m and n are integers.

The evaluation of the OTF as given by equation (12) can be rather inaccurate or time consuming if a conventional approach to integration such as Simpson's Rule is employed. The difficulty arises from the occurrance of a rapidly changing phase over a small region of integration in the presence of lens aberrations. Other methods for evaluating equation (12), such as those of Hopkins [21] and Barakat [22], represent a tradeoff between accuracy and computation time. A modification of the Hopkins method utilizing the computed aberration coefficients was chosen in the present study.

Expanding the phase part of the pupil function in a two-dimensional Taylor Series about the point (x,y), we can write

$$\varphi(x + k_{x}, y + k_{y}) - \varphi(x, y) = k_{x} \left[\frac{\partial \varphi(x, y)}{\partial x} \right] + k_{y} \left[\frac{\partial \varphi(x, y)}{\partial y} \right]$$

$$+ \frac{1}{2} \left[k_{x}^{2} \frac{\partial^{2} \varphi(x, y)}{\partial x^{2}} + 2k_{x} k_{y} \frac{\partial^{2} \varphi(x, y)}{\partial x \partial y} + k_{y}^{2} \frac{\partial^{2} \varphi(x, y)}{\partial y^{2}} \right]$$

$$+ \frac{1}{6} \left[k_{x}^{3} \frac{\partial^{3} \varphi(x, y)}{\partial x^{3}} + 3k_{x}^{2} k_{y} \frac{\partial^{3} \varphi(x, y)}{\partial x^{2} \partial y} \cdot \cdot \cdot \right] + \cdot \cdot \cdot (14)$$

Substituting the polynomial representation of $\varphi(x, y)$, as given by equation (11), into equation (14) we get

$$V(x,y,k_{x},k_{y}) = \frac{1}{\lambda} \sum_{n=1}^{23} b_{n} \left(k_{x} \frac{\partial}{\partial x} + k_{y} \frac{\partial}{\partial y} + \frac{k_{x}^{2}}{2} \frac{\partial^{2}}{\partial x^{2}} + k_{x} k_{y} \frac{\partial^{2}}{\partial x^{2}y} + \frac{k_{y}^{2}}{2} \frac{\partial^{2}}{\partial y^{2}} + \frac{k_{x}^{3}}{3} \frac{\partial^{3}}{\partial x^{3}} + k_{x} k_{y} \frac{\partial^{3}}{\partial x^{2} \partial y} + \dots \right) P_{n}(x,v) . (15)$$

Therefore, equation (12) may be written as

$$OTF(k_x,k_y) = \frac{1}{A} \iint exp \left[-2\pi i \ V(x,y,k_x,k_y) \right] dxdy$$
 (16)

which is the integral to be evaluated. The phase of the pupil function was determined earlier at grid points (X_m, Y_n) with grid spacing Δx . Over an elemental area defined by $x = X_m + x/2$ and $y = Y_n + \Delta x/2$, a two-dimensional Taylor expansion of $V(x, y, k_x, k_y)$ can be performed in which the first three terms determine the contribution of that region of integration to a good approximation. Writing the first three terms of the expansion about the point (X_m, Y_n) , we have

$$V_{m,n} = V(x,y,k_n,k_y) = V(X_m,Y_n, k_x,k_y) + \frac{\partial V(X_m,Y_n,k_x,k_y)}{x} (x-X_m) + \frac{\partial V(X_m,Y_n,k_x,k_y)}{\partial y} (y-Y_n).$$
 (17)

Therefore, the integral of equation (15) becomes

$$OTF(k_{x},k_{y}) = \frac{1}{(\Delta x)^{2}} exp \left\{-2\pi i V_{m,n}\right\}$$

$$\times \int_{(X_{m}-\frac{\Delta x}{2})}^{(X_{m}+\frac{\Delta x}{2})} \int_{(Y_{n}-\frac{\Delta x}{2})}^{(Y_{n}+\frac{\Delta x}{2})} exp \left\{-2\pi i \left[\frac{\partial V_{m,n}}{\partial x} \cdot (x-X_{n}) + \frac{\partial V_{m,n}}{\partial y} \cdot (y-Y_{n})\right]\right\}^{(18)} dxdy.$$

After a change of variables and integration, we obtain

OTF
$$(k_x, k_y) = \frac{1}{(\Delta k)^2} \exp \left\{-2\pi i \ V_{m,n}\right\} \times \left\{ sinc \left[2\pi \frac{x}{2} \frac{\partial V_{m,n}}{\partial x}\right] \right\}$$

$$\times sinc \left[2\pi \frac{\partial x}{\partial y} \frac{\partial V_{m,n}}{\partial y}\right] \right\}$$

where

sinc
$$x = (\sin x)/x$$
.

Assuming that the contribution of equation (18) for each elemental area is accepted or rejected depending on whether or not it lies within the region or integration, the OTF may be written as

OTF
$$(k_m, k_y) = \frac{1}{N} \sum_{m} \sum_{n} \exp \left\{-2\pi i V_{m,n}\right\} \times \left\{ sinc \left[2\pi \frac{\Delta x}{2} \frac{\partial V_{m,n}}{\partial x} \right] \times sinc \left[2\pi \frac{\Delta x}{2} \frac{\partial V_{m,n}}{\partial y} \right] \right\}$$
 (20)

where N is the total number of grid points for which there are data in the lens aperture. The reduced coordinates may be converted to real spatial frequencies by the relations $\mu_x = k_x/\lambda z_2$ and $\mu_y = k_y/\lambda z_2$.

This method of computation of the two-dimensional OTF was found to have superior accuracy especially for rapidly varying phase functions. For 25 fringes (approximately 400 sampling points) the two-dimensional OTF can be computed on the Univac 1108 computer [15] in less than two minutes. The present approach determines the two-dimensional OTF for all grid points (X_{m_i}, Y_n) ; computation time can significantly by calculating only tangential and sagittal cross sections of the OTF. While fast Fourier transforms [23] applied to an two-dimensional array of grid points would reduce computation time, the accuracy would not be equivalent without a considerable increase in array size; optimizing the computation of the OTF for both time and accuracy is under study.

V.2. Variation with Focus Position

As noted in equation (3), the nominal frequency $kl\phi/z_2$ of the fringes seen in the interferograms is a function of the displacement ℓ of the cube backface from the test-lens focal plane. For a given interferogram, the total distance $\ell+z_2$ is fixed by the test system. This sum of $\ell+z_2$ must be measured and used to calculate the shear distance ΔX which, in turn, is used in the data reduction. (See equations (5)-(7).) The ratio of ℓ to z_2 , however, may be arbitrarily specified. The effect of changing this ratio would be to change the frequency or spacing of the reference fringes from which the local fringe deviations are measured. This change is equivalent to changing the radius of the reference sphere [11] and thereby, the focus position. The ratio of ℓ to z_2 corresponding to a different focus position would be substituted into equation (7); the resulting set of equations given by equation (9) would be solved, and a new OTF would be calculated.

An easier approach to calculating the OTF for a focus change is to alter the pupil function computed for the original value of z_2 . To describe the pupil function for a different focus position z_2' where $z_2 = z_2' + \Delta$, we can rewrite equation (1) as

$$F(x,y) \exp \left\{-ik \left[\left(\frac{x^2+y^2}{2(z_2^1+\Delta)}\right)+\varphi(x,y)\right]\right\}$$
 (21)

Since the reference sphere now becomes

$$\exp\left\{-ik\left(\frac{x^2+y^2}{2z_2^1}\right)\right\} , \qquad (22)$$

we regroup equation (21) in the form

$$F(x,y) = \exp \left\{-ik \left[\left(\frac{x^2 + y^2}{2z_2^{\dagger}} \right) + f(x,y,\Delta) + \varphi(x,y) \right] \right\}$$
 (23)

where

$$f(x,y,\Delta) = \frac{x^2 + y^2}{2(z_2^{\dagger} + \Delta)} - \frac{x^2 + y^2}{2z_2^{\dagger}}$$
 (24)

or

$$f(x,y,\Delta) = -\frac{\Delta(x^2 + y^2)}{2z_2^*(z_2^* + \Delta)}$$
 (25)

Therefore, the new pupil function is given by

$$F(x,y) = \exp \left\{-ik \left[\left(\frac{x^2 + y^2}{2z_2^{\dagger}}\right) + \varphi_{\Delta}(x,y) \right] \right\}$$
 (26)

where

$$\varphi_{\Delta}(x,y) = \varphi(x,y) - \frac{\Delta(x^2 + y^2)}{2z_2'(z_2' + \Delta)}$$
 (27)

Thus, if F(x,y) is known for any one focus position, the pupil function for any other may be determined from equations (26) and (27).

The change of focus as expressed by equation (25) corresponds to changing only the defocus term in the polynomial representation of the pupil function,

$$(\delta b_4)(x^2 + y^2) = -\frac{\Delta(x^2 + y^2)}{2z_2^*(z_2^* + \Delta)}$$
 (28)

where δb_4 is the difference between the defocus coefficient obtained from the original pupil function and the defocus coefficient corresponding to a different focal position z_2 . The choice of Δ , which is the difference in focal positions along the optical axis, is arbitrary, but should depend on the nominal depth of focus expected from the test lens. The present version of the computer program to reduce WSI fringe data has the option of incrementing the focus position in fractional units of the Rayleigh depth-of-focus criterion [24] given by

$$\Delta = F \left[\frac{\pm 3.2 \left(\frac{\lambda}{2\pi} \right) \left(\frac{z_2}{a} \right)^2} \right]$$
 (29)

where F is the fractional value, a is the aperture radius of the test lens, z_2 is the nominal focal length or image conjugate of the test lens, and λ is the radiation wavelength. Using equations (27), (28), and (29), the pupil function is computed. This procedure is repeated for different values of Δ on both sides of the original focus position z_2 until the minimum value for the root-mean-square of the wavefront is obtained. The resulting value of z_2' represents the optimum focal plane.

VI. CUBE INTERFEROMETER

VI.1. Parameters

Since the cube is equivalent to a glass plate of dimensions t x t x 2t, the relationship of the minimum cube dimension t_{min} to f-number of the system under test is determined by the focal position as shown in figure 7. If the acceptance angle of the cube is μ , then

$$f# = 1/(2tan\mu)$$
. (30)

Using Snell's law, the acceptance angle becomes μ inside the cube and

$$\sin \mu = N \sin \mu' \tag{31}$$

where N is the index of refraction of the cube glass. Because the beam is focused a distance ℓ from the backface of the cube, the relationship of maximum acceptance angle μ^* to the cube dimension is given by

$$\tan \mu' = \frac{t/2}{t+\ell} \tag{32}$$

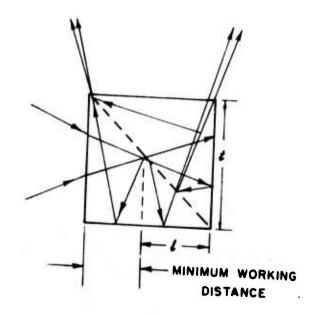
Combining equation (30), (31) and (32) and letting the fringe spacing equal the shear distance ($\ell = \lambda/\Phi^2$) yields

$$f# = \frac{5t^2 - N^2t^2 + 8\lambda t/\phi^2 + 4\lambda^2/\phi^4}{4N^2t^2} .$$
 (33)

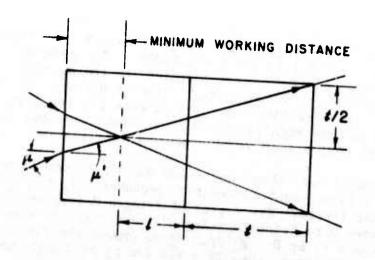
The f-number versus t_{min} is plotted in figure 8 for several cube shear angles with λ = 546.1 nm and N = 1.46008. In general, the minimum working distance (t-l) corresponding to the distance from the lens surface or flange to focus, rather than f-number, is the limiting parameter in selecting the proper cube for testing; however, this limitation becomes significant only for high numerical-aperture, short focal-length optics such as microscope objectives.

The choice of shear angle for the WSI system is governed by the number of fringes required and the f-number of the optical system system being tested. The number of fringes M is given by the ratio of lens diameter D to fringe spacing ΔF where D is related to f-number and conjugate z_2 by $D = z_2/f\#$. If we choose the fringe spacing equal to the shear distance, then $\Delta F \approx z_2 \Phi$ for $z_2 >> 2$ and combining these expressions yields the relationship

$$\Phi = 1/M f\#. \tag{34}$$



(a) WSI cube.



(b) Equivalent glass plate.

Figure 7. - Schematic of light path in WSI cube of thickness t and in equivalent glass plate of thickness 2t.

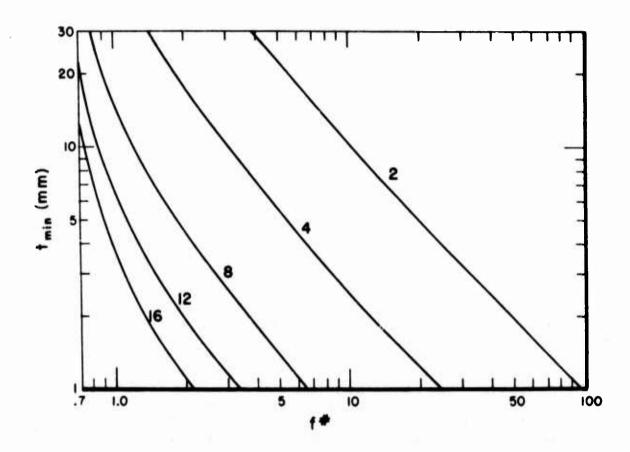


Figure 8.- Minimum WSI cube dimension as a function of f-number for given shear angles Φ .

If we let M equal 25 in equation (34), we obtain the values shown in table 2(a) for the best choice of shear angles to be used with testing a wide range of optical systems. These values are based on straight-line, equally-spaced fringes characteristic of well-corrected optical systems, fringe spacing equal to the shear distance, and $z_2 > 2$; for highly aberrated lenses or in cases where the ratio 2/2 is greater than approximately 0.1, it may be necessary to use a different shear angle to produce 25 fringes. The choice of 13 mm for the cube dimension exceeds the minimum requirements of equation (33) and furthermore, it is not difficult to polish such cube surfaces to 2/20 flatness. Hence, the optimum choice of cube parameters is governed by the quality of the test lens, its f-number, and focal length. For a high-quality lens, table 2(a) represents a selection of cubes which would satisfy most lens-testing requirements.

The parameters for the set of cubes delivered to the spongor are given in table 2(b). A comparison with table 2(a) shows that the optimum values of shear angles, or values very close to the optimum, were obtained in fabricating the cubes for the sponsor. This set of cubes should be adequate for testing most of the sponsor's optical systems, such as collimators, with f-numbers down to about f/1 as originally intended in this program. For these systems, 22 >> 1 and, therefore, the available working distance (t-l) will not be the limiting factor as in the case of testing microscope objectives. However, as discussed in the next section, several hundred wavelengths of third-order spherical aberration may be introduced when testing an f/1 system. The resulting fringe pattern for 25 fringes would exhibit highly curved fringes, and the error in locating the fringe peak could be significant. Even though the computer program would automatically remove this large aberration from the data, it is not likely that a measurement accuracy of even 0.01λ could be maintained.

VI.2. Aberrations

Because the WSI cube is part of the imaging system as described earlier, the effects of the cube on the test results are important. The cube is equivalent to a thick glass plate of thickness 2t where t is the length of a cube side. The path traversed by a converging beam of light as it passes through a glass plate is illustrated in figure 9. If the faces of the cube are of interferometer quality and the glass homogeneous, the increase in optical path length introduced by the cube may be calculated from figure 9. Although it is known [25] that a thick glass plate introduces defect of focus and spherical aberration for the case where the optical axis is normal to the face

TABLE 2. - WSI CUBE PARAMETERS^a
(a) GENERAL LENS TESTING

f-number of test element	Shear angle, Φ (milliradians)	Displacement, & (mm)	Minimum working distance (mm)
11.0	3.6	42.1	not limited
8.0	5.0	21.8	not limited
5.6	7.1	10.8	2.2
4.0	10.0	5.46	7.54
2.8	14.2	2.71	10.29
2.0	20.0	1.36	11.64
1.4	28.6	.67	12.33
1.0	40.0	.34	12.66

(b) ASSEMBLED FOR SPONSOR

f-number of test element	Shear angle, ¢ (milliradians)	Displacement, & (mm)	Minimum working distance (mm)		
11.0	3.6	42.1	not	limited	
8.0	5.7	16.8	not	limited	
5.6	7.8	9.0		4.0	
4.0	10.0	5.46		7.54	
2.8	13.9	2.81		10.19	
2.0	20.0	1.36		11.64	
1.4	28.5	.68		12.32	
1.0	40.2	.34		12.66	

^a 13-mm-thickness; 25 fringes; and λ = 546.1 nm.

TEST LENS PLATE

OPTICAL
AXIS

Figure 9. - Schematic of convergent light beam passing through glass plate of thickness 2t.

of the plate and the beam is converging, the derivation was not available in the suitable form to use as a correction to the pupil-function data. Therefore, the optical-path differences were computed for the general case which allows for both symmetric and asymmetric aberrations.

From figure 9, we denote the optical path differences as

$$OPD = (Na + c - b)/\lambda \tag{35}$$

where N is the index of refraction of the cube. For a ray with angle of incidence $\theta + \emptyset$,

$$Na = \frac{Nt}{\cos(\Theta' + \emptyset)},$$

$$b = \frac{t}{\cos(\Theta + \emptyset)}$$

$$c = \frac{t}{\cos(\Theta + \emptyset)} \left[1 - \frac{\cos(\Theta + \emptyset)}{N\cos(\Theta' + \emptyset)}\right]$$
(36)

where

$$\cos(\Theta' + \emptyset) = \sqrt{1 - \frac{\sin^2(\Theta + \emptyset)}{N^2}},$$

$$\sin^2(\Theta + \emptyset) = \frac{y^2 + (x\cos\theta - z_2\sin\theta)^2}{x^2 + y^2 + z_2^2}.$$
(37)

and

Since we are not concerned with a constant increase or decrease in path length, we adjust the optical path differences to zero at the axis by subtracting $(N^2 - 1)/(N^2 - \sin^2 \theta) 1/2$. The resulting expression for the optical-path difference is

OPD =
$$\frac{t}{\lambda}$$
 (N² - 1) $\left\{ \left[N^2 - \sin^2(\theta + \theta) \right]^{-1/2} - \left[N^2 - \sin^2 \theta \right]^{-1/2} \right\}$ (38)

The above expression for OPD may be used as an exact point-by-point correction to the wavefront or may be curve-fitted to the polynomial containing the various aberration terms. Using the polynomial of table f(a), the terms were computed for a cube with f(a) mm and f(a) and f(a) are the solution of the cube are shown in figures 10 through 12 for a range of test-lens f-numbers. These primary aberrations include defocus, spherical aberration, coma, and f(a) astigmatism. Other aberrations, including higher orders of spherical, astigmatism, and coma, are not significant for the given f-numbers and angles. These angular values represent the angle between the test-system optical axis and the normal to the entrance face of the cube.

If the cube is normal to the optical axis, only the symmetric aberrations, defocus and third-order spherical, are significant. Third-order spherical aberration becomes significant (greater than 0.1λ) when testing systems with f-numbers below f/8. However, defocus is relatively large for most optical systems of interest. The defocus introduced by the cube can be compensated during testing if the recommended test procedure discussed in section XI.3 is followed. This procedure requires that the null-fringe position be located by moving the cube until an infinitely-wide dark or light fringe covers the entire test aperture; at this position, the lateral shear 10 is zero. The cube is then moved away from the null-fringe position to the & setting calculated to produce a desirable number of fringes. If the shear distance $l\phi + z_2\phi$ used in scanning the interferograms is based on this ℓ setting, then any resulting defocus in the focal plane at z_2 is due entirely to the lens. If this test procedure is not used, then the data-reduction computer program may be triggered to correct for the defocus introduced by the cube. (See appendix A.) Corrections for third, fifth, and seventh order spherical aberration are automatically made in the computer program. In the present version of the program, the value for the index of refraction N of the cube is 1.46008 (fused silica at λ = 546.1 nm). For testing lenses at a wavelength other than 546.1 nm, there will be a very slight error in the corrections for aberrations since N varies slightly with wavelength.

If the entrance face of the cube is not normal to the optical axis during the lens test, the asymmetrical aberrations of coma and 0° astigmatism may significantly affect the test results. Figure 11 shows that coma can be as large as $0.1~\lambda$ for testing an f/5.6 lens whenever the angle between the normal to the cube face and the test-system optical axis is from 1° to 2°. Whereas, figure 12 shows that the 0°

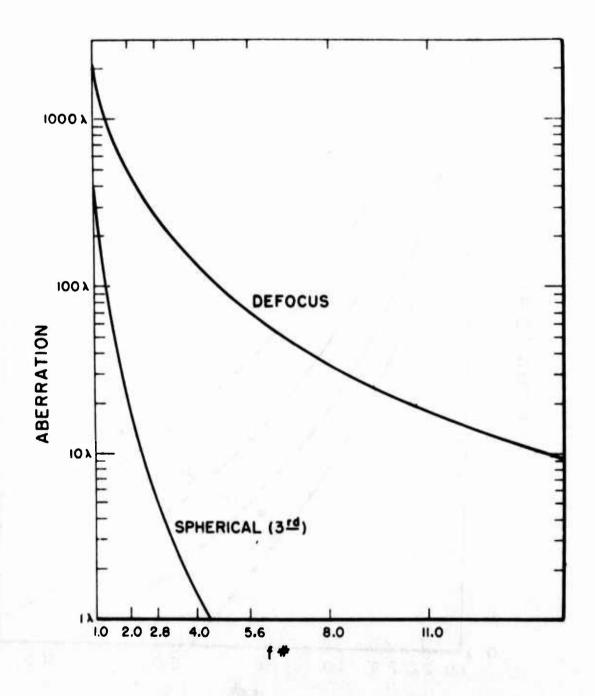


Figure 10. - Maximum values of defocus and third-order spherical aberration introduced by 13-mm-thick WSI cube; λ = 546.1 nm.

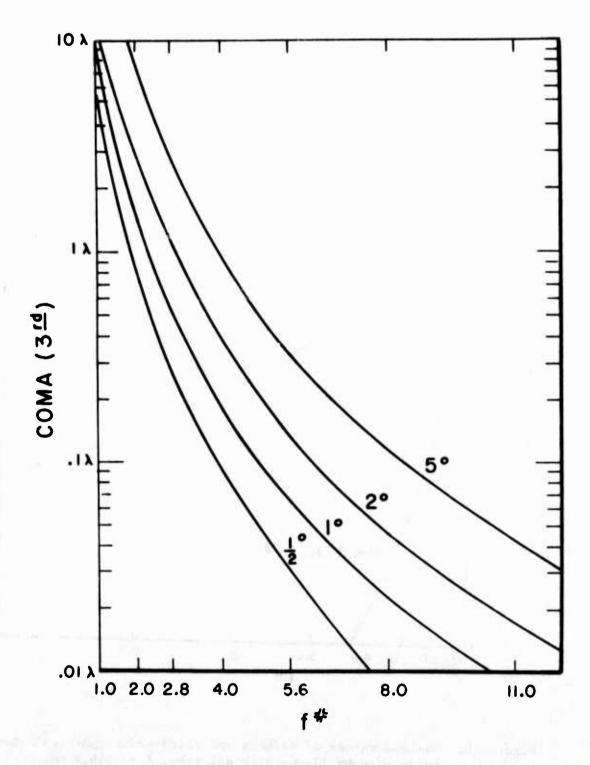


Figure 11.- Maximum values of third-order coma introduced by 13-mm-thick WSI cube for given angles of incidence $\theta + \phi$; $\lambda = 546.1$ nm.

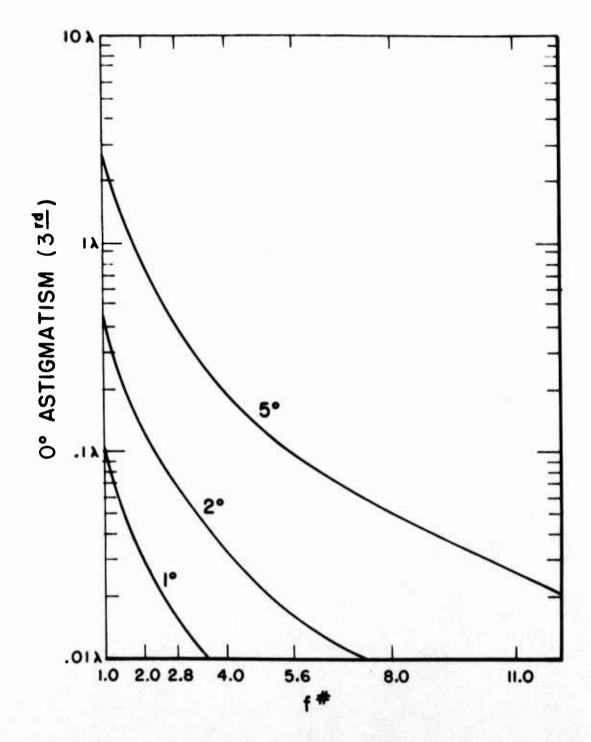


Figure 12.- Maximum values of third-order 0° astigmatism introduced by 13-mm-thick WSI cube for given angles of incidence $\theta+\phi$; λ = 546.1 nm.

astigmatism introduced by this cube misalignment would not be more than about 0.015 λ for testing the f/5.6 lens. Corrections for these asymmetrical aberrations are not included in the computer program. Their magnitude would depend on a measurement of the cube misalignment, and the cube could just as well be aligned during the measurement procedure. A simple technique for aligning the cube is described in section XI.3; this approach permits cube alignment to within 30 seconds which is sufficiently small to eliminate asymmetrical aberrations greater than about 0.01 λ for most lens systems.

Other cube properties such as glass homogeneity and surface flatness may also introduce aberrations. These possible sources of error in the test data are discussed in section VIII.1.

VII. AUXILIARY LENS .

The lens that relays the interferogram onto the film plane is operating in a coherent mode and has its own pupil function; therefore it it essential to know its effect on the measured fringe displacements. It is preferable to use this relay lens as a collimator placed a focal length away from the focus of the test lens. The interference pattern will then be a plane wavefront, and distortion will not be introduced for low f numbers.

In coherent systems, the complex amplitude distribution is propagated through the system, and the squared modulus of the result yields the intensity distribution at the film plane. In the present case, the complex amplitude distribution in one dimension (corresponding to the direction of shear) is the sum of the two sheared wavefronts at the exit pupil of the test lens and is given by

$$\exp\left(\frac{ik x^2}{2z_2}\right) \left\{ \varphi(x) + \varphi(x - \ell \Phi - z_2 \Phi) \exp\left[-ik(\ell \Phi x - \ell^2 \Phi^2/2)/z_2\right] \right\}$$
(38)

where the first exponential term represents the reference sphere and $\varphi(x)$ is the pupil function of the test lens as given be equation (1). If we let the expression in braces in equation (38) be denoted by D(x), the squared modulus of D(x) yields the interference pattern (in one dimension) of equation (3). Propagating the above distribution to the film plane yields an intensity distribution given by

$$I(w) = \left| K \int D(x) \exp \left(\frac{ik \ x^2}{2x_2} \right) \exp \left[-\frac{ik(u-x)^2}{2(z_2+f)} \right] G(u) \exp \left(\frac{iku^2}{2f} \right)$$

$$= \exp \left[-\frac{ik(w-u)^2}{2S} \right] dx du \right|^2$$
(39)

where the coordinates and parameters are shown in figure 13, K is a constant, and G(u) is the pupil function of the auxiliary lens of focal length f. After simplifying,

$$I(w) = \left| K \int \int D(x) \exp \left\{ ik \left[\frac{x^2}{2} \left(\frac{1}{z_2} - \frac{1}{z_2 + f} \right) + \frac{ux}{z_2 + f} \right] \right\} dx \right\} G(u)$$

$$\times \exp \left\{ ik \left[\frac{u^2}{2} \left(\frac{1}{f} - \frac{1}{z_2 + f} - \frac{1}{S} \right) + \frac{uw}{S} \right] \right\} du \exp \left(-\frac{ikw^2}{2S} \right)^2$$

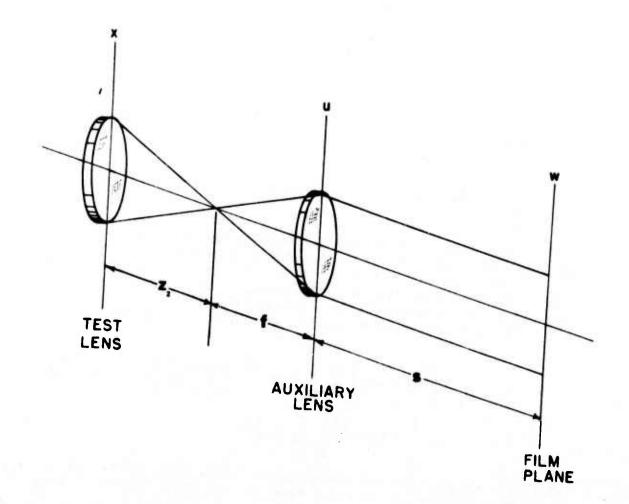


Figure 13. - Parameters and coordinates for computation of effects of auxiliary lens on WSI fringe pattern.

Since D(x) is slowly varying compared to the exponential in the x integral, the Fresnel Integral may be solved by the method of stationary phase [26]. After x integration by this method,

$$I(w) = \left| K' \int D\left(-\frac{uz_2}{f}\right) G(u) \exp\left[ik\left(-\frac{u^2}{2S} + \frac{uw}{S}\right)\right] du \exp\left(-\frac{ikw^2}{2S}\right)\right|^2. \quad (41)$$

The remaining u integral may be solved in the same manner yielding

$$I(w) = K'' \left[D\left(-\frac{wz_2}{f}\right) G(u) \right]^2. \tag{42}$$

For an auxiliary lens of uniform amplitude transmittance, the modulus squared of G(u) is a constant, and we are left with $|D[-(wz_2)/f]|^2$, which is the desired interferogram inverted and scaled by the ratio of z_2/f . Hence, the aberrations of the auxiliary lens, other than distortion, do not effect the measurement of fringe locations.

VIII. ERROR ANALYSIS

VIII.1. Cube Quality and Alignment

The quality of the glass prisms used in fabricating the WSI cubes should be of interferometric quality and thereby, reasonably free of bubbles, inclusions, and other scattering centers. (See appendix E.) Scattered light will reduce fringe contrast, and these scatterers can also appear on the final interferograms. Such patterns can result in fringe-location errors, particularly if coherent illumination is used In this respect, it is also important to keep the for testing. entrance and exit faces of the cube clean. Furthermore, the index of refraction should remain constant throughout the glass. Otherwise, the optical paths for the two beams traversing the WSI may differ and lead to a size difference in the two overlapping sheared images. data interpretation requires that the two sheared images represent the identical wavefront scaled to the same size. The flatness requirements ($\lambda/10$ or better for 546.1 nm) on all prism surfaces used to transmit or reflect light are necessary to limit wavefront errors which could not feasibly be separated from those of the test-lens. The assembled cube can be inspected for residual aberrations by techniques discussed in appendix E.

There are additional aberrations such as defocus, spherical aberration, and coma, introduced by the cube and discussed previously in section VI.2. These aberrations, in contrast to the material and surface errors in the cube, can be calculated and removed from the test data. It should be noted that for testing high-quality lenses (aberrations less than 1 λ) with f-numbers below about f/2, the defocus and spherical aberration become relatively large (greater than 100 λ), and the resulting test data would be highly suspect. It is, therefore, generally recommended that the WSI not be used to test optical systems with f/numbers much below about f/2.

The WSI cube should be positioned in the test system so that the cube entrance face is perpendicular to the test-system optical axis. Provided that the test lens is aligned with its optical axis along the test-system optical axis, the cube entrance face is also perpendicular to the test-lens optical axis. In this arrangement, no asymmetrical aberrations will be introduced by the cube. The effect of cube misalignment is discussed previously in section VI.2. As noted in that discussion, it should be just as easy to align the cube to within a few degrees as it is to measure the misalignment which is required if a correction is to be applied to the wavefront. The only requirement for the lateral position of the cube face in a plane perpendicular to the test-system optical axis is to avoid clipping, or vignetting, of the fringe pattern; no differences in fringe patterns should be observed for different lateral positions of the cube provided that the cube glass is homogeneous.

VIII.2. Experimental

There are several possible sources of error in the experimental set up. Those sources found to be important as a result of testing several lenses include lens alignment, method used to obtain the second or y-sheared interferogram, experimental parameters required as input data for computer reduction of test data, and use of an auxiliary lens to photograph fringe patterns.

A test-system optical axis must first be established for testing lenses with the WSI. Alignment of the test lens along this test-system is required to a high degree of accuracy in order to obtain repeatable measurements of the OTF to within a few percent. This requirement is particularly important when testing multi-element lenses or collimators with a relatively narrow field of view. As an example, repeated tests with an f/8.7 collimator realigned in a nodal slide that could not be accurately positioned showed a variation of up to 0.15 λ in the asymmetric aberrations, such as astigmatism. An improved nodal slide resulted in a reproducibility of less than 0.05 λ in the wavefront. This level of precision was obtained even though the lens was realigned for the y-sheared interferogram. The method used to align the test lens is discussed in section XI.3.

The original approach to obtaining the second or y-sheared interferogram was to rotate the test lens 90°. The nodal slide used for mounting the test lens did not maintain the initial lens alignment as the lens was rotated 90°. Therefore, the lens had to be realigned after the 90° rotation. Successive tests in which the lens was realigned showed non-repeatable values for astigmatism. The realignment of the lens at the 90° setting most likely displaced the lens along the optical axis and, therefore, introduced astigmatism. As a result, a fixture which rotates the relay lens, film plane, and cube as a fixed unit about the optical axis has been built and is used for current lens testing; a photograph of this fixture is shown in figure 14. This fixture maintains the cube at a fixed location along the optical axis during rotation. Furthermore, the ball-pivot assembly for holding the cube permits the cube to be angularly realigned, with essentially no linear displacement, in order to maintain the cube entrance face normal to the optical axis for both the 0° and 90° It is not required that the axis of rotation for this fixture be coincident with the test-system optical axis; as noted earlier, a lateral movement of the cube during rotation should not alter the fringe pattern if the cube material is homogeneous. effect of an angular error in the 90° setting of the fixture has not been determined; however, for high-quality optics with pupil functions that change very little across the aperture, an error of a few degrees would probably have an insignificant effect on the test results. This fixture also keeps the film plane at the same distance from the test lens for the 0° and 90° settings, thereby reducing any magnification changes in the x and y-sheared interferograms.

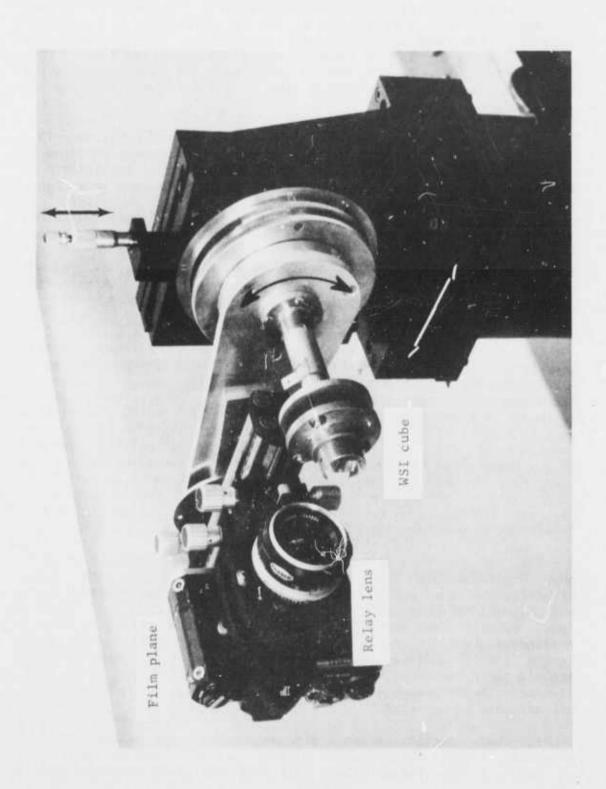


Figure 14. - Photograph of fixture for rotating WSI cube, relay lens, and film plane.

The experimental parameters that are used as input values in the reduction of the interferogram data are the cube shear angle Φ , cube thickness t, radiation wavelength λ , and the sum of $\ell + z_2$. The shear angle Φ must be known accurately since an error in this parameter will generate an error in the calculated shear distance $\Phi(\ell + z_2)$ and, subsequently, in the scanned fringe positions. The cube shear angle can be measured to within \pm 0.05 mrad using the techniques described in appendix E.

The cube thickness should be known to within \pm 0.1 mm. This thickness is used to calculate the symmetric aberrations introduced by the cube as discussed in section VI.2. For testing lenses with f-numbers approaching f/2, these aberrations are significant and, therefore, an error in cube thickness should be more important. For example, an error in cube thickness of 0.1 mm for a f/2.8 test lens would give errors of about 2 λ of defocus and about 0.04 λ of third-order spherical aberration in the aberrations removed from the fringe pattern during data reduction. Considering that the defocus introduced by the cube can be compensated by the experimental procedure described in section VI.2, the remaining error would be about 0.04 λ .

The value of the radiation wavelength used to illuminate the test lens is used throughout the data-reduction computer program such as in solving the basic equations for the pupil function and the aberrations introduced by the cube. (See equations (9) and (37), respectively.) Although an assessment of errors in the wavelength value has not been made it appears that the result of such as error would be to alter the magnitude of the pupil-function values and the OTF values. Provided that a laser or an arc source with a filter of measured or known mean wavelength is used as a light source, the wavelength value should not be a source of error. Also, any filters used should produce a spectral transmission function which is symmetrical about the mean wavelength in order not to distort the cosine finges.

The sum of $\ell + z_2$ is measured directly from the test set up after positioning the cube at the axial position that will give the number of fringes desired for scanning. (See figure 4.) The distance z_2 is the distance from the second principal plane of the test lens to the focal plane. For testing a lens at infinite conjugates with a collimated light source, z_2 is equivalent to the effective focal length (EFL); however, when testing at finite conjugates with a pinhole light source situated at a distance less than the hyperfocal distance (about twenty or more times the EFL), z_2 is not equal to the EFL and must be measured.

For both testing modes, the second principal plane should be physically located using a nodal slide; thus, the total distance ℓ + z_2 could be determined by measuring from this plane to the backface

of the cube. However, for infinite-conjugate testing, the EFL furnished by the lens manufacturer could be used for z_2 ; if this value is incorrect, there will be an error associated with the pupil function as discussed below. In either case if the defocus introduced by the cube is to be eliminated experimentally, a separate measurement of ℓ is required to position the cube to give the desired number of fringes.

The refractive effect of the cube will lead to a slight error in the measured value of the sum $\ell + z_2$ since this value should be measured totally in air. Consequently, there will be a slight error in the calculated shear distance ($\Delta X = \Phi(\ell + z_2)$) used for sampling fringe data from the interferograms and an error in the resulting pupil function. For most lenses, the shear-distance error would be typically less than a few percent; furthermore, most pupil functions are not rapidly varying over the shear distance, so the effect on the calculated pupil function and OTF will be small.

VIII.3. Interferogram Quality, Scanning, and Registration

The errors introduced by the quality of the interferogram are somewhat dependent on the mode of scanning and data reduction used. For any scanning method, a serious attempt should be made to produce interferograms which have density variations approaching a cosine distribution across the light or dark fringes, uniform density values along the fringe peaks, absence of spurious fringe patterns, and are relatively free of pinholes and other film defects. Some of these factors can be controlled in the experimental set up, and others during film processing.

Spurious fringe patterns can be largely avoided by not using a laser for a test light source. As discussed earlier, the WSI cubes are adjusted for chromatic compensation, and, therefore, a filtered white-light source can be used. If a laser is used, special care must be taken to clean all optical surfaces in the test system in order to eliminate diffraction patterns arising from scattering centers. The light source should also illuminate the test lens uni ormly so that there will not be a significant variation in film density along a fringe peak.

It should be noted that although the WSI is relatively insensitive to mechanical vibrations and thermal drifts, these effects can still affect the interferogram quality. For a test lens with a relatively long z_2 value, mechanical vibrations and thermal drifts near the test lens can result in a vibrating or changing interference pattern. If the vibration or thermal sources cannot be eliminated, then short exposure times, depending on the frequency of the disturbance, may help to reduce the problem.

If both light and dark fringes exhibit a flat density distribution across the peak and valley, the interferogram should be discarded, and the interference pattern should be rephotographed. These flat density distributions can result from the improper combination of film and exposure times or in the processing used to make the enlargements for scanning. However, for interferograms in which only the light, or the dark, fringes exhibit finesse, these fringes can be scanned.

There are two types of errors which are dependent on the number of fringes in the interferogram rather than the interferogram quality. The first of these errors may be called the reading error RE and defined as the scanner reading error ϵ divided by the fringe spacing ΔF in the interferogram, viz,

$$RE = \frac{\varepsilon}{\Delta F} \quad . \tag{43}$$

For a given interferogram, we can write the fringe spacing ΔF as the test-lens aperture diameter D (on the interferogram) divided by the number of fringes M, viz,

$$WF = \frac{D}{M} . (44)$$

Substituting equation (44) into equation (43), we obtain

$$RE = \frac{\varepsilon M}{D} .$$
(45)

For the manual scanner (Grant comparator), ϵ = 0.005 mm, D = 50 mm, and typically M = 25; thus, RE = 0.0025 (units of wavelength). For the automatic scanner (Photoscan P-1000), ϵ = 0.050 mm, D = 100 mm, and typically M = 25; thus, RE = 0.0125 (units of wavelength).

The other error which is dependent on the number of fringes in the interferogram is the fringe interpolation error. As discussed in section 4, fringe-order values must be interpolated at coordinates on a grid in order to determine the pupil function. The interpolation approach used in the data-reduction computer program is based on a spline fit. For a lens which has a maximum wavefront error of 2 λ spherical aberration and a WSI interferogram with 22 fringes, the interpolation error is less than 0.001 λ . Although this error is much smaller than the reading error discussed previously, it should be remembered that the interpolation error for the spline fit will depend on the type and magnitude of errors in the test lens and the number of fringes in the interferogram.

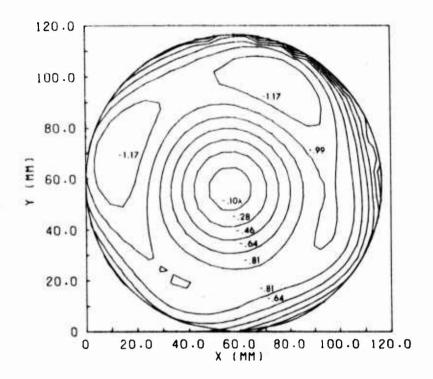
The scanning errors are, of course, directly dependent on the type of facility used for interferogram scanning. The two basic methods of scanning are manual and automatic. The manual approach usually relies on a visual judgment of fringe-peak location, whereas the automatic approach provides film-density data that can be processed to determine fringe-peak locations. The scanner properties which bear directly on the resulting data are resolution, accuracy, quality the of reproducibility, and linearity. Since these properties vary widely depending on the particular scanner and a general discussion of their effects would be lengthy, it is not appropriate to include an analysis in this report. The positional accuracy of placing the interferogram in the scanner is also important, particularly since the data from two WSI interferograms must eventually be registered. This registration is discussed in appendix D, and the possible errors from registration are discussed in the present section.

In order to determine possible differences in fringe data from the automatic scanner (Photoscan P-1000) and the manual scanner (Grant comparator) used in the present tests, interferograms of the same test lens were scanned on each instrument. Since the size of the interferograms used for the two scanning systems is different, two pairs of enlargements were prepared from the original interferogram. The resulting fringe-peak data from both scanners were scaled to the actual lens coordinate system by using the appropriate magnification. The magnification for each pair of interferograms was determined by using an optical comparator to measure a scale appearing in the interferogram; the scale was located near the test-lens exit pupil and was photographed along with fringe pattern. The scaled fringe data from the two scanners were plotted, and these plots were superimposed to provide a direct comparison. These fringe patterns showed a two difference in magnification. An alternate approach to determine the magnification or each interferogram pair is to use a microdensitometer to trace the scale in the interferograms; this approach showed that the magnification difference can be reduced to about 1 percent. In any event, a quantitative comparison of fringe locations is not possible without scaling both sets of fringe data to exactly the same size lens aperture. The comparison did show, however, that the measured magnification can be a source of error in the comparison of fringe data obtained on different instruments that require different size interferograms. For this reason, both sets of fringe data were reduced, and the results are shown in figure 15 and table 3.

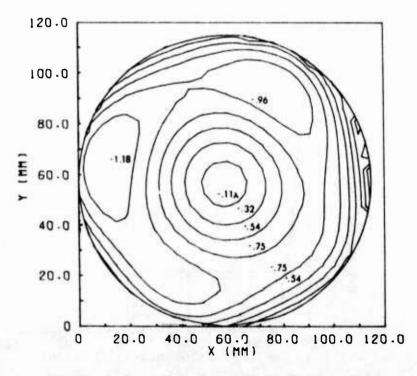
The data shown in figure 15 are for an f/8.7 collimator in the plane of best focus. Figures 15(a), 15(c), and 15(e) are data reduced from interferograms scanned on the automatic scanner, and figures 15(b), 15(d), and 15(f) are data reduced from interferograms scanned on the manual scanner. A comparison of the aperture diameters in figures 15(a) and 15(b) shows the 1-percent difference in the magnification used to scale each set of fringe data. A comparison of the isocontours for the pupil functions in these two figures shows that these distributions appear essentially the same. The root mean square (RMS) of the difference of these two wavefronts normalized to the same coordinate system was calculated to be $0.12~\lambda$. This difference is probably due primarily to registration particularly in the data from the automatic scanner. The improved registration technique discussed in appendix D should eliminate some of these errors.

comparison of figures 15(c) and 15(d) shows only minor differences in the MTF values resulting from the two sets of scanner A comparison of figures 15(e) and 15(f), however, shows large differences in the PTF values. The accuracy of these PTF values for the upper spatial frequencies is not very high. The PTF is defined as the arctangent of the ratio of the imaginary and real parts of the OTF. As discussed in section V.1, the method used to computed the OTF was found to have superior accuracy even for highly aberrated lenses, i.e., lenses with a rapidly varying pupil-function phase. However, at the higher spatial frequencies, the computational accuracy is reduced since fewer points lie within the region of integration. (See equation (20).) Moreover, for highly aberrated lenses such as the collimator discussed in figure 15, the real and imaginary parts of the OTF are very small and fluctuate in sign starting at the mid-range spatial frequencies. Therefore, the calculation of the PTF involves the ratio of very small and rapidly changing values, and the resultant PTF exhibits large and rapid changes in both magnitude and sign as shown in figures 15(e) and 15(f).

A comparison of the maximum aberration values for the manual and autobact scanning in table 3 show that differences between the same type of asymmetric aberrations are less than about 0.05 λ for most of these terms. Only third-order y coma and third-order 45° astigmatism show differences much greater than 0.1 λ . As noted earlier, part of the difference in the two wavefronts is probabily due to registration errors. Such errors could result in differences in the 45°-astigmatism term. (See section X.1.) Although there are large differences between the same type of symmetrical aberration for the manual and automatic-scanner data, the difference in the net sums of these symmetrical aberrations is only 0.04 λ . Therefore, the differences in the aberration terms resulting from the two sets of

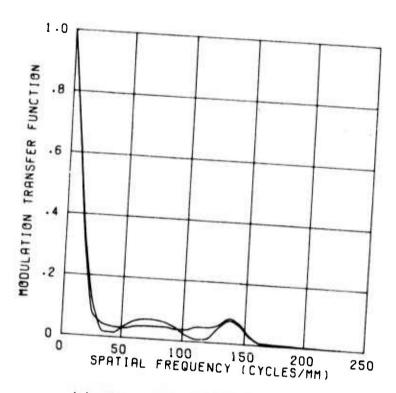


(a) Pupil-function phase; automatic scanner.

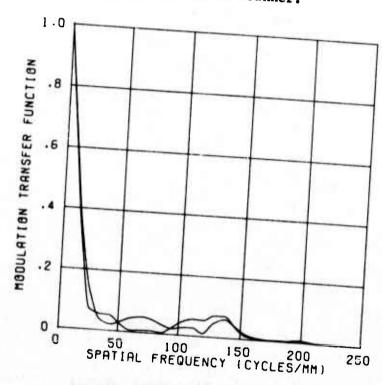


(b) Pupil-function phase; manual scanner.

Figure 15.- Comparison of test results for fringe data obtained from automatic and manual scanning of same pair of WSI interferograms; f/8.7 collimator and λ = 546.1 nm.

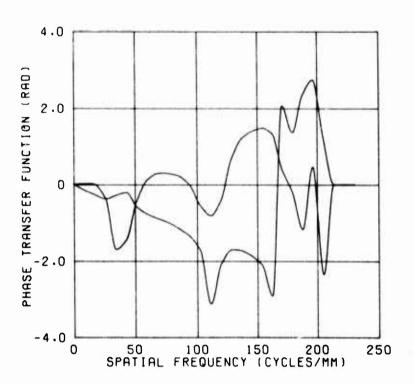


(c) MTF; automatic scanner.



(d) MTF; manual scanner.

Figure 15. - Continued.



(e) PTF; automatic scanner.

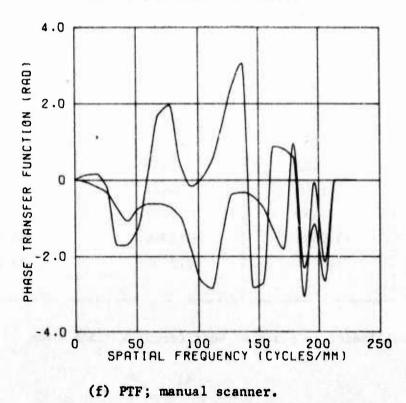


Figure 15. - Concluded.

TABLE 3. - COMPARISON OF MAXIMUM ABERRATIONS RESULTING FROM SCANNING SAME PAIR OF WSI INTERFEROGRAMS WITH MANUAL AND AUTOMATIC SCANNERS^a

	Maximum aberration	ns, units of λ	Туре		
n	Manual	Automatic			
4	-4.821	-5.250	focus		
5	1062	1314	0° astigmatism		
6	. 2080	0461	45° astigmatism		
7	.6441	.1573	x coma (3rd)		
8	3685	6316	y coma (3rd)		
9	. 2209	.1750	x clover (3rd)		
10	1603	0934	y clover (3rd)		
11	7.1699	8.3341	3rd spherical		
12	.1365	.1378	0° astigmatism (5th)		
13	.1297	0020	45° astigmatism (5th)		
14	.0336	.0101			
15	.2568	.2698			
16	1396	.0503	x coma (5th)		
17	.3120	.3054	y coma (5th)		
18	0188	0727	x clover (5th)		
19	.1405	.1033	y clover (5th)		
20	.1164	.0821			
21	.0155	.0192			
22	-3.8634	-5.5946	5th spherical		
23	1.4013	2.3383	7th spherical		

^a f/8.7 collimator in plane of best focus; $\lambda = 546.1$ nm.

scanning data are significant only for the asymmetric terms. It should be noted that differences in a given aberration term for two or more sets of data from different scanners or repeated scans on the same scanner should not always be considered at face value. Even for data from different lenses, the comparison of the same aberration term may be misleading. The polynomial solution for the wavefront is sensitive to random fluctuations in the fringe data, particularly for the higher order terms. Random errors in the fringe-peak positions can result from the scanner and noise in the interferogram.

Repeated scans of interferograms for an f/8.7 collimator were made on the manual scanner in order to determine an over-all RMS value for the scanning process. Resulting aberration values and RMS values for the plane of best focus are given in table 4 for each of the three scannings. Except for the various orders of spherical aberration, focus defect, and y-coma (third and fifth order), the aberration values for the different scans do not differ by more then about 0.05λ . The least-squares fitting of the data to the 23-term polynominal is far more sensitive to the higher-order terms, such as the fifth and seventh-order spherical aberrations; thus, their greater variation for small differences in input fringe data is expected. Furthermore, it is important to look at the net result of adding the focus defect and spherical-aberration terms since this total or residual is more representative of the overall wavefront deviations. Therefore, a comparison of the residual values of these symmetric aberrations as given in table 4(b) shows that the differences between repeated scans is about 0.01λ ; thus, the aberrations in this test lens are primarily coma. A comparison of the RMS of the wavefront for the plane of best focus in table 4(b) shows that these values do not differ by more than 0.01λ . A better indication of the RMS for the scanning process than either the RMS of the wavefront or aberrations [27] is shown in table 4(c). This table gives the RMS of the difference of two wavefronts from the repeat scannings. These values indicate that the repeatability for scanning process on the manual scanner is about 0.02λ . A similar test is planned for the automatic scanner.

As discussed in appendix D, the proper registration of two WSI interferograms requires that each interferogram be scanned parallel to the shear axis. Provided that this axis has been located and marked accurately on each interfergram, the interferogram should be placed in the scanner so that scan axis is parallel to the shear axis. An approach for accomplishing the proper orientation of the interferogram in a scanner is described in appendix D. A modification to the computer software for reducing the data from the automatic scanner could be made to include this approach; the modification would probably be a correction to the fringe-peak data based on the angular tilt of the interferogram. The primary aberration introduced by an

TABLE 4. - COMPARISON OF MAXIMUM ABERRATIONS, RMS VALUES, AND RESIDUAL SYMMETRIC ABERRATIONS RESULTING FROM THREE SCANS OF SAME

(a) MAXIMUM ABERRATIONS

	Ma	ximum aberra	at lone	MAXIMUM A	
n	Scan	Maximum aberration an 1 Scan 2			
4	39			Scan 3	Туре
5	.03	01	357	470	focus
7	.00	- 1	SCANN THE	0533	0° astigmatism
8	.179	1 .17	96	.1479	45° astigmatism
9	.046	.083		.0952	x coma (3rd)
10	.0111	.064	1	.0778	y coma (3rd) x clover (3rd)
11	.9927	1.6469		.0316	y clover (3rd)
12	0304			1.4857	3rd spherical
4	.0328	.0373		.0387	0° astigmatism (5th)
5	0265	0202	-	.0230	45° astigmatism (5th)
ě	1372	0050		.0019	
	1907	1800	1	.1679	x coma (5th)
	0658	0590	1	.0474	y coma (5th)
	0877	0728	1	0840	x clover (5th)
	0053 0165	0057	1	0057	y clover (5th)
	-1.2698	.0150		0156	
	.6658	-2.3947 1.2664	-2.1		5th spherical
7 col1		Countries on the formal bearing of the formal	1.1	085	7th spherical

 $^{^{}a}$ f/8.7 collimator in plane of best focus; $\lambda = 632.8$ nm.

TABLE 4. - CONCLUDED

(b) RMS VALUES AND RESIDUAL SYMMETRIC ABERRATIONS

	Scan 1	Scan 2	Scan 3
RMS	λ/20.625	λ/25.754	λ/24.547
Residual symmetric aberrations ^a	006λ	 019λ	.017۸

^a $b_4F_4 + b_{11}F_{11} + b_{22}F_{22} + b_{23}F_{23}$ where b_nF_n is the nth aberration.

(c) RMS OF DIFFERENCE OF TWO WAVEFRONTS

	Scan 1 and	Scan 2 and	Scan 1 and
	Scan 2	Scan 3	Scan 3
RMS	.017λ	.013λ	.023λ

angular error in one or both of the interferograms during scanning is 45° astigmatism. For example, a rotational difference of about 1° in the scanning orientation of the two interferograms could introduce about 0.2 λ of third-order 45° astigmatism.

In addition to defining the shear direction on an interferogram, a fiducial system must differentiate between the x and y-sheared interferograms and must show the positive or negative directions for a coordinate system common to both interferograms. The registration discussed in appendix D includes both these requirements. The magnitude of errors that would result from improper interferogram identification or improper scanning direction have not been determined. Their values would depend, to a large extent, on the differences in the two interferograms, i.e., whether the test lens has significant asymmetrical aberrations.

IX. AUTOMATIC SCANNER

IX.1 Description

high-speed digital microdensitometer (Photoscan P-1000; Optronics International Inc. [15]) was used for automatic scanning of the WSI interferograms. This scanner incorporates an electro-optical rotating drum which converts photometric data on film transparencies to digital form for computer processing. Figure 16 is a photograph of the scanner with a magnetic-tape transport unit. The sampling interval in both the x and y directions can be set at 12.5, 25, or 50 um. For a film optical-density ranging from 0 to 2 or 0 to 3, a total of 256 gray levels can be resolved. The following discussion of scanner calibration and data reduction is not restricted to this particular scan system; these procedures are generally applicable to any automatic microdensitometer that can be used to scan interferogram transparencies.

The interference patterns obtained from the WSI test set up were typically 1 to 2 cm in diameter on 35-mm film. In order to take advantage of the scanner resolution and to present the fringe pattern in a format suitable for scanning with the Photoscan System, it was necessary to make enlargements of the original interferograms. Thus, 12.7 cm x 12.7 cm (5 in. x 5 in.) transparencies with a nominal 9-cm-diameter fringe pattern were made for scanning. The requirements for high-quality film transparencies suitable for scanning have been discussed earlier in section VIII.3. It should be added that an effort was made to limit the optical density of the enlargements to a value of 3.0 (0.10 percent transmission) since this represents the upper detectable gray level for the scanner.

During automatic scanning, a transparency is digitized into density data over the entire selected scan window. For the typical enlargement with a 9-cm-diameter fringe pattern and a sampling interval of 50 µm along both the x and y axes, a total of about 4 million density data are generated, and the scanning time is about 30 minutes. From these data, it is necessary to extract the following (1) test-lens aperture boundary with the sense of two items: orientation preserved; and (2) fringe-peak locations. As discussed in the following subsections, the entire 4 million density values are not required to extract this information. However, the resolution required to determine the fringe-peak locations essentially demands the smallest available sampling interval across the fringe width. desirable to interface a computer to the scanner to permit automatic control of the sampling interval (both raster and aperture settings) over the entire film transparency. Ideally, the WSI interferograms would have to be scanned at only about 25 equally-spaced scans across The sponsor's Photoscan System is currently interfaced the fringes. to a mini-computer which permits the raster setting (along the



Figure 16.- Photograph of automatic-scanning microdensicometer with magnetic-tape transport unit.

rotating drum axis) to be under program control; in addition, the data from a single scan can be processed prior to the successive scan, thereby dramatically reducing the total density data accumulated or stored on magnetic tape.

IX.2. Calibration

Calibration tests to determine the resolution, density response, and dimensional fidelity of the scanner should be made prior to scanning interferograms. These tests were conducted on the Photoscan System as installed at the sprnsor's facilities. It is further suggested that these calibration tests be repeated during the future use of the scanner to maintain proper performance.

A positive transparency of a resolution test chart, such as the 1951 USAF tri-bar target [28] shown in figure 17, is recommended for checking the scanner resolution. For the 12.5-µm raster and aperture, the test chart should have patterns with spatial frequences higher than about 40 cycles/mm. The 1951 USAF target may include patterns up to about 230 cycles/mm as listed in table V. After scanning the resolution test target, the resultant density data are inspected to determine for which pattern groups the bars and spaces can be detected.

The density response of the scanner can be determined by scanning a calibrated photographic step tablet such as those offered by the National Bureau of Standards (NBS) [29]. These NBS tablets have about 20 density steps ranging from an optical density of 0.05 to 3.00 with an accuracy of the larger of 0.01 optical density or 1 percent. After scanning the step tablet, the resultant density data, or gray levels, are plotted against the calibrated density levels of the step tablet; this curve should be linear over the entire density range of the scanner. If the density response is not linear, the scanner should be adjusted.

The dimensional fidelity of the scanner may be determined by scanning a positive transparency of an orthogonal grid. The x and y coordinates of the intersections of the grid lines should be known by an independent approach, such as an optical comparator, to better than the expected position accuracy of the scanner. These known grid coordinates are compared to those obtained from the scanner. Usually the scanner data will have to be corrected for tilt since it is difficult to align the grid to better than the positional accuracy of the scanner.

Group No.	Element No.	y, lea/ma	Group No.	Fleamnt No.	rgrles/mm	Group No.	Element No.	ryclen/m
2	1	0.750	2	1	4.00	5	1	32,0
	2	. 280		2	4.49		2	38.0
	3	.315		3	5.04		3	40.3
	4	. 35 1		4	4.68		4	45.3
	5	. 197		5	6.35		5	50.8
	6	.445		6	7.13		6	57.0
-1	1	0.500	3	1	8.00	6	1	64.0
	2	.561	1	2	8.98		2	71.8
	3	. 630		3	10.1		3	80.6
	4	. 707		4	11.3		4	90.5
	5	.793		r _k	12.7		5	102.
	6	.891		0	14.3		6	114.
0	1	1.000	4	1	16.0	1	1	128.
	2	1.12		2	17.95		2	144.
	3	1.28		3	20.16		3	161.
	4	1.41	İ	4	22.63		4	101.
	5	1.59	1	5	25,39		5	102.
	6	1.78		6	28.51		6	114.
1	1	2.00		•			• • • • •	
	2	2.24						
	3	2.52						
	4	2.83						
	5	3.17						
	6	3.58						

Table 5.- Pattern spatial frequencies for 1951 USAF tri-bar target.

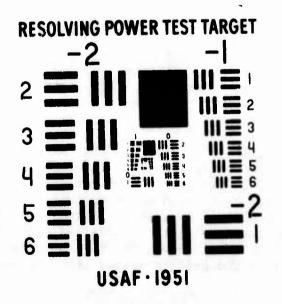


Figure 17. - Photograph of 1951 USAF tra-bar target.

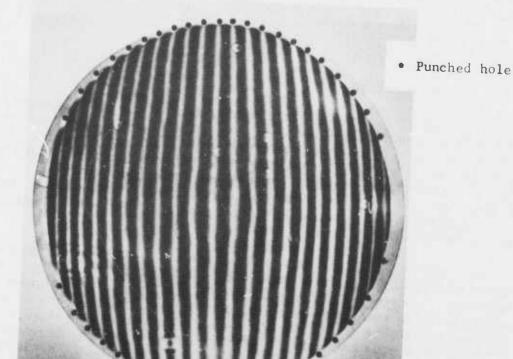
IX.3. Data Reduction

The computer program for reducing the density data obtained with the automatic scanner is outlined in appendix C. Two subroutines contained in this program locate both the test-lens aperture boundary and the fringe peaks. These two data-reduction steps produce the basic input data for the subsequent calculation of the test-lens properties, and they comprise the major portion of computer time in the reduction of automatic-scanner data; thus, both steps are discussed separately in this section.

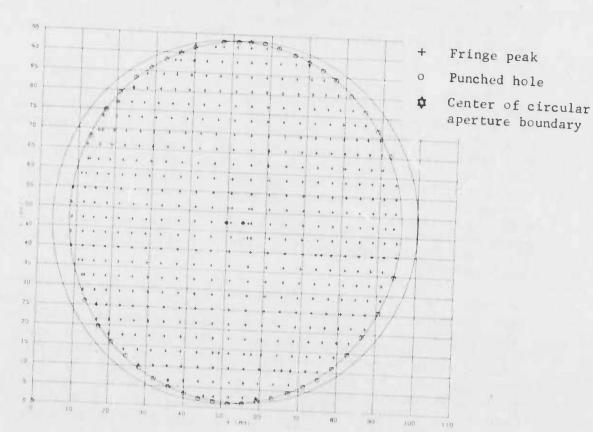
Of the 4 million data samples recorded with the 50-µm-sampling intervals, one quarter are used to locate the test-lens aperture boundary. Searching for specific information in a million samples is time consuming even for a high-speed computer. Methods of using the density variations in the photograph to identify the aperture boundary are even more time consuming. Most of these techniques depend on differentiation, autocorrelation, or other similar techniques. To reduce the number of required operations in the search and to reduce the possibility of errors, a method of punching small holes (about 1 mm in diameter) in the transparency at the beginning and end of every fringe was adopted. These holes not only clearly define the boundary, but also help to locate the fringe peaks and to assign fringe-order numbers. A typical interferogram with these punched holes is shown in figure 18(a).

The computer program searches for the holes by testing for density levels less than a given threshold value. If such a value is found, the scan is restricted to adjacent points, and all values below the threshold are counted. Since noise or pinholes in the transparency will sometimes result in values below the threshold, less than a given number in such a count is considered to be noise and ignored; whereas a sufficiently high count indicates that a hole has been located. The average location of the values below the threshold is noted, and the scan is continued over the entire transparency. The locations of the holes are then sorted and paired as the beginning and end of a fringe. After sorting the hole locations, they are curve-fitted to a circular lens aperture.

From the 2,000 or more recorded scans obtained with the 50-µm-raster setting, those scans within the aperture, spaced at intervals corresponding to multiples of the shear distance, are chosen for locating the fringe peaks. Since only 20 to 30 scans are used, the computer time required to perform this search is relatively short. The fringe peaks are located in the following manner. By a process which most nearly corresponds to differentiation, the approximate location of a fringe peak is noted. Because of the noise in the photograph and lack of finesse in the fringes, this operation is not



(a) WSI interferogram.



(b) Plot of fringe-peak locations.

Figure 18. - Comparison of WSI interferogram with fringe-peak locations obtained from automatic scanning.

sufficiently accurate. Therefore, in the region of the peak, an interval of the scan corresponding to one cycle of the cosine is used to perform an autoconvolution. The location of the peak of the autoconvolution function corresponds to the fringe peak. The effects of photographic noise are minimized by this technique which approximates the operation performed by the operator using the Grant comparator. This procedure is performed over all cycles of the scans used.

The resulting locations of fringe peaks are then assigned order numbers in the following manner. Since the holes corresponding to the beginning and ends of fringes have already been sorted and the fringes assigned order numbers in increasing values of x, the fringe locations in the first scan are assigned the same order number as the hole to which they are closest. Subsequent scans are compared with the locations of peaks in the previous scan and assigned order values similarly. If more than on a peak location appears at the same order number because of noise or other anomalies in the photograph, the one which is closest to the previous x value is assigned that fringe number and the other discarded. This technique works extremely well for current interferograms. There is minimal noise in the interferograms and seldom any real problem with incorrect choices of fringeorder numbers. The only major problem in using this program has occurred because holes were punched in the wrong place on the interferogram. If the holes do not touch the fringe terminals, or are displaced horizontally, the proper assignment of order number may not be made.

Figure 18(b) is a computer-generated plot of the fringe-peak locations from the automatic data reduction for the WSI interferogram in figure 18(a). The location of the punched holes is also shown; one of these holes is incorrectly plotted at the origin of the coordinate axes. The two circles shown correspond to the sheared and unsheared aperture boundaries of the test lens. In some areas, there are two closely spaced values for a fringe-peak location. The additional values usually result from noise in the interferogram, such as diffraction patterns from the aperture boundary or dust on the test lens. An apparent fringe for which holes are not punched is also shown; this fringe is only partially visible in figure 18(a) and was not treated as useable data.

X. WSI FRINGE PATTERNS

X.1. Analytic Form

Discussions of shearing interferograms resulting from various types of lens aberrations may be found throughout the literature [30, 31]. For the present cube interferometer, the general form of the interferograms for shear in the x direction may be found by setting the cosine argument of equation (3) equal to $2\pi p$, viz,

$$\frac{x\ell\phi}{\lambda x_2} + \frac{\varphi(x,y)}{\lambda} - \frac{\varphi(x-\ell\phi-z_2, y)}{\lambda} = p$$
 (46)

where p is an integer corresponding to fringe peaks, x is the fringe location measured from the center of the lens aperture, and the term $k(\ell\Phi)^2/2z_2$ corresponding to a small constant displacement of the fringe pattern has been omitted. In order to simplify the solution of equation (46) for fringe locations, we may rewrite it in a normalized form, viz,

$$x + c \left[\varphi(x,y) - \varphi(x-1, y) \right] = p$$
 (47)

where the ideal fringes are assumed to be at unit spacing $(\ell \Phi / \lambda z_2 = 1)$, the shear distance is assumed unity $(\ell \Phi + z_2 \Phi = 1)$, and c is a constant $(c = \frac{C_1}{\lambda}; C_1 = constant)$. A similar equation results for the y-sheared interferogram.

From table 1(a), we can write an analytical form of $\varphi(x,y)$ for specific aberrations. Substituting this form of $\varphi(x,y)$ into equation (47) and solving for x will give the fringe pattern for the x-sheared interferogram. For example, with third-order x coma, equation (47) becomes

$$x + cx (x^2 + y^2) - c_1 (x-1) \left[(x-1)^2 + y^2 \right] = p$$
 (48)

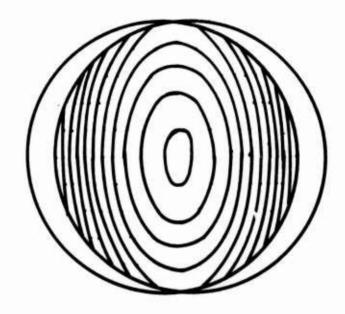
The y-sheared interferogram for this aberration is given by

$$y + cx (x^2 + y^2) - cx \left[x^2 + (y-1)^2\right] = p$$
 (49)

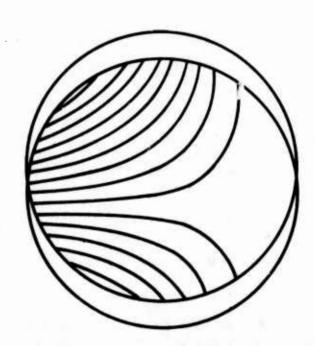
Solving equation (48) and (49) for 2 λ of third-order x coma gives the fringe patterns shown in figures 19(a) and 19(b).

As another example, consider third-order 0° astigmatism; for this aberration, we can write

$$x + c(x^2 - y^2) - c \left[(x - 1)^2 - y^2 \right] = p$$
 (50)



(a) x-sheared interferogram.



(b) y-sheared interferogram.

Figure 19.- Schematic of WSI interferograms for 2λ of third-order x coma.

for the x-sheared interferogram; and

$$y + c (x^2 - y^2) - c \left[x^2 - (y - 1)^2\right] = p$$

for the y-sheared interferogram. Solving these equations for 2 λ of third-order 0° astigmatism gives the fringe patterns shown in figures 20(a) and 20(b). The resulting fringe are straight in both interferograms, but the fringe spacing is different. The other component of astigmatism given in table 1(a), viz, third-order 45° astigmatism, also produces straight-line fringes, but with different slopes or orientations in the x and y-sheared interferograms. The fringe patterns for 2 λ of third-order 45° astigmatism are shown in figures 21(a) and 21(b).

X.2. Test Cases

One approach to check the logic and accuracy of the computer datareduction program outlined in appendix A is to input data representing a lens with a known aberration and compare the resulting pupil function and aberrations with the input value. Consider a lens with third-order spherical aberration; for this aberration, equation (47) becomes

$$x + c (x^2 + y^2)^2 - c [(x - 1)^2 + y^2]^2 = p.$$
 (52)

Since spherical aberration is rotationally symmetric, both the x and y-sheared interferograms will be identical. Solving equation (52) for x yields a cubic equation with real solutions at x = A + B where

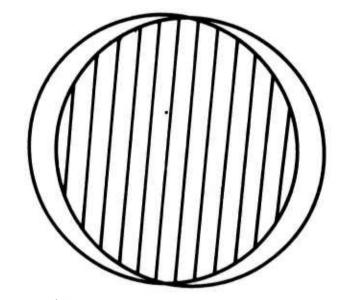
$$A = \sqrt[3]{\frac{b}{2} + \sqrt{\frac{b^2}{4} + \frac{a^3}{27}}}$$

$$B = \sqrt[3]{\frac{b}{2} - \sqrt{\frac{b^2}{4} + \frac{a^2}{27}}}$$

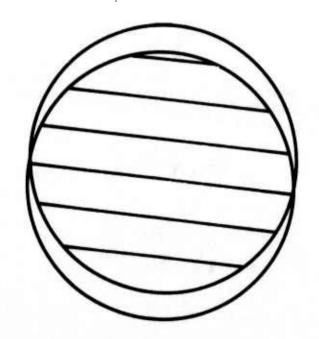
$$a = y^2 + \frac{1}{2}$$

$$b = \frac{3}{8} - \frac{m}{4}$$
(53)

and

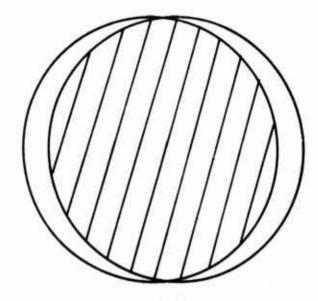


(a) x-sheared interferogram.

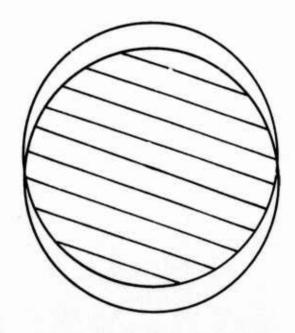


(b) y-sheared interferogram.

Figure 20. - Schematic of WSI interferograms for 2λ of third-order 0° astigmatism.



(a) x-sheared interferogram.



(b) y-sheared interferogram.

Figure 21.- Schematic of WSI interferograms for 2 λ of third-order 45° astigmatism.

Solving equations (52) and (53) for 2 λ of third-order spherical aberration gives the fringe pattern shown in figure 22. These fringe locations were used as input to the computer data-reduction program. The resulting maximum aberrations are given in table 6; also given in this table are the maximum aberrations for the case of 1 λ of thirdorder spherical aberration. The pupil-function phases for these two cases are shown in figures 23(a) and 23(b). The isocontours of the MTF's are shown in figures 24(a) and 24(b); the two-dimensional MTF's are shown in figure 25(a) and 25(b). The isocontours of the PTF's are shown in figures 26(a) and 26(b); the two-dimensional PTF's are shown in figures 27(a) and 27(b). For these plots, wavelength is unity and the radius of the lens aperture is 12 units; the spatial frequency is normalized. For both cases, the computed pupil functions are accurate to $\lambda/10^4$. The computed MTF's and PTF's agree with the calculations reference 32 to within plotting accuracy. Since spherical aberration is symmetrical, as readily apparent from figure 23, there should be no differences between the sagittal and tangential MTF's. For the PTF's, there are large differences between the sagittal and tangential values above 0.6 cycles/mm. These differences are due primarily to computational inaccuracies as discussed in section 8.2 and do not signify a real difference in the sagittal and tangential PTF's.

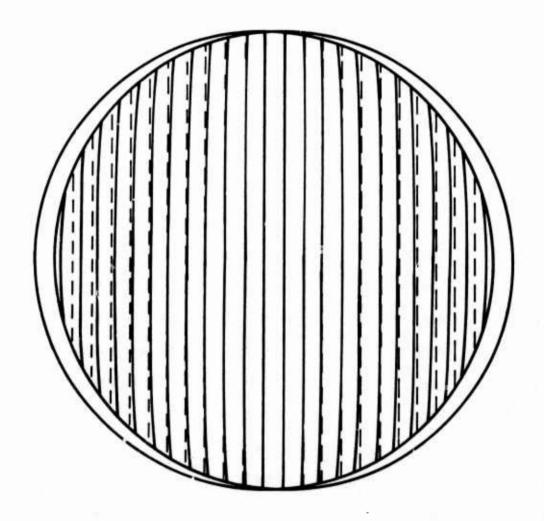
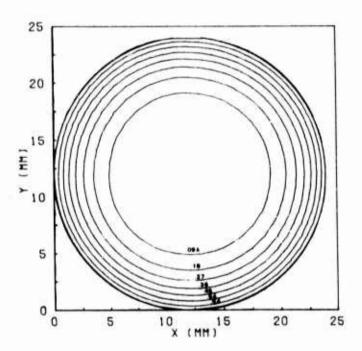


Figure 22. - Schematic of WSI interferogram for 2 \(\) of third-order spherical aberration. (Dashed lines represent equally spaced, straight-line reference fringes for aberration-free lens.)

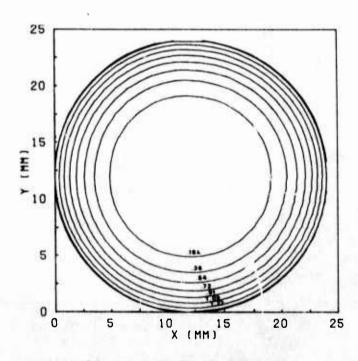
TABLE 6.- MAXIMUM ABERRATIONS FOR TEST CASES OF 1λ and 2λ OF THIRD-ORDER SPHERICAL ABERRATIONS $^{\bf a}$

n	$oldsymbol{1}\lambda$ spherical	2λ spherical	type
4	0010	.0014	focus
5	0000	.0002	0° astigmatism
6	.0000	0000	45° astigmatism
7	0017	0011	x coma (3rd)
8	0009	0010	y coma (3rd)
9	.0002	.0021	x clover (3rd)
10	.0043	.0013	y clover (3rd)
11	1.0065	1.9955	3rd spherical
12	.0000	0002	0° astigmatism (5th)
13	0000	.0000	45° astigmatism (5th)
14	.0000	.0001	4
15	.0000	.0000	
16	.0016	.0009	x coma (5th)
17	.0008	.0011	y coma (5th)
18	0003	0026	x clover (5th)
19	0054	0012	y clover (5th)
20	0002	0001	
21	.0000	0015	
22	0106	. 0038	5th spherical
23	.0063	0016	7th spherical

 $a_{\lambda} = 1.0$

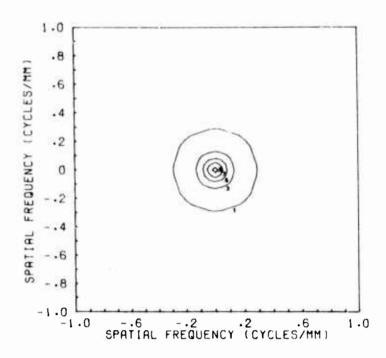


(a) 1λ spherical aberration.

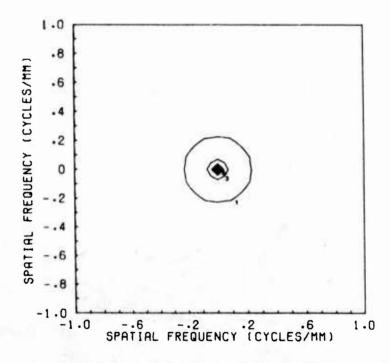


(b) 2λ spherical aberration.

Figure 23.- Isocontours of pupil-function phase for test cases of WSI fringe patterns with 1λ and 2λ of third-order spherical aberration.

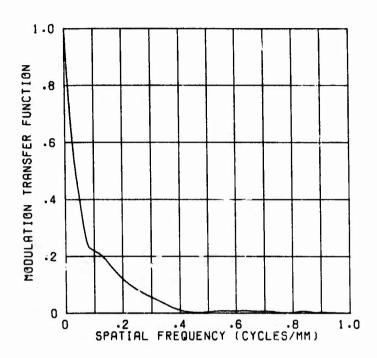


(a) 1λ spherical aberration.

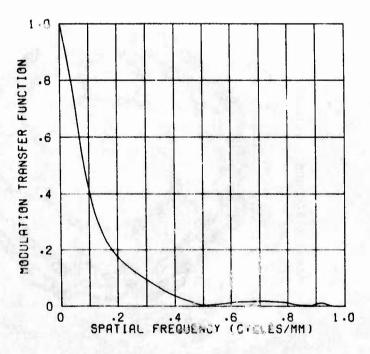


(b) 2λ spherical aberration.

Figure 24. - Isocontours of MTF for test cases of WSI fringe patterns with 1λ and 2λ of third-order spherical aberration.

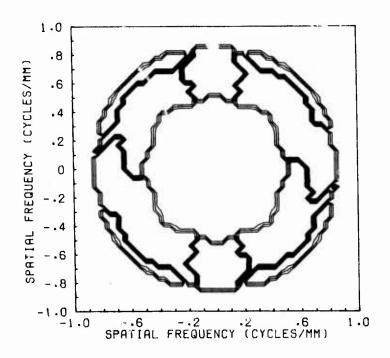


(a) 1λ spherical aberration.

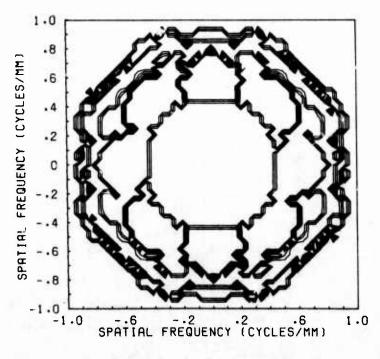


(b) 2λ spherical aberration.

Figure 25.- MTF for test cases of WSI fringe patterns with 1λ and 2λ of third-order spherical aberration.

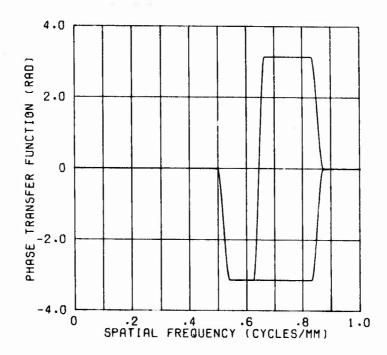


(a) 1λ spherical aberration.

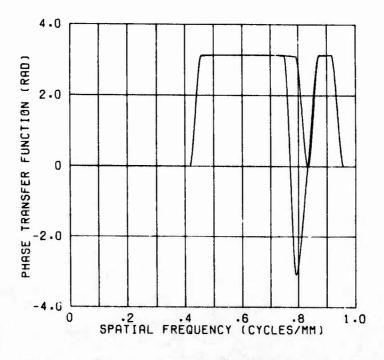


(b) 2λ spherical aberration.

Figure 26.- Isocontours of PTF for test cases of WSI fringe patterns with 1λ and 2λ of third-order spherical aberration.



(a) 1λ spherical aberration.



(b) 2λ spherical aberration.

Figure 27.- PTF for test cases of WSI fringe patterns with 1λ and 2λ of third-order spherical aberration.

XI. TEST SYSTEM AND PROCEDURES

The test system and experimental procedures used for testing lenses in the WSI system have, to a great extent, been discussed throughout previous sections. These items are collected in this section to serve as a guideline in the set up and use of a WSI test system.

XI.1. Testing Mode

As shown previously in figures 2 and 3, the WSI system can be arranged for testing lenses at either finite or infinite conjugates. Although the double-pass mode is the usual arrangement for infinite-conjugate testing, this approach is not satisfactory for testing relatively short focal-length lenses. For such lenses in a double-pass mode, the available working distance is not long enough to allow a pellicle or beam splitter to be positioned between the pellicle and cube. An alternative for testing most lenses at infinite conjugates is to use a diffraction-limited or high quality collimator in a single-pass mode as shown in figure 28. If a aberration-free collimator is unavailable, a third approach, which is also a single-pass system, is to place the test lens at a distance from the light source beyond the hyperfocal distance.

It should be noted that in testing in the double-pass mode the test-lens wavefront aberrations are doubled. Therefore, the fringe displacements are automatically halved during computer data reduction for this case.

XI.2. Components

The basic components required for lens testing with the WSI are a set of cube interferometers, optical bench, light source and pinhole, auxiliary lens, and nodal slide or fixture for rotating cube, film plane, and auxiliary lens. For infinite-conjugate testing, a flat mirror and pellicle or collimator may also be required.

The choice of a WSI cube with a fixed shear angle depends primarily on the f-number of the test lens. (See table 2(a).) A set of eight or nine cubes with shear angles ranging from about 2 to 40 mrad should be sufficient for testing lenses with f-numbers from f/15 to f/1. However, it should be noted that testing lenses below about f/2 should generally not be undertaken since the aberrations introduced by the cube are very large. (See section VI.2.)

The optical bench should dampen external vibrations, remain straight over the span of the test system, and exhibit high dimensional stability. For the present tests, an optical bench which remained level to within 0.1 mm over 1 m was used. Vibrations of the fringe patterns were detected occasionally even though the bench was relatively heavy steel. The test-system components were mounted at

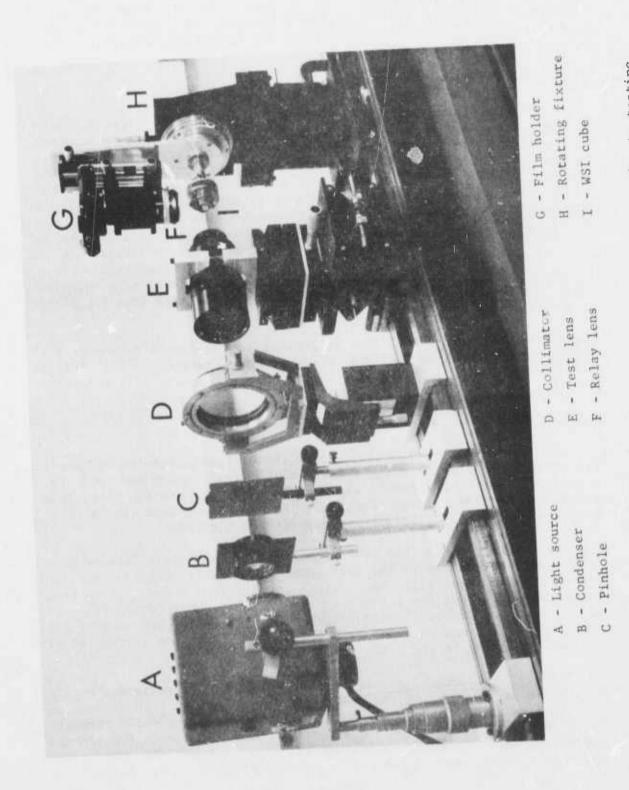


Figure 28.- Photograph of single-pass WSI test system for infinite-conjugate testing.

about 30 cm above the top surface of the bench, and, therefore, introduced a mass at the end of a relatively long lever arm; this design probably led to the observed vibrations.

The light source can be filtered polychromatic light or a laser. A 100-watt mercury-arc lamp with a monochromatic filter and a 15-mW He-Ne laser were both used in the present tests. A pinhole is used for a point source, and the size of the pinhole is determined by the degree of coherence required to produce fringes of good contrast. For the present tests, a $100-\mu\text{m}$ -diameter pinhole was used to test a 1-m focal-length lens, and a $10-\mu\text{m}$ -diameter pinhole was used to test a 50-mm focal length lens. In addition, condenser optics are generally necessary to produce a high-energy, focused image of the light source at the pinhole. These condenser optics should be selected and adjusted so that the cone of light diverging from the pinhole fills the test lens completely and uniformly.

The choice of an auxiliary lens to image the interference pattern on the film plane is related to both the f-number of the test system and the desired image size of the interferogram. Since the auxiliary lens should be placed a distance equal to its focal length away from the test-lens focal plane, the diameter of the resulting interferogram D will be given by D = $f_c/f^{\#}$ where f_c is the focal length of the auxiliary lens and $f^{\#}$ is the f-number of test lens. For the f/8 and f/8.7 lenses in the present tests, an auxiliary lens with f_c = 105 mm at f/2.5 was used to give an interferogram with D ~ 12 mm.

Ideally, a nodal slide that maintains test-lens alignment during rotation to the 90° or y-sheared setting should be used. If such a lens mount is not available, two alternatives are to (1) rotate the auxiliary lens, film plane, and cube as a fixed unit about the test-system axis; or (2) realign the test lens after the 90° rotation. The latter approach was used in the present tests. However, since completion of these tests, a fixture for rotating the auxiliary lens, film plane, and cube was built and is currently used for lens testing with the WSI; it is generally recommended that such a fixture be used rather than realigning the lens after rotation. (See figure 12.)

The flat mirror that may be required for infinite-conjugate testing should ideally not introduce any wavefront deviations greater than the smallest repeatable deviations detected with the WSI test system. Present testing techniques with the WSI have shown that wavefront deviations down to about 0.04 λ can be repeated. The 14-cm-diameter mirror used as a retro-reflector in the present tests was inspected with a Twyman-Green interferometer and found to give wavefront deviations (peak to valley) no greater than about 0.10 λ . The largest surface deviations, as with most flat mirrors, occurred near the mirror edge. For the present tests, only the central mirror area with a diameter of about 11 cm was used; thus, the wavefront deviations introduced by the mirror were probably far less than 0.10 λ . For current testing, a 20-cm-diameter mirror with a maximum peak-to-valley deviation of only 0.03 λ is used.

If a beam splitter is required to fold optically the WSI test system, a pellicle rather than a glass-plate should be used. A glass plate, like the cube interferometer, will introduce aberrations. Since a glass-plate beamsplitter is commonly used with light incident at 45° to the glass surface, significant asymmetrical aberrations would be added to the wavefront. A nominally 5-µm-thick, 8-cm-diameter pellicle with an optical flatness of a few wavelengths over the diameter was used in the present tests. A pellicle area measuring from only 0.5 to 1 cm in diameter was actually used to transmit and reflect the wavefront.

If a collimator is used to provide a plane wavefront for infinite-conjugate testing, the collimator should be tested first to determine its performance. One of the f/8.7 collimators tested in the present study and discussed in the following section was found to be nearly diffraction limited; thus, this collimator is currently used to test lenses at infinite conjugates on the WSI. If should be noted that special care must be taken to align a collimator in the WSI test system since many collimators are designed with a very narrow angular field of view of 1 or 2 degrees; otherwise, off-axis aberration will be introduced even for a collimator that is diffraction-limited on axis.

XI.3. Alignment

After mounting the test-system components on the optical bench, it is necessary to establish an optical axis and to align the components along this axis. As noted earlier, an optical axis, which did not vary in height more than 0.1 mm over a 1-m length, was defined at about 30 cm above the top surface of the bench. To establish this axis, the centers of a cross hair and an alignment target were fixed at the same height and transverse position by visual sighting through an alignment telescope (theodilite). Thus, the optical axis could be "reconstructed" at any time by simply reinstalling the cross hair and alignment target on the optical bench.

The system components, excluding the WSI cube, test lens, and auxiliary lens, were centered to within 0.5 mm of the test-system optical axis by means of the alignment telescope. For a test system using a pellicle to fold optically the light source, the pellicle must be angularly adjusted in order to center the image of the point source.

The cube interferometer is roughly centered on the optical axis by visual sighting. Other than avoiding any non-homogeneities in the cube, the cube must be located so that no vignetting of the interference pattern occurs. For systems that rotate the cube 90° to obtain the y-sheared interferogram, these requirements, of course, apply to both angular settings. A 1-mW He-Ne laser was used to align the front face of the cube normal to the optical axis. After aligning the laser beam along the optical axis, the cube was adjusted angularly until the beam reflected from the front face returned through the laser aperture. With this approach, the cube face was aligned to within 15 arc minutes, thereby eliminating asymmetric aberrations which arise from a tilted cube. The cube should be aligned to well within 15 arc minutes when testing lenses below f/4; otherwise, significant coma may be introduced. This angular alignment must also be maintained if the cube is rotated for the y-sheared interferogram.

The rotational position of the cube about the optical axis is related to interferogram registration and, therefore, is discussed in appendix D. The cube position or & setting along the optical axis is discussed following the test-lens alignment since this cube setting is dependent on test-lens location and alignment.

The test lenses were aligned by the Boys-point method [33] which uses subsidiary images of the light source formed by reflections from the front and back surfaces of the test-lens. A schematic of this technique is shown in figure 29. In this technique the test lens is alternately translated and tilted until a subsidiary image formed behind the lens and one formed in front of the lens are both centered on the optical axis. During alignment the subsidiary images can be seen on the cross hairs and alignment target; the centers of the cross hairs and alignment target define the optical axis as noted earlier. In the present tests, the test lenses were aligned to within two arc minutes. For infinite-conjugate testing, with a collimator, the position of the test lens along the optical axis is not important; however, for infinite-conjugate testing without a collimator, the test lens must be placed at a distance from the light source beyond the hyperfocal distance. For finite-conjugate testing, it is important to position the test lens at the required distance from the light source.

After positioning and aligning the test lens, the cube interferometer is moved along the optical axis until the null-fringe position is located. This is the cube position in which the fringe field is either all dark or all light, i.e., a dark or light fringe of infinite extent denotes the null-fringe position. At this position, the backface of the cube is located in the plane of the test-lens

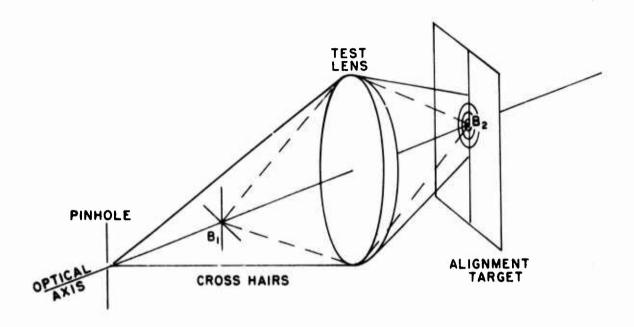


Figure 29.- Schematic of Boys-point method to align test lens in WSI system.
(B₁ and B₂ are subsidiary images formed by test lens.)

focus and, therefore, there is no lateral shear or $l\phi = 0$. figure 4.) Since the depth of focus for a lens increases with increasing f-number [24], the null-fringe position is less repeatable for lenses with higher f-numbers. For example, the null-fringe position in the present tests with the f/8.7 lens could be repeated to within 0.1 mm. This is consistent with the focal properties of the test lens since the depth of focus for an f/8.7 lens at λ = 0.50 μ m is about 0.1 mm. Thus, the error in locating and repeating the null fringe position may be no larger than the depth of focus for the test lens. The cube interferometer is then moved along the optical axis a predetermined distance & away from the null-fringe position. Although the same fringe pattern can be obtained for the same & setting on either side of focus, it is recommended that the cube be moved outside of the test-lens focus. This setting is consistent with the present data-reduction technique which requires & + z2 as an input parameter where & > 0. The & distance is determined by first choosing the total number of fringes M to appear in the interferogram. From equation (44), the fringe spacing ΔF is given by D/M and from equation (7), the reference fringe spacing for a given ℓ is $\lambda z_2/\ell \Phi$. Equating these two expressions for fringe spacing gives

$$\frac{D}{M} = \frac{\lambda z_2}{\ell \Phi} . \tag{54}$$

Solving equation (54) for & yields

$$\ell = \frac{M\lambda z_2}{D\Phi} \tag{55}$$

which is used to determine the axial position of the cube as measured from the null-fringe position.

The auxiliary lens must be positioned so that the interference pattern incident on the film plane is collimated, unobstructed, and relatively free of distortion. After fixing the axial, angular, and rotational settings of the cube interferometer, the auxiliary lens should be centered with respect to the beam exiting from the cube and opened to the lowest f-stop. Furthermore, the auxiliary lens should be roughly aligned along the exit-beam axis so that lens distortion is kept to a minimum. This alignment can be done visually by inspecting the image geometry on the film plane. Assuming that the film is normal to the exit-beam axis, the image should be round for a test lens with a circular aperture. The auxiliary lens must also be located axially so that the fringe pattern is collimated. This can be checked by comparing the image diameter at the film plane with the image diameter at some distance relatively far behind the film plane; the image diameter is constant for collimated light.

XI.4. Interferogram Photography

The choice of film for recording fringe patterns in the test system and making enlargements suitable for scanning depend upon many variables such as film speed, resolution, and range of contrast obtainable under various processing conditions. As discussed in section VIII.3, the requirements for a high-quality interferogram ideally include a density variation that approaches a cosine distribution across the fringe pattern and a transparency which is free of pinholes, scratches, and other similar defects. Any film and subsequent processing which can produce an interferogram that approaches these conditions will be suitable.

For the majority of the present tests, 35-mm AHU microfilm (ASA 64) at exposure times of 1/4 to 1 second was found to give satisfactory interferograms. In a few instances, 35-mm TRI-X pan film (ASA 400) at exposure times of 1/30 to 1/8 second was used and also gave satisfactory interferograms. Ortho sheet film - Type 3 (ASA 10) and Ortho Super Speed Portrait sheet film (ASA 125) were used to make enlargements for scanning. Depending on the quality of the original 35-mm interferogram, the exposure and processing for the enlargements were often varied to produce acceptable interferograms.

As discussed in appendix D, roll film is recommended over sheet film for original interferograms. With roll film, the proper orientation between x and y-sheared interferograms can be preserved more easily.

XII. TEST RESULTS

In the present study, three lenses were tested on axis with the WSI. These lenses were: (1) f/8.7 collimating doublet (collimator A); (2) f/8.7 collimating doublet (collimator B); and (3) f/8 OTF Standard Test Lens. Although test procedures, test-system components, and data-reduction procedures were improved throughout the testing of these three lenses, the data presented are representative of WSI test data and accurately reflect the test-lens performance.

XII.1. Collimator A

The f/8.7 collimating doublet has a clear aperture of 11.5 cm and a nominal effective focal length of 1 m. This collimator was reported by the supplier to be diffraction limited over a 1.9-cm field of view (1.1°) from 510 nm to 610 nm.

The collimator was tested at infinite conjugates since it is designed to be used under these conditions. The test system was arranged in a double-pass mode using a 14-cm-diameter plane mirror as shown in figure 3. A 100-W high-pressure mercury-arc lamp with a monochromatic interference filter (λ = 546.1 nm), condensing optics, and a nominally 100- μ m-diameter pinhole were used for the light source. A cube interferometer with Φ = 4.55 mrad was used.

The initial fringe pattern observed for the collimator was highly curved, thereby indicating that this lens was not diffraction limited or large errors were being introduced by the test system. Possible sources of errors in the test system were, therefore, investigated. The retro-reflecting plane mirror was tested on a Twyman-Green interferometer and found to give wavefront deviations (peak to valley) no greater than about 0.10 λ over the entire 14-cm diameter; deviations were much smaller over the 11.5-cm-diameter portion used to reflect the test wavefront. The pellicle, which was used to fold optically the light source, was repositioned several times, but no fringe pattern was observed; furthermore, the the substitution of two other rellicles did not change the fringe pattern. The cube interferometer was also replaced by several other cubes with different shear angles, and after adjustments to obtain the same number of fringes in all cases, the resulting fringe pattern was the same. The collimator was also reversed front to back in the nodal slide since many achromats, like the collimator, are designed to be used only with the point source on the back side of the lens; however, no change in fringe pattern was observed. Finally, the collimator was very carefully realigned to well within the 1.1° angular field of The resulting fringe pattern was essentially identical to the

initial pattern, thereby demonstrating that the fringes accurately reflected the lens performance. Thus, interferomgrams were scanned, and the resulting pupil function, if TF, and PTF for the plane or best focus are shown in figures 30(a), 30(b), 30(c), 30(d), and 30(e). The resulting maximum aberrations are given in table 7.

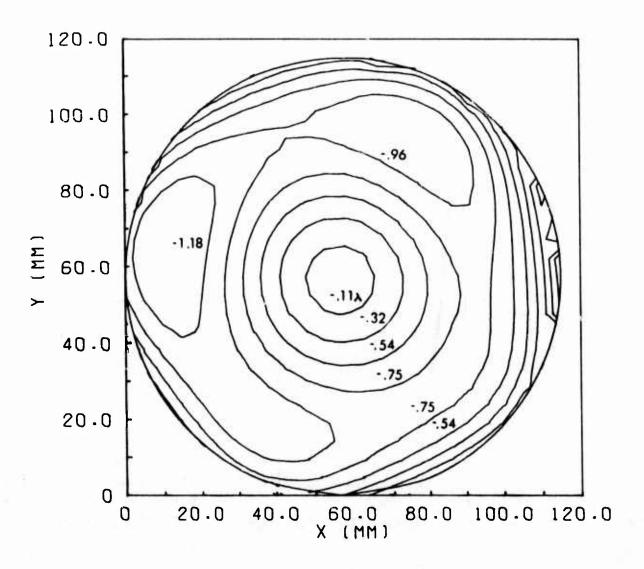
The pupil-function plot in figure 30(a) shows that there are both symmetrical and asymmetrical aberrations in the collimator. The maximum deviation of the wavefront is about 2.1 λ , and the RMS of the wavefront is about $\lambda/3$. Inspection of table 7 shows that the net symmetrical aberration, which results from combining defect of focus and spherical aberration, is about -.1 λ . The significant asymmetrical aberrations are third-order x coma (-0.6 λ), third-order y coma (-0.4 λ), and fifth-order y coma (0.3 λ). The coma may arise from a decentration error [34] since the collimator was tested on axis, or at the center of the field, and coma arising from improper shape of the lens surface does not occur on axis. On the other hand, the astigmatism at the center of field does not result from decentration of the lens elements; this error results from imperfect lens surfaces.

The MTF for the diffraction-limited lens ($\lambda = 546.1$ nm) with the same f-number as the collimator is also shown in figure 30(b). The large differences between the collimator and a diffraction-limited lens are readily apparent.

Isocontours of the MTF for the collimator are shown in figure 30(c). The zero value of spatial frequency occurs at the center of the lens aperture; the spatial-frequency values given along the coordinate axes apply to values along lens diameters drawn parallel to these axes.

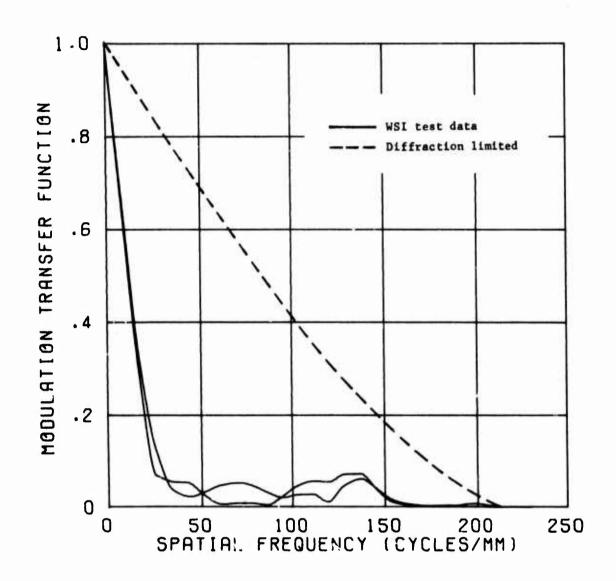
The PTF for the collimator is given in figure 30(d). However, as noted earlier in section VIII.3, the accuracy of these phase values is probably not very high since their calculation involved very small and rapidly changing values of the OTF. The isocontours of the PTF are shown in figure 30(e). The intricate pattern of this plot results, to some degree, from the same computational inaccuracies indicated above. However, this plot does illustrate the ability of the test system and data-reduction program to handle a lens with a rapidly varying OTF.

Since the collimator performance was found to be considerably less than diffraction limited, it was returned to the supplier. Follow-up testing by the supplier confirmed the test results obtained with the WSI test system.



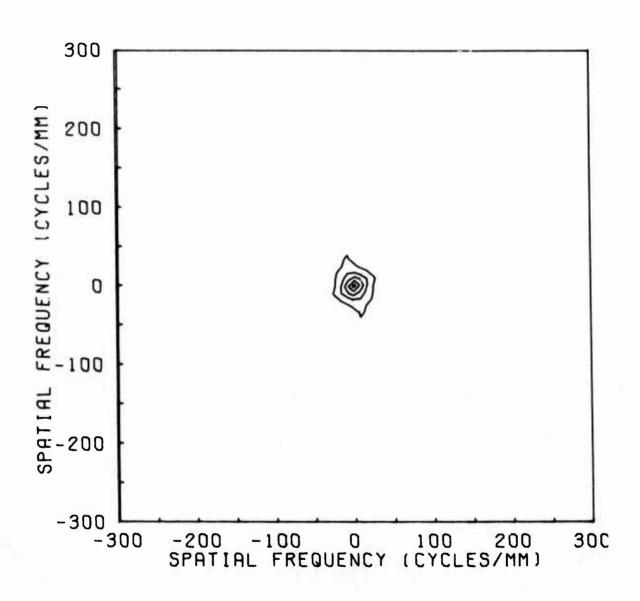
(a) Isocontours of pupil-function phase.

Figure 30. - On-axis WSI test results in plane of best focus for f/8.7 collimating doublet (collimator A); $\lambda = 546.1$ nm.



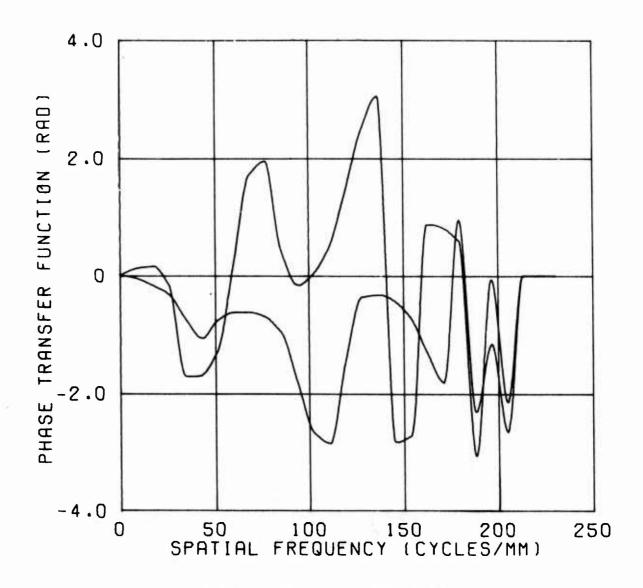
(b) Tangential and sagittal MTF.

Figure 30. - Continued.



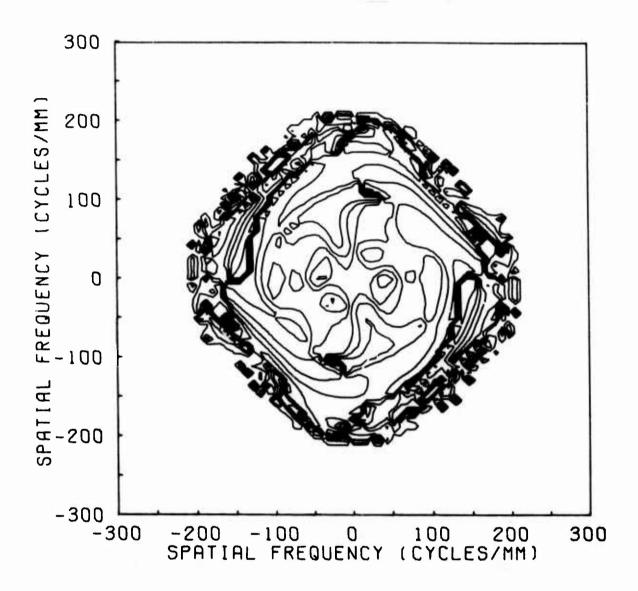
(c) Isocontours of MTF.

Figure 30. - Continued.



(d) Tangential and sagittal PTF.

Figure 30. - Continued.



(e) Isocontours of PTF.

Figure 30. - Concluded.

TABLE 7. - MAXIMUM ABERRATIONS FOR f/8.7 COLLIMATING DOUBLET (COLLIMATOR A) a

n	Maximum aberrations, units of λ	Туре
4	-4.821	focus
5	1062	0° astigmatism 45° astigmatism x coma (3rd) y coma (3rd) x clover (3rd) y clover (3rd) 3rd spherical 0° astigmatism (5th) 45° astigmatism (5th)
6	- 2080	
7	.6441	
8 9 10 11 12 13	3685	
	.2209	
	1603	
	7.1699	
	.1365	
14	.0336	
15	.2568	
16	1200	40.00
17	.3120	x coma (5th) y coma (5th) x clover (5th) y clover (5th)
18	0188	
19	1405	
20	.1164	
21	.0155	
22	-3.8634	5th spherical
23	1.4013	7th spherical

^aIn plane of best focus; $\lambda = 546.1$ nm.

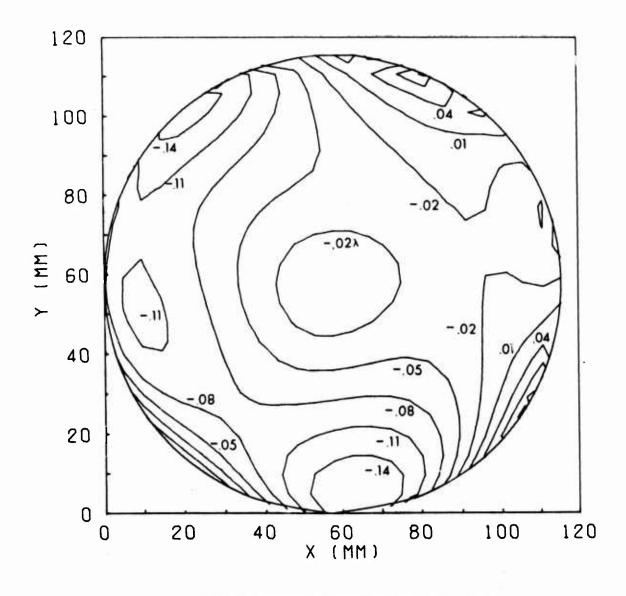
XII.2. Collimator B

This collimator has the same nominal f-number of f/8.7 and effective focal length of 1 m as the previous collimator. The supplier of collimator B also reported this collimator to be diffraction limited over a 1.9-cm (0.75 in.) field of view (1.1°) from 510 nm to 610 nm.

Collimator B was also tested at infinite conjugates as shown in figure 3. However, for this collimator, a 15-mW He-Ne laser (λ = 632.8 nm) with a beam expander and 16-µm-diameter pinhole was used. An initial attempt to use the filtered mercury-arc lamp with a 10-µmdiameter pinhole, rather than the 100-um-diameter pinhole used earlier, was made. The diameter of the Airy disc [35] for a diffraction-limited f/8.7 lens is about 12 µm; therefore, a 100-µmdiameter pinhole may lead to off-axis illumination. In any case, sufficient energy for reasonably short photographic exposures was not available with the mercury-arc lamp and the 10-µm-diameter pinhole. A special effort was made to keep the collimator and test-system components free of dust which might cause spurious fringe patterns in laser illumination. An improved nodal slide, which offered finer controls for lens alignment, was used. The same cube interferometer with $\Phi = 4.55$ mrad was used. The resulting pupil function, MTF's, and PTF's for the plane of best focus are shown in figure 31. Table VIII lists the resulting maximum aberrations.

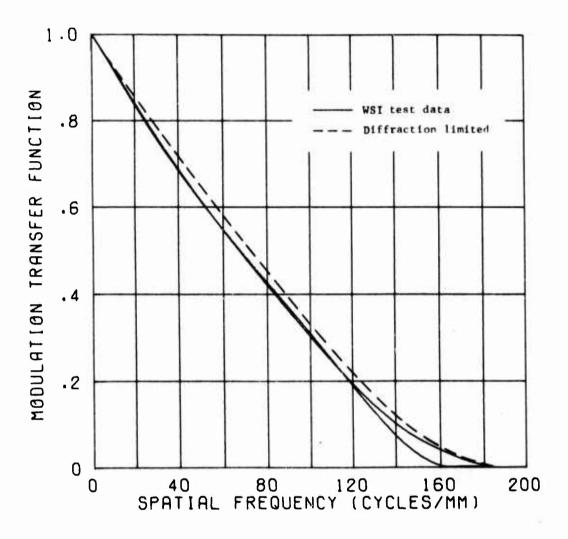
Figure 31(a) shows that the pupil function exhibits primarily asymmetrical aberrations. The net result of the symmetrical aberrations listed in table 8 is about $-0.01\,\lambda$. The primary asymmetrical aberrations appear to be x and y coma (third and fifthorder). The maximum value for each of these aberrations is about \pm 0.2 λ ; this value is also the maximum deviation of the wavefront which has an RMS of $\lambda/21$. As noted in the previous section, this coma, which occurs on axis, may be due to a decentration error, i.e., one or both lens elements in the collimator doublet may not be centered exactly. The effective focal length for the plane of best focus was determined to be 999.566 mm.

The MTF for diffraction-limited performance of an f/8.7 lens is shown in figure 31(b) along with the test results for collimator B. A comparison shows that the collimator is slightly below diffraction-limited performance. However, it should be remembered that the collimator was tested at $\lambda = 632.8$ nm which is outside of the wavelength range (510 nm to 610 nm) in which the supplier reported the collimator to be diffraction limited. The tangential and sagittal MTF's are nearly identical up to a spatial frequency of about 120 cycles/mm. Thus, even though the pupil function is primarily asymmetric, the magnitude of these asymmetrical aberrations is sufficiently small such that the MTF appears to be somewhat



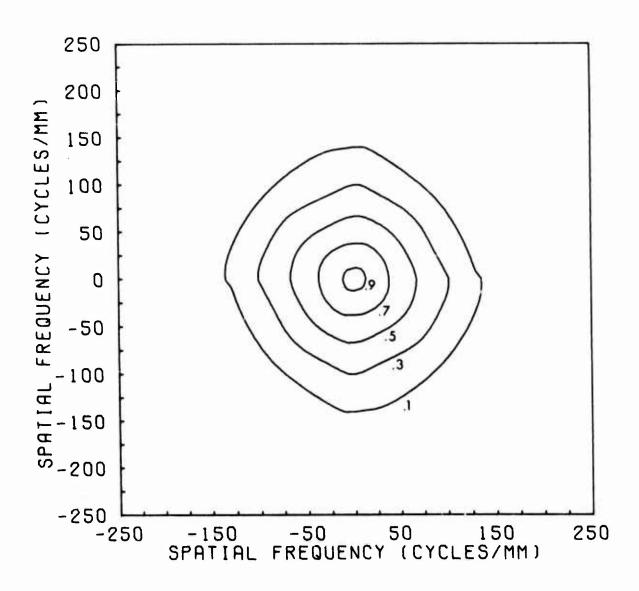
(a) Isocontours of pupil-function phase.

Figure 31.- On-axis WSI test results in plane of best focus for f/8.7 collimating doublet (collimator B); $\lambda = 632.8$ nm.



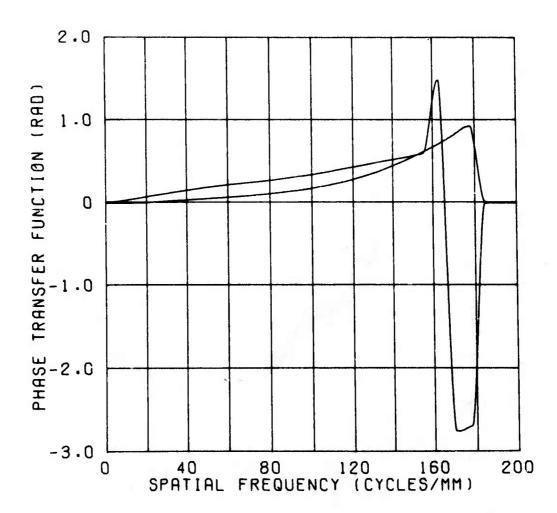
(b) Tangential and sagittal MTF.

Figure 31. - Continued.



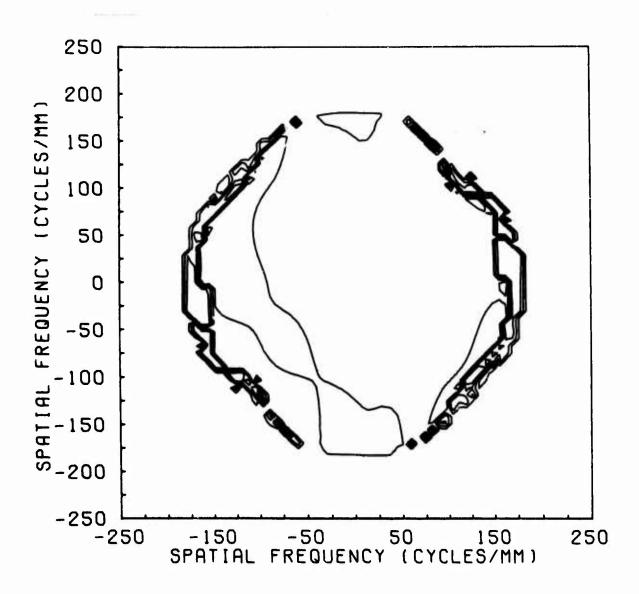
(c) Isocontours of MTF.

Figure 31. - Continued.



(d) Tangential and sagittal PTF.

Figure 31. - Continued.



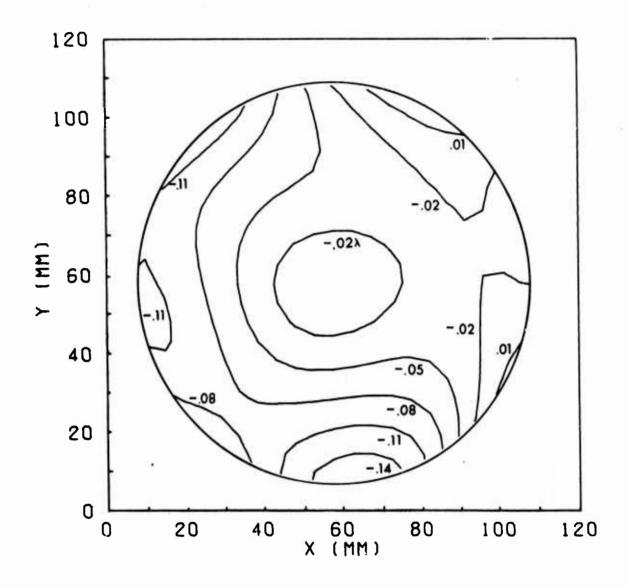
(e) Isocontours of PTF.

Figure 31. - Concluded.

TABLE 8. - MAXIMUM ABERRATIONS FOR f/8.7 COLLIMATING DOUBLET (COLLIMATOR B)^a

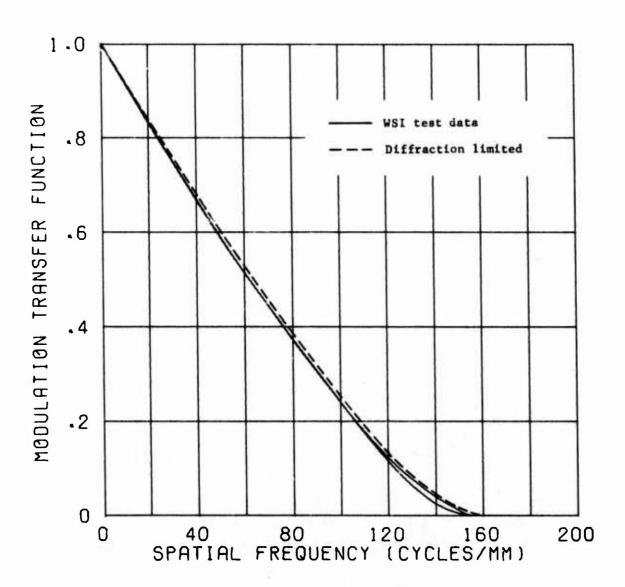
n	Maximum aberrations, units of λ	Туре
4 5	395	focus
6 7 8 9	.0391 .0097 .1796 .1781 .0463	0° astigmatism 45° astigmatism x coma (3rd) y coma (3rd)
10 11 12 13 14	.0111 9927 0304 .0328 0265	x clover (3rd) y clover (3rd) 3rd spherical 0° astigmatism (5th) 45° astigmatism (5th)
15 16 17 18 19	0526 1372 1907 0658 0877	x coma (5th) y coma (5th) x clover (5th) y clover (5th)
21 22 23	0053 .0165 -1.2698 .6658	5th spherical 7th spherical

In plane of best focus; $\lambda = 632.8 \text{ nm}$.



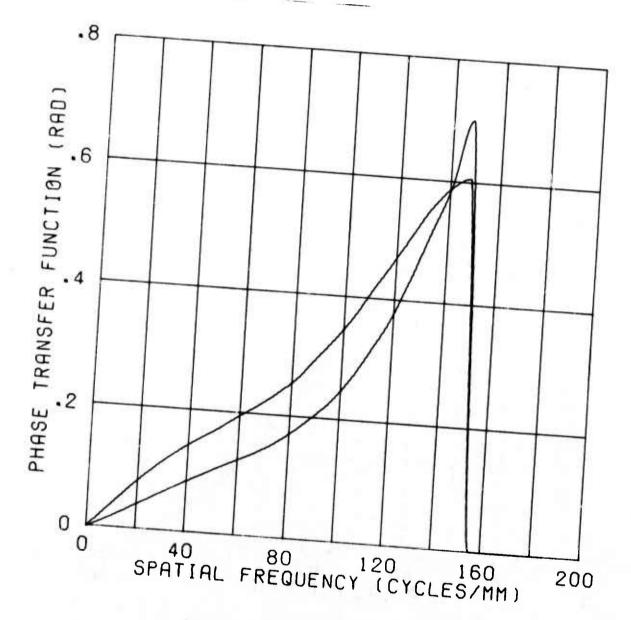
(a) Isocontours of pupil-function phase.

Figure 32.- On-axis WSI test results in plane of best focus for f/8.7 collimating doublet (collimator B) stopped down to f/10; $\lambda = 632.8$ nm.



(b) Tangential and sagittal MTF.

Figure 32. - Continued.



(c) Tangential and sagittal PTF.

Figure 32. - Concluded.

TABLE 9. - MAXIMUM ABERRATIONS FOR f/8.7 COLLIMATING

DOUBLET (COLLIMATOR B) STOPPED DOWN TO f/10^a

n	Maximum aberrations, units of λ	Туре
4	237	focus
5	.0293	·0° astigmatism
6	.0073	45° astigmatism
7	.1164	x coma (3rd)
8	.1154	y coma (3rd)
9	.0300	x clover (3rd)
10	.0072	y clover (3rd)
11	.5568	3rd spherical
12	0170	0° astigmatism (5th)
13	.0184	45° astigmatism (5th)
14	0149	
15	0295	
16	0666	x coma (5th)
17	0926	y coma (5th)
18	0320	x clover (5th)
19	0425	y clover (5th)
20	0026	Continue of Particular and American
21	.0080	
22	5334	5th spherical
23	.2095	7th spherical

^aIn plane of best focus; $\lambda = 632.8$ nm.

rotationally symmetric. This relative symmetry of the MTF is shown in the MTF isocontours plotted in figure 31(c).

The PTF for collimator B is given in figure 31(d). The differences in the tangential and sagittal PTF's are more pronounced than the differences in the corresponding MTF's. The isocontours of the PTF are plotted in figure 31(e).

Since collimator B was within a few percent of the diffraction-limited MTF, it was accepted. However, additional testing of the collimator on the WSI system to determine performance within the spectral region of 510 nm to 610 nm is planned. The collimator is used in the WSI test system to provide a collimated light beam for testing other lenses at infinite conjugates. Since the aberrations in the collimator are largest at the aperture edge, the full aperture is not used. In particular, the maximum aperture diameter used is about 10 cm or about 75 percent of the clear aperture; this is equivalent to stopping down the collimator from f/8.7 to f/10.

The performance of a lens at a greater f-number than that used in the WSI test system can be determined with the data-reduction computer program. (See appendix A.) The same test data, except for the original radius the test-lens aperture, is used as input data. The new value chosen for the radius corresponds to the modified f-number. In this case, the maximum value of the aberrations, the pupil function, and the OTF are for the stopped-down version of the test lens. For collimator B stopped down to f/10, the pupil function, MTF, PTF, and aberrations are shown in figures 32(a), 32(b), 32(c), and table 9, respectively. The resulting MTF is only about 1 percent below diffraction-limited performance up to 120 cycles/mm. The net sum of the symmetrical aberrations is $-0.004\ \lambda$, and the maximum value of the asymmetrical aberrations is about $+0.1\ \lambda$. The RMS of the wavefront is $\lambda/29$, and the effective focal length is 999.536 cm.

XII.3. OTF Standard Test Lens

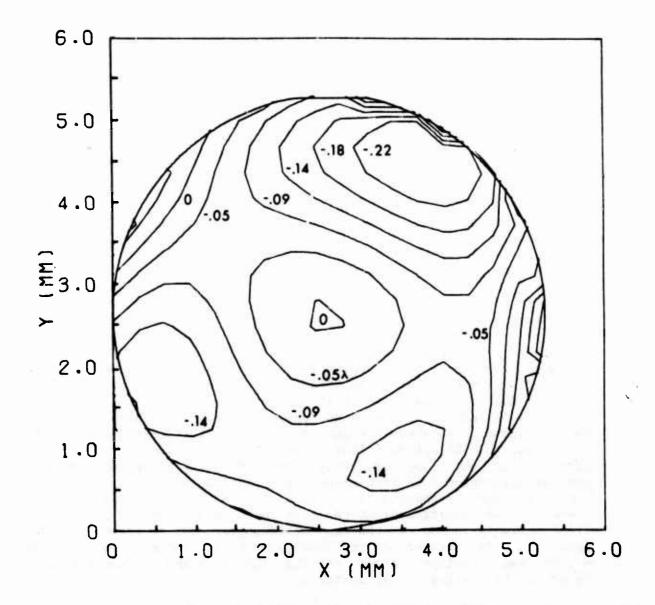
The OTF Standard Test Lens was designed and developed by SIRA, Chislehurst, Kent, Egland, as a test standard for OTF equipment. The results of OTF measurements on one of these lenses by various laboratories throughout the world are presented in reference 36. This lens is a simple planoconvex lens with a nominal thickness of 10 mm, a nominal diameter of 28 mm, and a nominal focal length of 50 mm. For the present tests, the lens was stopped down to f/8, thereby giving a lens diameter of 5.30 ± 0.025 mm. With this stop plane located 1.0 mm behind the plane surface of the lens, the image distance z_2 was 42.0 mm.

The OTF Standard Lens was tested at infinite conjugates by locating the light source about 4 m from the lens. This separation was accomplished by folding the optical path along the 2.75-m length test bench. The resulting test system was basically the system shown in figure 3 except that the test lens was located between the pellicle and interferometer cube; furthermore, the test system was single pass. A 100-W mercury-arc lamp with a monochromatic filter (λ = 546.1 nm), condensing optics, and a nominally 100- μ m-diameter pinhole were used for the light source. A cube interferometer with Φ = 4.55 mrad was used.

The first test results showed an MTF performance significantly below (as large as 25 percent) published values. Since this lens was particularly difficult to align using the Boys'-point method, it appeared that alignment errors may have been significant. Standard Lens is planoconvex with a relatively short focal length and, therefore, shows only one visible Boys'-point or subsidiary image. For this reason, a different alignment technique, which uses the one subsidiary image, a lens image of crosshairs, and a reflection from the front plane surface of the lens was devised. With this technique, the lens appeared to be centered when viewed through an alignment telescope; the supplier states that the lens optical axis is within 0.025 mm of the geometrical center of the lens aperture. However, the test-lens mount still did not have sufficient control for aligning the lens within the high degree of accuracy required for onaxis testing. An improved nodal slide for the test lens was obtained only after the OTF Standard Test Lens, which was on loan, had to be returned to the supplier; this improved nodal slide was used for testing collimator B as discussed in the previous section. Therefore, the test data presented in this section may contain slight errors stemming from misalignment of the test lens. Also, errors resulting from misregistration of the two interferograms may be present in the test data. An improved set of fiducial marks to reduce registration errors was developed after testing the OTF Standard Test Lens and prior to the testing of collimator B.

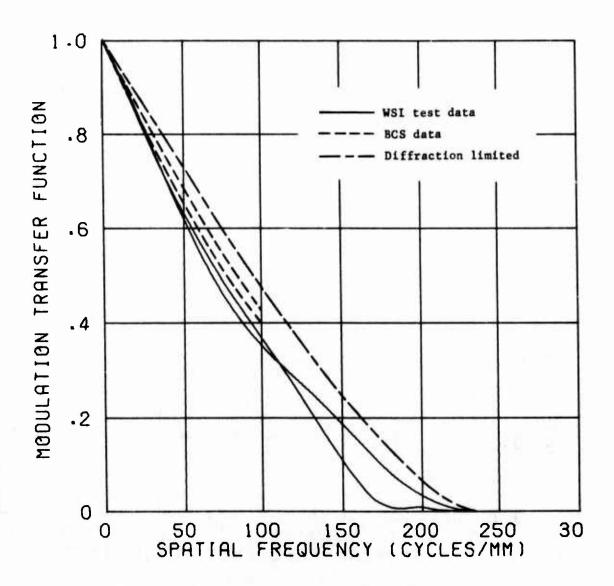
The resulting pupil function, MTF's, and PTF's for the plane of best focus are shown in figure 33. Table 10 lists the resulting maximum aberrations.

As shown in figure 33(a), the pupil function is asymmetric. The largest asymmetrical aberrations are x-coma (third and fifth-order) and x-clover (third and fifth-order); each of these aberrations has a maximum value of 0.09 λ to 0.17 λ . In reference 36, it is noted that with the stop positioned 1 mm from the plane surface of the OTF Standard Test Lens, coma is almost a minimum and, as a result, there is very little variation in the PTF as one goes off axis.



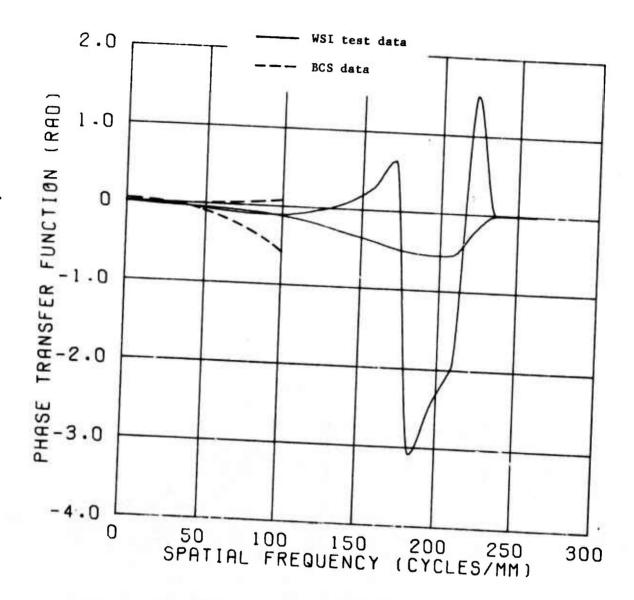
(a) Isocontours of pupil-function phase.

Figure 33.- On-axis WSI test results in plane of best focus for f/8 OTF Standard Test Lens; $\lambda = 546.1$ nm.



(b) Tangential and sagittal MTF.

Figure 33. - Continued.



(c) Tangential and sagittal PTF.

Figure 33. - Concluded.

TABLE 10. - MAXIMUM ABERRATIONS FOR f/8 OTF STANDARD TEST LENS^a

n	Maximum aberrations, units of λ	Type
4	618	focus
5	.0119	0° astigmatism
6	.0092	45° astigmatism
7	1717	х coma (3rd)
8	.0403	y coma (3rd)
9	.1919	x clover (3rd)
10	.0500	y clover (3rd)
11	1.0444	3rd spherical
12	0178	0° astigmatism (5th)
13	.0581	45° astigmatism (5th)
14	.0314	
15	0839	
16	.2356	x coma (5th)
17	.0363	y coma (5th)
18	1485	x clover (5th)
19	0376	y clover (5th)
20	.0161	
21	.0273	The second second
22	6480	5th spherical
23	.1919	7th spherical

^aIn plane of best focus; $\lambda = 546.1$ nm.

Therefore, assuming that minimum coma should be well below the 0.17 λ determined from the present test data and that coma does not increase significantly for slightly off-axis positions, the measured value of coma would not be expected from the possible lens misalignment discussed earlier. The maximum deviation of the wavefront is about 0.3 λ , and the RMS of the wavefront is $\lambda/14$. The effective focal length, as measured from the stop plane rather than the second principal plane, is 41.658 mm.

In figure 33(b) the MTF for diffraction-limited performance of an f/8 lens and the MTF of the OTF Standard Test Lens as measured by the British Calibration Service (BCS) are given along with the MTF measured on the WSI test system. Both of the measured MTF's show that the lens is not diffraction limited. The differences between the tangential and sagittal MTF's are greater for the BCS data than the WSI data. Assuming that the MTF is not symmetric as these data show, these differences would be expected since the lens orientation about the optical axis was most likely not the same setting in the two test systems, i.e., the tangential and sagittal directions for the two sets of test data are not the same. The manufacturer of the OTF Standard Test Lens claims that the lens orientation about the test-system optical axis is unimportant since the lens has been constructed with a high degree of precision. However, as the measured MTF's show, the lens does exhibit asymmetry. It should be noted that the BCS test data does not extend beyond 100 cycles/mm, but the WSI test data continues out to the test-lens cut-off frequency. The WSI test system, unlike some other OTF-measurement systems, does not use an illuminated target of varying spatial frequency which is imaged by the test lens. Therefore, the WSI test system does not depend on the quality of the target or the degree of coherence of the target illumination; these factors can introduce OTF-measurement errors in the associated test systems, particularly at spatial frequencies beyond 100 cycles/mm [37]. The fairly large differences in the tangential and sagittal MTF's above 100 cycles/mm for the WSI test data may be due in part to lens misalignment or interferogram misregistration as discussed earlier.

The PTF's for the OTF Standards Lens as measured in the present tests and as measured by the BCS are given in figure 33(c). The closer agreement between tangential and sagittal values for the WSI test results as compared to the BCS test results is quite evident. The large differences in the tangential and sagittal PTF's in the vicinity of 100 cycles/mm for the WSI test data, like the MTF's, may in part result from lens misalignment or interferogram misregistration.

XIII. COMPUTER PROGRAMS

The computer software for use with data from the WSI system consists of three programs to perform the following tasks: (1) reduction of fringe data to determine lens aberrations, pupil function, and OTF; (2) plotting of pupil function, MTF, and PTF; and (3) reduction of optical-density data from automatic fringe scanner to determine fringe-peak locations and lens aperture boundary. These programs are written in FORTRAN V for the Univac 1100 series computer systems. Some changes may be required to use these programs on other computer systems. A flow diagram of the complete data-reduction procedure for the WSI interferograms, including the computer programs, is given in figure 34.

An outline of the program operations, a tabulation of input and other variables, and a computational listing are presented for each of the three programs in appendices A, B, and C; sample printouts for the programs discussed in appendices A and B are also given. Other auxiliary program variables and parameters are also defined in these appendices, but no attempt has been made to define every alphanumeric quantity such as indexing parameters and dummy variables. The program listing contains comment cards which further define program variables and explain program operations.

Table 11 gives the approximate computer words required to execute the latest versions of the data reduction and plotting programs on the Univac 1108/Exec 8 computer system at the National Bureau of Standards, Washington, D.C. Also, included in this table are typical central-processor times for the programs at the NBS facility. The central-processor time for the data-reduction program in dependent on the size of the input data array (fringe-peak locations); the value given in table 11 is for an average array size of 25 (fringes) by 25 (scans) for each interferogram.

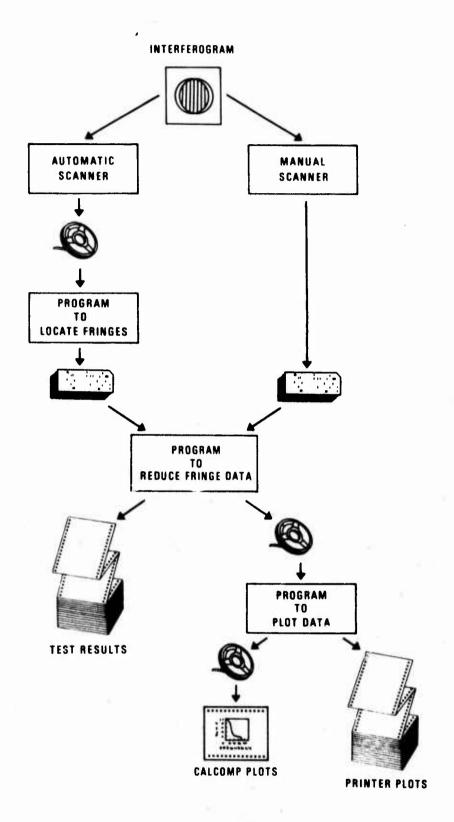


Figure 34.- Flow diagram of complete data-reduction procedures for WSI interferogram.

TABLE 11. - EXECUTION TIME AND STORAGE REQUIREMENT FOR WSI COMPUTER PROGRAMS

Computer program	Central processor time (CPU), sec.	Computer words
Data reduction	180 ^a	10.00
Plotting	50	40,200 55,900
a _{For highlan}		33,300

For highly aberrated test lenses, the time required to search for plane of best focus may significantly increase CPU time.

bl word is 36 bits for Univac computer system.

XIV. CONCLUSIONS

The present study was directed towards developing, evaluating, and installing an interferometric lens-testing system that would fit the test requirements of the sponsor. A wavefront shearing interferometer (WSI) system was developed and used to test several lenses on axis at the National Bureau of Standards. Several computer programs were also developed to automate reduction of the WSI test data.

A set of eight WSI cubes, which permits lens testing over a wide range of f-numbers, was fabricated and delivered to the sponsor. The computer programs for reducing both the WSI test data and the interferogram scan data from an automatic scanner were also presented to the sponsor. An automatic scanner purchased by the sponsor was tested and used at NBS for scanning some WSI interferograms; this scanner was later installed at the sponsor's facilities and subsequently interfaced to a minicomputer to permit controlled scanning. Therefore, a viable WSI test system is currently available to the sponsor at the sponsor's facilities.

Lens testing with the WSI at the NBS demonstrated the following:

- the WSI is a versatile, inexpensive, and simple alternative for interferometric testing of lenses; lenses may be tested at infinite or finite conjugates;
- 2) the major effort required in testing with the WSI is data reduction; with the available computer programs and an automatic scanner, this task is greatly simplified;
- asymmetric aberrations introduced by the WSI cube, which acts as a glass plate, can be kept to less than 0.05 wavelength by careful alignment procedures; spherical aberration is automatically removed in the data-reduction program and defect of focus is compensated during testing;
- 4) the major source of error in WSI testing is generally misalignment of the test lens; a nodal slide with translational and rotational controls is necessary to reduce alignment errors;
- 5) present testing techniques have resulted in root-mean-square differences of less than 0.04 wavelength; these differences could be further reduced with improvements in the technique to register the x and y-sheared interferograms;
- 6) recommendations for further testing with the WSI include extension to off-axis testing, improvement of the efficiency

and accuracy of data-reduction computer programs and extension of these programs to partially obscured and non-circular lens apertures, development of alternate techniques for locating the aperture boundary with the automatic scanner, and development of a real-time test system in which an aerial image of the fringe pattern is scanned, the results fed directly into a computer, and the lens performance automatically displayed on a viewing screen.

XV. RECOMMENDATIONS

Although the WSI test system and data reduction procedures developed in the present study meet the requirements of the sponsor for a viable lens and mirror test system, there are modifications, extensions, and alternatives to be recommended. The implementation of these recommendations will depend, in part, on the specific needs of the user and the computer and scanning facilities available to the user.

A very desirable WSI test system would be one that performs essentially real-time testing. For such a system, the aerial image of the interference pattern would be scanned, rather than scanning a photographic record. The scan information would be input directly into a computer which, in turn, would reduce the test data. The resulting pupil function, MTF, PTF, and aberrations would be displayed on a viewing screen. With this system, the effect of lens alignment and other test-system parameters on the lens performance could be noted almost immediately. Thus, the systematic errors could be minimized. In addition, the time required for testing would be greatly reduced.

The WSI test system should be extended to off-axis testing. Lenses and mirrors are generally used to image an extended object, rather than a point source, and, therefore, the performance of the lens or mirror for off-axis imaging should be measured. With any of the various techniques currently used for off-axis testing, the primary difficulty is a very accurate measurement of the field position. For the WSI test system, this specification of field position means that the location and orientation of both the cube interferometer and the test lens with respect to the test-system optical axis must be measured accurately. In addition, the data-reduction computer program would have to be modified to process non-circular (elliptical) apertures.

Fiducial marks that can be correctly identified from the automatic-scanner data should be developed in order to reduce the interferogram-registration errors for automatic scanning. The current approach for registration of the x and y-sheared interferograms is designed primarily for a manual scanner. The image analysis for fiducial marks to be used with an automatic scanner should include the following: (1) distinguish fiducial marks from fringe locations, aperture boundary, and film defects; (2) identification of the x and y axes; and (3) distinguish between the x and y-sheared interferograms.

automatic scanning, it is also recommended that other techniques for locating the edge of the test-lens aperture be investigated. The present approach of manually punching holes at the fringe terminals preparatory to scanning is subject to errors in

The computer programs for reducing data from the automatic scanner and for determining the pupil function, OTF, and aberrations should be extended to include data from a partially obscured aperture, and a non-circular aperture. In addition, these computer programs should be optimized in terms of efficiency and accuracy. Alternate computational techniques for such quantities as the pupil function and

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APPENDIX A

COMPUTER PROGRAM TO REDUCE WSI FRINGE DATA

The computer program used to determine lens performance from the WSI fringe data is presented. An outline of program operation is given together with a detailed input description, auxiliary definitions of program variables, listing of subroutines, computation program listing, and a sample printout.

Outline of Program Operation

The outline of the program is presented with references to sections of this report that contain detailed information on the particular topic. The present program assumes the following: (1) input fringe data will be no longer than a 29 x 29 array; (2) lens aperture is circular and unobscured; (3) data from one scan does not contain more than one pair of coodinates for the same fringe, i.e., closed or looped fringe data is not treated; and (4) amplitude of pupil function is constant and assumed to be unity over the lens aperture.

A. Input data

- 1. Test-lens and experimental parameters
- Fringe-peak coordinates and fringe orders from either manual or automatic scanner

B. Calculations

- 1. Register fringe data from x and y-sheared interferograms in common coordinate system (See appendix D.)
- 2. Convert fringe-coordinate data to normalized values using shear distance (See section IV.)
- 3. Use spline fit to interpolate fringe orders at grid points of rectangular normalized grid (See section IV.)
- 4. Determine pupil function to within a constant at grid points (See section IV.)
- 5. Perform least-squares fit of pupil function to twentythree term polynomial representing aberration (See section IV.)

- 6. Remove symmetrical aberrations introduced by WSI cube from pupil function (See section VI.2.)
- 7. Remove constant and x and y tilt terms from pupil function
- 8. Calculate root mean square (RMS) of initial solution of pupil function, RMS of polynomial describing pupil function, and RMS of difference in these two solutions of the pupil function
- O Calculate maximum values of aberrations at edge of lens aperture
- 10. Determine from polynomial representation values of pupil function in areas (lunes) of aperture for which fringe data could not be interpolated
- 11. Determine focal plane for which RMS of pupil function is a minimum by adjusting defocus term (See section V.2.)
- 12. Calculate pupil function (complex quantity) where amplitude is assumed to be constant with a value of 1.0
- 13. Calculate OTF by auto-correlation of pupil function (See section V.1.)
- 14. Determine MTF and PTF

C. Output data

- 1. Paper printout (See sample printout.)
 - a. Test-lens experimental parameters
 - b. Fringe-peak coordinates from scanner for x and ysheared interferograms
 - c. Normalized fringe-peak coordinates for y and y-sheared interferograms
 - d. List of grid coordinates which lie inside lens aperture but outside region of interpolation

- e. Incidence matrix for x and y-sheared interferograms to show grid points at which fringe orders were interpolated
- f. Fringe-order deviations determined at grid points by interpolation for x and y-sheared interferograms
- g. Values of the pupil function to within a constant
- h. Symmetrical aberrations introduced by WSI cube
- Differences between initial solution and polynomial representation of pupil function
- j. RMS of initial solution, RMS of polynomial representation of pupil function, and RMS of difference between these two solutions
- k. Listing of aberration coefficients and maximum values of aberrations
- Incidence matrix for grid points to indicate whether fringe order was interpolated, extrapolated, or outside of lens aperture
- m. Pupil-function phase values corresponding to the focal plane specified by input value
- n. Defocus coefficient, focal distance, and RMS or wavefront for different focal planes separated by increments of Rayleigh depth-of-focus tolerance
- o. Pupil-function phase values corresponding to optimum focal plane
- p. Coordinates of grid points
- q. Values of complex pupil function
- r. OTF values
- s. MTF and PTF values
- t. List of parameters written on tape for plotting program
- Magnetic tape with values of parameters, pupil function, and OTF to be used by plotting program.

Auxiliary Definitions

Several quantities appear in the final printout. In addition, some of these and other quantities can be useful in evaluating the sequence of operations in the program listing. Those quantities which have not been defined elsewhere are defined as follows:

FORTRAN Variable	Description
B(I)	Aberration coefficient in polynomial describing wavefront, b
B4CUB	Coefficient of defocus introduced by cube, a2
B4MAX	Maximum value of defocus introduced by cube, a2
B11CUB	Coefficient of third-order spherical aberration introduced by cube, a ₃
B11MAX	Maximum value of third-order spherical aberration introduced by cube, a ₃ (RADIUS/z ₂) ⁴
B22CUB	Coefficient of fifth-order spherical aberration introduced by cube, a4
B22MAX	Maximum value of fifth-order spherical aberration introduced by cube, a_4 (RADIUS/ z_2) ⁶
B23CUB	Coefficient of seventh-order spherical aberration introduced by cube, a ₅
B23MAX	Maximum value of seventh-order spherical aberration introduced by cube, a_5 (RADIUS/ z_2) ⁸
B4BEST (M)	Coefficient of residual defocus for plane of best focus
DE(I,K)	Phase of pupil function or deviation of wavefront from reference sphere, ϕ (x,y)
DEFFOC	Maximum value of residual defocus for plane of best focus
DEL(I,K)	Phase of pupil function with constant b_1 and tilt terms b_2x , and b_3y present
DELTA	Shear distance, Δx or Δy
DELTXY	Spatial-frequency increment, $\Delta \mu_{x}$ or $\Delta \mu_{y}$

FORTRAN Variable	Decription
DEVMAX	Maximum value of pupil-function phase
DEVMIN	Minimum value of pupil-function phase
F(L)	Terms of polynominal describing wavefront, F(x,y)
FNO	f-number of test lens, $z_2/2$ (RADIUS)
FNOBST	f-number of test lens for plane of best focus
FRACT	Multiplicative factor by which focal plane is shifted along optical axis in units of Rayleigh tolerance on depth of focus
FRSPAC	Fringe spacing in interferogram of perfect lens, $(\lambda z_2)/(\ell \Phi)$
HD(J,K)	Interpolated fringe-order deviation for x-sheared interferogram, $P(J, K, N)$ or $Q_{m,n}$
ISUMA	Total number of grid points for which fringe-order values were interpolated
ISUMB	Total number of grid points for which fringe- order values were extrapolated
ISUM	ISUMA + ISUMB
кх	Reduced spatial-frequency increment along x-axis,

MI(I,K) Incidence

KY

Incidence matrix for test-lens aperture; MI = 1 indicates that fringe-order value was interpolated at grid point (I,K); MI = 2 indicates that fringe-order value was extrapolated at grid point (I,K); MI = 0 indicates that grid point lies outside

Reduced spatial-frequency increment along y-axis,

aperture

MII(I,K)

Incidence matrix for x-sheared interferogram; MII

(I,K) = 1 indicates that fringe-order value was interpolated at grid point (I+2, K+2); MII(I,K) = 0 indicates that no interpolation was made or grid point lies outside aperture

FORTRAN Variable	Description
MI2(I,K)	Incidence matrix for y-sheared interferogram; MI2 (I,K) = 0 indicates that fringe-order value was interpolated at grid point (K+2, I+2); MI2 (I,K) = 0 indicates that no interpolation was made or grid point lies outside aperture
N	Trigger or subscript to identify interferogram or frame
	<pre>N = 1 for x-sheared interferogram N = 2 for y-sheared interferogram</pre>
NS 👡	Maximum number of scans for either x or y-sheared interferogram
OTF(I,K)	Optical transfer function
P(J,K,N)	Interpolated fringe-order deviation for x or y-sheared interferogram, $Q_{m,n}$ or $S_{m,n}$
POLYMX(I)	Maximum value of aberration term; $b_n F_n (x,y)$ where $x^2 + y^2 = (RADIUS)^2$ and $n = 1,2,23$
RAYLGH	Rayleigh tolerance on depth of focus, \pm 3.2 $(\lambda/2\pi)$ $(z_2/RADIUS)^2$
RMS	Root mean square of DEL values after removing cube aberrations and b_1 , b_2 x, and b_3 y
RMSDE	Root mean square of DE values, including extrapolated values, after removing cube aberrations and b_1 , b_2x , and b_3y
RMSMAX	RMSDE for plane of best focus
RMSR	Root mean square of DE value (interpolated) after removing cube aberrations and b_1 , b_2x , and b_3y
RMSS	Root mean square of V(I,K)
SIGN	Sign of Rayleigh tolerance on depth of focus; SIGN = 1.0 for focal plane shifted away from test lens; SIGN = - 1.0 for focal plane shifted towards test lens

FORTRAN Variable	Description
TRANS(I,K)	Pupil function
VD(J,K)	Interpolated fringe-order deviation for y-sheared interferogram, $P(J,K,2)$ or $S_{m,n}$
V(I,K)	Residual wavefront, DEL(I,K) - DE(I,K)
x	x-coordinate of grid point, X_{m}
X(J,K,N)	x-coordinate of fringe-peak location, x,j
XCEN	x-coordinate of center of aperture, XCEN = RADIUS
XGRID(1,K)	x-coordinate of grid point, X_{m}
XINT	Coordinate of grid point at which fringe order is interpolated in x or y-sheared interferogram, X_m or Y_n
X1(K)	x-coordinate of left-hand boundary of aperture along Kth scan
X2(K)	x-coordinate of right-had bountary of aperture along Kth scan
Y	y-coordinate of grid point, Y n
YBOUN1	y-coordinate of upper boundary of aperture, YCEN - RADIUS
YBOUN2	y-coordinate of lower boundary of aperture, YCEN + RADIUS
YCEN	Y-coordinate of center of aperture, YCEN = RADIUS
YGRID(K)	y-coordinate of grid point, Yn
YINT	Interpolated fringe order for x or y-sheared interferogram, $p(X_m)$ or $p(Y_n)$
ZZ2(M)	Focal-plane position along z-axis
Z2BEST	Optimum focal-plane position along z-axis

Subroutines

A list of the subroutines used in this program is presented

FORTRAN		
Name	Called by	Function
SPLICO	MAIN	Determination of coefficients for spline-fitting interpolation (See reference 16).
SPLINE	MAIN	Interpolation of fringe order by method of spline fitting (See reference 16.)
SPECSP	MAIN	Interpolation of fringe order by method of spline fitting in special case of only two fringe-peak data for a scan
DEV	MAIN	Determination of pupil function, aberrations, and plane of best focus
INVERT	DEV	Perform matrix inversion by method of Gauss-Jordan Elimination (See reference 39.)
CORREL	MAIN	Compute optical transfer function by auto-correlation of pupil function

Input Description

The following list contains the program input variables which are arranged according to order of presentation in the program.

Frame 1 is the x-sheared interferogram and frame 2 is the y-sheared interferogram. All variables that represent distances or coordinates in the lens aperture are measured from the interferograms as shown in figure 35.

Input Card	FORTRAN Variable	Description
1	TEST	Identifies test lens and test number or date
2	FOCUS	Trigger for determining focal plane in which OTF is calculated FOCUS = 1 nominal focal plane at distance Z2 FOCUS = 2 for optimum focal plane where RMS of wavefront is minimum
3	CUBE	Trigger for determining and removing defocus introduced by cube by interferometer CUBE = 1 for experimental case of measuring ZL from null fringe position; only corrections for spherical aberration are made CUBE = 2 for experimental case of measuring ZL from nominal focal plane at Z2; correction for defect of focus and spherical aberration are made
	THICK	Cube thickness, t, mm
4	ZL*	Distance along optical axis from nominal focal point or null-fringe position to back of cube, £, mm (See figure 4.)
	22	Nominal focal length, Z ₂ , mm (See figure 4.)

^{*}This value is positive if cube is located between focal point and auxiliary lens and negative if cube is located between test lens and focal point.

Input Card	FORTRAN <u>Variable</u>	Description
	XMAG	Magnification of interferogram; ratio of diameter of test-lens aperture as measured on interferogram to nominal diameter of test-lens aperture
	РНІ	Cube shear angle, Φ, rad
	WAVEL	Wavelength of light used to illuminate test lens, λ , mm
5	PASS	Trigger for double-pass tests PASS = 1 for single-pass test PASS = 2 for double-pass test
6	INPUT	Trigger to indicate method used for scanning interferogram INPUT = 1 for fringe data from manual scanner INPUT = 2 for fringe data from automatic scanner
7	сх	Distance along x axis of scanner from coordinate origin to left side of unsheared aperture for frame 1; mm (See figure 35.)
	СҰ	Distance along y axis of scanner from coordinate origin to right side of unsheared aperture for frame 2; mm (See figure 35.)
	POSX*	Distance along y axis of scanner from aperture edge to first scan for frame 1; mm (See figure 35.)
	POSY*	Distance along y axis of scanner from aperture edge to first scan for frame 2; mm (See figure 35.)

^{*} The values selected should be less than the shear distance DELTA; recommended values are DELTA/2.

Input Card	FORTRAN <u>Variable</u>	Description
	RADIUS	Radius of test-lens aperture as measured from interferogram; mm
8	NSX	Number of scans in frame 1
	NF1	Number of fringes in frame 1
9	NSY	Number of scans in frame 2
	NF2	Number of fringes in frame 2

The remaining input cards contain scan parameters and fringe-peak locations. The order of these cards depends upon the type of fringe scanning (manual or automatic), and the total number of cards depends upon the number of fringes and scans. The arrangement of these input cards is outlined for both methods of fringe scanning.

Manual Scanning:

FORTRAN Variable	Description
К	Scan number; K = 1
J1	Order number for first fringe of Kth scan; K = 1
Ј2	Order number for last fringe of Kth scan; K = 1
X(J,K,N)	Fringe-peak location of Jth-order fringe of first scan of frame 1; mm
: : X(J,K,N)	J = J1; K = 1; N = 1
K,J1,J2	Scan parameters for scan 2
X(J,K,N)	J = J1; K = 2; N = 1
X(J,K,N) :	J = J2; K = 2; N = 1
	Variable K J1 J2 X(J,K,N) X(J,K,N) K,J1,J2 X(J,K,N)

The input data cards are continued in the above manner from all scans and fringe-peak locations for frames 1 and 2; data from frame 2 follow the data of frame 1 and are arranged in the same format.

Automatic Scanning:

Note: These input cards contain a rectangular array of values of X(J,K,N) for each frame; since the test lens aperture is circular, X(J,K,N) = 0.0 for some values of J and K.

Input Card

12

X(J,K,N)

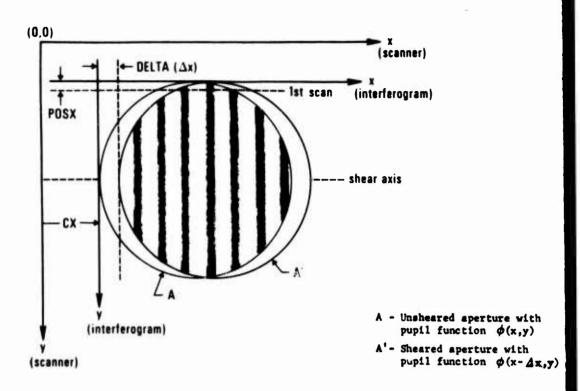
The order of these input cards is best described by giving the READ and FORMAT statements from the program:

READ (5,215)((X(J,K,N),J=1,7),K=1,NS) READ (5,219)((X(J,K,N), J=8,15),K=1,NS) READ (5,219)((X(J,K,N),J=16,23),K=1,NS) READ (5,219)((X(J,K,N),J=24,29), K=1,NS)

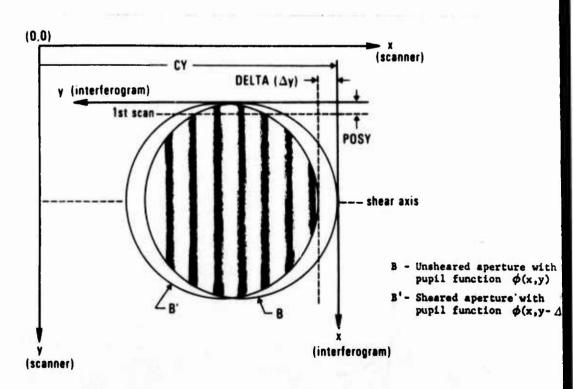
215 FORMAT (7X,7F7.2) 219 FORMAT (8F7.2)

(See auxiliary definitions for NS.)

The input data cards are repeated in the above manner for frame 2 (N=2).



(a) x-sheared interferogram.



(b) y-sheared interferogram.

Figure 35.- Schematic of x and y-sheared WSI interferograms showing measured parameters for input to data-reduction computer program.

Computation Program Listing

THE FOLLOWING PRORAM PERFORMS THE DATA REDUCTION OF WSI C INTERFERGGRAMS TO OBTAIN PUPIL FUNCTION, OTF, MTF, AND PTP C FOR TEST LENS INPUT DATA ARE FRINGE-PEAK POSITIONS FROM EITHER -(1) MANUAL SCANNER OR (2) AUTOMATIC SCANNER DIMENSION B(23), C(4,32), DE(32,32), DU(32), DUMMY(2), HD(32,32), 1MI(32,32), MI1(32,32), MI2(32,32), P(72,32,2), VD(32,32), X(32,32,2), 2XDUN(32) DIMENSION TEST(6) COMPLEX TRANS(32,32), GTF(65,65) REAL JDUM(32) INTEGER PASS, CUBE, FOCUS EQUIVALENCE (HD(1,1),P(1,1,1)),(VD(1,1),P(1,1,2)) THE FOLLOWING PARAMETER IS READ AS INPUT TO IDENTIFY TEST LENS READ(5,3) (TEST(1),1-1,6) 3 FORMAT(6A6) THE FOLLOWING PARAMETER IS READ AS INPUT TO PERMIT DETERMINATION OF PUPIL-FUNCTION PHASE IN PLANE OF BEST FOCUS READ(5, 10)FOCUS THE FOLLOWING PARAMETERS ARE READ AS INPUT TO PERMIT DETERMINATION OF THE EFFECT OF THE CUBE INTERFEROMETER ON TEST-LENS WAVEFRONT READ(5, 11)CUBE, THICK 11 FORMAT(12, F10.3) THE FOLLOWING PARAMETERS ARE READ AS INPUT DATA IN ORDER TO CALCULATE SHEAR DISTANCE (DELTA) AND SPATIAL FREQUENCY (DELTXY) READ(5,15)ZL,Z2,XMAG,PHI,WAVEL 15 FGRMAT(3F10.3, 2E10.3) THE FOLLOWING PARAMETER IS READ AS INPUT TO ALLOW PROGRAM TO HANDLE DATA FROM DOUBLE-PASS SYSTEM READ(5, 10)PASS 10 FGRMAT(12) THE FOLLOWING PARAMETER IS READ AS INPUT TO INDICATE IF INTERFERGRAMS WERE SCANNED MANUALLY OR AUTOMATICALLY READ(5,10)INPUT IP(INPUT.EQ.1) GG TG 100 IF(INPUT.EQ. 2) GO TO 200 THE FOLLOWING PARAMETERS ARE READ AS INPUT DATA IF THE INTERPERGGRAMS ARE SCANNED MANUALLY 100 READ(5,16)CX,CY,PGSX,PGSY,RADIUS 16 FGRMAT(5F10.3) READ(5,12)NSX,NF1 12 FORMAT(312) READ(5, 12)NSY, NF2 FRINGE-PEAK POSITIONS ARE READ FOR A GIVEN SCAN MAXINUM NG. OF FRINGES ALLOWED PER FRAME IS 29 N-1

NSS-NSX

201 READ(5,12)K, J1, J2

READ(5,14)(X(J,K,N),J-J1,J2)

```
14 FGRMAT(5XF7.3)
   IP(K.LT.NSS) GG TG 201
   IF(N. EQ. 2) GG TG 19
   NSS-NSY
   G6 T6 201
19 NS-MAXO( NSX, NSY)
   WRITE(6,1)TEST
 1 PORMAT(1H1,10X THE POLLOWING PRINT OUT RESULTS FROM A COMPUTER DAT
  2A REDUCTION OF TWO INTERFEROGRAMS OBTAINED BY TESTING THE 1/48X 6A
  36//35x on the Wavepront Shearing Interperoneter (WSI) test system!
  4////>
    WRITE(6, 30)
 30 FORMAT(1H VALUES AND DEFINITIONS OF PROGRAM PARAMETERS ARE PRINTE
  1D BELOW -1/6X NOTES (1) X AND Y AXES ARE COORDINATE SYSTEM OF SCAN
   2NER 1/12X 1(2) DISTANCE VALUES ARE IN MM UNLESS SPECIFIED OTHERWISE 1
    WRITE( 6, 29 )
 29 FORMAT(1H 'INPUT - 1 INDICATES THAT INPUT DATA WAS FRINGE-PEAK POS
   1 ITIONS OBTAINED FROM MANUAL SCAN'/)
    IP(PASS .EQ. 1) WRITE(6,205)
    IF(PASS .EQ. 2) WRITE(6,206)
205 FORMAT(1H PASS - 1 INDICATES THAT TEST SYSTEM WAS SINGLE PASS 1//)
206, FORMAT(1H PASS - 2 INDICATES THAT TEST SYSTEM WAS DOUBLE PASS 1//)
    WRITE(6, 31)CX,CY,PGSX,PGSY,RADIUS,NF1,NF2,NSX,NSY,NS
 31 FORMAT(15X FRAME 1 IS X-SHEARED INTERFEROGRAM AND FRAME 2 IS Y-SHE
   1ARED INTERFERGGRAM 1///4X CX - 1F8.3,5X DISTANCE ALONG X-AXIS BETWE
   2EN Y-AXIS AND APERTURE EDGE IN FRAME 11//4X1CY = 158.3,5X65H
   48X = 1F8.3.5X DISTANCE ALONG Y-AXIS BETWEEN FIRST SCAN POSITION AN
   5D X-AXIS IN PRAME 1 //4X PGSY - 1F8.3,5X71H
   6 11
                               . .
                                    11
                                          11 FRAME 2//4X RADIUS . F8.
   73.5X RADIUS OF TEST-LENS APERTURE 1/4X NF1 - 113.5X NUMBER OF FRIN
   8GES IN FRAME 1 1/4X NF2 - 13,5X28H 11 11
                                                         II FRAME 2//4
   9x'nsx - 13,5x'number of scans in frame 1'//4x'nsy - 13,5x26H
      11 11 FRAME 2//4X'NS - 113,5X'MAXIMUM NUMBER OF SCANS IN
   2PITHER FRAME!)
    IF(INPUT.NE.2) GO TO 34
    THE FOLLOWING PARAMETERS ARE READ AS INPUT DATA IF THE
    INTERFERGGRAMS ARE SCANNED AUTOMATICALLY
200 READ(5,16) CX,CY,PGSX,PGSY,RADIUS
    READ(5, 12)NSX, NF1
    READ(5, 12)NSY, NF2
    WRITE(6,1) TEST
    WRITE(6,30)
    WRITE(6, 33)
 33 FORMAT(2X INPUT - 2 INDICATES THAT INPUT DATA WAS FRINGE-PEAK POSI
   11TIONS OBTAINED FROM AUTOMATIC SCAN 1/)
    IF( PASS .EQ. 1) WRITE( 6, 205)
    IF(PASS .EQ. 2) WRITE(6,206)
    N-1
```

210 READ(5,215)((X(J,K,N),J-1,7),K-1,NS)
READ(5,219)((X(J,K,N),J-8,15),K-1,NS)
READ(5,219)((X(J,K,N),J-16,23),K-1,NS)
READ(5,219)((X(J,K,N),J-24,29),K-1,NS)

IF(N.EQ.2) GG TG 35 N-2 NS-NSY G6 T6 210 215 FORMAT(7X,7F7.2) 219 FORMAT(8F7.2) 35 NS-MAXO(NSX,NSY) WRITE(6, 31)CX, CY, POSY, POSY, RADIUS, NF1, NF2, NSX, NSY, NS 1 DISTANCE ALONG OPTICAL AXIS BETWEEN BACK FACE OF CUBE INTERFEROME 2TER AND TEST-LENS FOCUS 1//1H 1 Z2 - 1F8.3,5X1 IMAGE DISTANCE OF T PHI - 1 EG.4.2X'RAD1 5X'SHEAR ANGLE OF C //1H 1 3EST LENS! AUBE INTERFEROMETER 1/1H WAVEL - 1 E9.4, 2X MM 5X WAVELENGTH OF SLIGHT SCURCE 1//1H 1 XMAG = 1F6.3.5X1MAGNIFICATION OF INTERFERENC 6E PATTERN OCCURRING IN SCANNED INTERFEROGRAM //IH THICK - F7. 73,2X MM SX WSI CUBE THICKNESS //) COMPUTE SHEAR DISTANCE IN INTERFERGERAM FOR COORDINATE **NORMALIZATION** DELTA-(ZL+Z2)+PHI+XMAG WRITE(6,39)DELTA DELTA - 'F6.3,5X'COMPUTED SHEAR DISTANCE'/) 39 FORMAT(1H COMPUTE FRINGE SPACING IN INTERFEROGRAM FOR IDEAL LENS ZL-ABS(ZL) FRSPAC*((WAVEL*Z2)/(ZL*PHI))*XMAG WRITE(6, 40)FRSPAC 40 FORMAT(1H FRSPAC - 'F8.3,5X'FRINGE SPACING FOR IDEAL LENS'/) WRITE(6,42) 42 FORMAT(181 FRINGE-PEAK POSITIONS X(J,K,N) AS SCANNED (INPUT DATA) 1ARE PRINTED BELOW -1/1 J - FRINGE No. 15x1k - SCAN NO. 1//1 VALUES 2 OF X(J,K,N) ARE PRINTED IN 2 BLOCKS FOR EACH FRAME 1// MAXIMUM N SUMBER OF FRINGES AND SCANS ALLOWED, PER FRAME IS 291) D6 49 N-1,2 WRITE(6, 191)N WRITE(6,43) 43 FGRNAT(18 3x1J13x1117x1217x1317x1417x1517x1617x1717x1817x1916x1101 16X 11 6X 12 6X 13 6X 14 6X 15 6X 16 1/1 K1) Dd 44 K-1,30 44 WRITE(6,45)K,(X(J,K,N),J=1,16) 45 FORMAT(1H 12,1X16F8.3) WRITE(6,46) 46 FGRMAT(//1H 3X1J12X11716X11816X11916X12016X12116X12216X12316X12416 1x12516x12616x12716x12816x1291/1 K1) DØ 47 K-1, 30 47 WRITE(6,45)K,(X(J,K,N),J=17,29) 49 CONTINUE REVERSE GRDER OF DATA IN EACH SCAN OF SECOND INTERFEROGRAM TO PERMIT LATER REGISTRATION OF DATA FROM TWO INTERFERGRAMS THIS CORRECTION ASSUMES A 90 DEGREE ROTATION CLOCKWISE BETWEEN FIRST C AND SECOND INTERFERUGRAM DATA IS SIMULTANEOUSLY SHIFTED TO ALLOW TWO COLUMNS OF ZEROES K-1 302 D6 303 J-1,NF2

```
303 DU(J)-X(J,K,2)
     D6 305 J-1,NF2
 305 X(J+2, K, 2) DU(NF2+1-J)
     IF(K.GE.NS) G6 T6 310
     K-K-1
     GO TO 302
     DATA FROM FIRST FRAME IS SHIFTED TO ALLOW FOR TWO COLUMNS OF ZERGES
 310 K-1
 301 D6 304 J-1,NP1
 304 DU(J)-X(J,K,1)
     D6 306 J-1, NF1
 306 X(J.2,K,1)-DU(J)
     IF(K.GE.NS) G6 T6 311
     K-K-1
     96 T6 301
 311 D6 312 K-1,NS
     D6 312 J-1,2
     X(J, K, 2)-0.
 312 X(J,K,1)-0.
C
      CONVERT FRINGE-PEAK POSITIONS TO NORMALIZED COORDINATES USING
      DELTA AND MOVE GRIGIN OF COORDINATE SYSTEM UNTIL AXES ARE TANGENT
      TO LENS APERTURE
      NF1 A-NF1 +2
      NF2A-NF2+2
      N-1
      D6 315 K-1,NS
      D6 315 J-1,NF1A
    IF(X(J,K,N).LT. 0.001) G6 T6 315
      X(J,K,N)-ABS((CX-X(J,K,N))/DELTA)
  315 CONTINUE
      N-2
      D6 320 K-1, NS
      D6 320 J-1, NF2A
      IF(X(J,K,N).LT. 0.001) GG TG 320
      X(J,K,N)-ABS((CY-X(J,K,N))/DELTA)
  320 CONTINUE
      WRITE(6,190)
  190 FORMAT(1H1, 'NORMALIZED PRINGE POSITIONS X(J,K,N) ARE PRINTED BELOW
     1 -1/1 J - FRINGE NO.
                                K . SCAN NO. 1// VALUES OF X(J,K,N) ARE
     2PRINTED IN 2 BLOCKS OF 32(ROWS) BY 16(COLUMNS) FOR EACH FRAME 1//1
     3NOTE - THE FIRST FRINGE WAS ASSIGNED J-3 AS INPUT DATA, THE SECOND
     4 FRINGE J-4, ETC. 1)
  406 Dd 199 N-1,2
      WRITE (6,191)N
  191 FORMAT(///1H 62X FRAME 12///)
      WRITE (6,192)
  192 FORMAT(1H 3X'J'3X'2'7X'3'7X'4'7X'5'7X'6'7X'7'7X'8'7X'9'6X'10'6X'11
     1 6x 12 6x 13 6x 14 6x 15 6x 16 6x 17 / KI)
      D6 193 K-1,32
  193 WRITE(6,194)K,(X(J,K,N),J-2,17)
  194 FORMAT(1H 12,1X16F8.3/)
      WRITE(6, 196)
  196 FORMAT(//1H 3x1J12x11816x11916x12016x12116x12216x12316x12416x12516
     1x12616x12716x12816x12916x13016x13116x13216x1331/1 K1)
      DG 197 K-1,32
```

```
197 WRITE(6,194)K,(X(J,K,N),J-18,33)
  199 CONTINUE
      INTERPOLATE FRINGE-GRDER VALUES AT GRID POINTS COMMON 13
C
C
      FRAME 1 AND FRAME 2
      POSX-POSX/DELTA
      POSY - POSY/DELTA
      U-POSY
      JHIN-0
      JMAX-0
      N-1
      NS-NSX
      WRITE(6, 349)
  349 FORMAT( 1H1 THE FOLLOWING GRID POINTS XINT, IF ANY, LIE INSIDE LENS
     1 APERTURE BUT GUTSIDE REGION OF INTERPOLATION 1///)
  350 D6 340 K-1,NS
      D6 323 J-3,31
      1F(JMIN.GT.0) G6 T6 321
      IF(X(J,K,N).LT.0.0001) G6 T6 323
      JMIN-J
  321 IF(X(J,K,N).LT.0.0001) GG TG 322
      GØ TØ 323
  322 JHAX -J-1
      OF TO 326
  323 CONTINUE
  326 N-JMAX-JMIN+1
      D6 329 J-JMIN, JMAX
      XDUM(J-JMIN+1)-X(J,K,N)
      JDUM(J-JMIN+1)-J
      IF(N .LE. 2) G6 T6 800
  329 CONTINUE
      USE SUBROUTINES TO INTERPOLATE FRINGE DEVIATION AT GRID POINTS BY
C
C
      SPLINE-FITTING TECHNIQUE
      REFERENCE - R.H. PENNINGTON, INTRODUCTORY COMPUTER METHODS AND
C
      NUMERICAL ANALYSIS, 2ND ED. (THE MACMILLAN COMPANY, U.S.A., 1970)
  330 CALL SPLICE(XDUN, JDUN, N,C)
      MM-XDUM(M)-1.00
      JM-XDUM( 1 )-1.00
      IP(JM.LT.1)JN-1
      DO 335 J.JM.NM
      XINT-U-J
      KDUM-K
       CALL SPLINE( %DUM, JDUM, M, C, XINT, YINT, 4335, N, KDUM)
      SUBTRACT INTEGER ORDER NUMBER MULTIPLIED BY RATIO OF SHEAR
       DISTANCE TO IDEAL FRINGE SPACING FROM INTERPOLATED VALUE TO GIVE
C
      DEVIATION OF FRINGE PROM IDEAL FRINGE
C
      P(J+2,K+2,N)-YINT-J+(DELTA/FRSPAC)
       IP(N .EQ. 1) MI1(J+2,K+2)-1
       IF(N .EQ. 2) MI2(K+2,J+2)-1
       ALL INTERPOLATED FRINGE-ORDER VALUES HAVE ALS BEEN SHIFTED TO
       ALLOW FOR TWO ROWS OF ZEROS
  335 CONTINUE
       JNIN-0
       JMAX-0
       G6 T6 340
       SPECIAL EXTRAPOLATION FOR SCAN WITH ONLY TWO FRINGE-PEAK LOCATIONS
   800 IF(K+4 .GT. NS) G6 T6 850
       XDUK(1)-2.0
```

```
XDUM(2)-3.0
   XDUM(3)-4.0
   XDUN(4)-5.0
   JDUM(1)-X(JMIN-1,K+1,N)
   JDUM(2)-X(JMIN-1,K+2,N)
   JDUM(3)-X(JMIN-1,K+3,N)
   JDUM(4)=X(JMIN-1,K+4,N)
   M-4
   XINT-1.0
   KDUM-K
   CALL SPLICG(XDUM, JDUM, M,C)
   CALL SPECSP(XDUM, JDUM, M, C, XINT, YINT, N, KDUM)
   YONE-YINT
   JDUM(1)=X(JMAX+1,K+1,N)
   JDUM(2)-X(JMAX+1,K+2,N)
   JDUM(3)=X(JMAX+1,K+3,N)
    JDUM( 4 ) - X( JMAX+1, K+4, N)
    CALL SPLICS(XDUN, JDUN, N,C)
    CALL SPECSP(XDUM, JDUM, M, C, XINT, YINT, N, KDUM)
    XDUM(1)-YONE
    XDUM(2)-X(JMIN,K,N)
   XDUM(3)-X(JMAX, K, N)
    XDUM(4)-YINT
    JDUM(1)-JMIN-1
 , JDUM(2)-JMIN
    JDUN(3)-JWAX
    JDUM(4)-JMAX+1
    G6 T6 330
850 XDUM(1)=1.0
    XDUM(2)-2.0
    XDUN(3)-3.0
    XDUN(4)-4.0
    JDUM(1) = X(JMIN-1, K-4, N)
    JDUM(2)-X(JMIN-1,K-3,N)
    JDUM(3)-X(JNIN-1,K-2,N)
    JDUM(4)-X(JMIN-1,K-1,N)
    M-4
    XINT-5.0
    KDUM-K
    CALL SPLICE(XDUN, JDUN, N,C)
    CALL SPECSP(XDUM, JDUM, M, C, XINT, YINT, N, KDUM)
    YONE-YINT
    JDUM(1)-X(JMAX+1,K-4,N)
    JDUN(2)-X(JMAX+1, K-3, N)
     JDUM(3)-X(JMAX+1,K-2,N)
    JDUM(4) = X(JMAX + 1, K-1, N)
    CALL SPLICO(XDUM, JDUM, M, C)
    CALL SPECSP(XDUM, JDUM, N. C. XINT, YINT, N. KDUM)
    XDUN( 1 )-YONE
    XDUM(2) X(JNIN, K, N)
     XDUM(3)=X(JMAX,K,N)
    XDUM(4)-YINT
     JDUM(1)-JMIN-1
     JDUM(2)-JMIN
     JDUM(3)-JMAX
     JDUN(4) JNAX+1
     G6 T6 330
340 CONTINUE
```

IF(N.EQ.2) GG TG 360
N-2
NS-NST
U-PGSX
VAR2-PGSY
GG TG 350
P(J.K.N) S ARE NOW INTERPOLATED TG SAME GRID

C RESET NS TO PREVIOUS VALUE 360 NS-NAXO(NSX,NSY)

300 WRITE(6,600)

600 PORMAT(1H1 VALUES OF MII(I,K) ARE PRINTED BELOW -1//1 MII = 1 IND 1 ICATES THAT A VALUE OF FRINGE ORDER P(J,K,N) WAS INTERPOLATED AT G 2RID POINT (1+2,K+2) IN X-SHEARED INTERPEROGRAM 1//1 NOTE - FOR CAS 3E OF TWO INPUT FRINGE PEAKS IN A SCAN, ONE VALUE OF P(J,K,N) IS IN 4 TERPOLATED AND TWO VALUES MAY BE EXTRAPOLATED 1///) WRITE(6,601)MII

601 FORMAT(1H0,3213) WRITE(6,602)

602 FORMAT(1H1 VALUES OF MI2(I,K) ARE PRINTED BELOW -1//1 MI2 - 1 IND 11CATES THAT A VALUE OF FRINGE ORDER P(J,K,N) WAS INTERPOLATED AT G 2RID POINT (K+2,I+2) IN Y-SHEARED INTERFEROGRAM 1//1 NOTE - FOR CAS 3E OF TWO INPUT FRINGE PEAKS IN A SCAN, ONE VALUE OF P(J,K,N) IS IN 4 TERPOLATED AND TWO VALUES MAY BE EXTRAPOLATED 1///) WRITE(6,601)MI2

C PRINGE-ORDER DEVIATIONS ARE DIVIDED BY 2 IF THE WSI SYSTEM IS
C DOUBLE PASS
500 IF(PASS.EQ.1) GO TO 550

D6 501 N=1,2 D6 501 K=1,31 D6 501 J=1,31 P(J,K,N)=P(J,K,N)/2.0

501 CONTINUE

550 WRITE(6,370)

370 FORMAT(1H1 'FRINGE-ORDER DEVIATIONS P(J,K,N) DETERMINED
1AT GRID POINTS BY INTERPOLATION FROM ADJACENT ORDER VALUES ARE PRI
2NTED BELOW'' J - COLUMN NO. OF GRID POINT K - ROW NO. OF GR
3ID POINT'/' VALUES OF P(J,K,N) ARE PRINTED IN 2 BLOCKS OF 32(ROWS
4) BY 16(COLUMNS) FOR EACH FRAME'/' NOTE - VALUES AT GRID POINTS F
50K WHICH J-1 (NOT PPINTED), J-2, AND AT GRID POINTS FOR WHICH K-1,
6 K-2, HAVE BEEN SET EQUAL TO 0.0')

D6 299 N-1,2 WRITE(6,191)N WRITE(6,192) D6 293 K-1,32

293 WRITE(6,194)K,(P(J,K,N),J-2,17) WRITE(6,196)

D6 295 K-1,32

295 WRITE(6, 194)K,(P(J,K,N),J=18,33)

299 CONTINUE

C CALL SUBROUTINE TO DETERMINE PHASE OF PUPIL FUNCTION

```
NSA-NS+2
      DEVMAX = 0
      DEVNIN-0
      CONVERT FOLLOWING PARAMETERS TO ACTUAL COORDINATE SYSTEM OF LENS
      APERTURE
      ICEN-RADIUS
      TCEN-RADIUS
      RADIUS-RADIUS/XMAG
      DELTA-DELTA/XMAG
      XCEN-XCEN/XMAG
      YCEN-YCEN/XMAG
      PGSX-PGSX+DELTA
      POSY -POSY - DELTA
      COMPUTE F/NUMBER OF TEST LENS
      PNG-0.5+Z2/RADIUS
      CALL DEV(MI, DE, NSA, MI1, MI2, DEVMAX, DEVMIN, RADIUS, DELTA, HD, VD, POSX,
     1 Pdsy, xcen, ycen, b, wavel, fdcus, thick, z2, sum, pass, cube, z2 best, fnd,
     2RMSMAX)
      DETERMINE PUPIL FUNCTION OR COMPLEX TRANSMITTANCE MATRIX
C
      D6 400 K-2, NSA
      D6 400 J-2, NSA
      IF(MI(J, K).EQ.C) TRANS(J, K)-(0.0,0.0)
      IF(MI(J, K). EQ. 0) GO TO 400
      IF(NI(J,K).EQ.2)NI(J,K)-1
      A-CGS(6.2831852+DE(J,K))+NI(J,K)
      D-SIN(6,2831852+DE(J,K))+NI(J,K)
      TRANS(J, K) - CMPLX(A,D)
  400 CONTINUE
      WRITE(6, 390)
  390 FORMAT(1H1 VALUES OF THE PUPIL FUNCTION TRANS(I,K) ARE PRINTED BEL
     10W - 1/// THE PUPIL FUNCTION IS A COMPLEX QUANTITY AND, THEREFORE
     2, EACH VALUE IS A PAIR OF NUMBERS'/ VALUES OF TRANS(I, K) ARE PRI
     3NTED IN 4 BLOCKS OF 32(ROWS) BY 8(COLUMNS)1///)
      WRITE(6, 391)
  391 FORMAT(1H 2X 1 1 8X 1 1 15X 12 1 15X 13 1 15X 14 1 15X 15 1 15X 16 1 15X 17 1 15X 18 1/1
     1 K1)
      Dd 700 K-1,32
  700 WRITE(6, 392)K,(TRANS(I,K), I-1,8)
  392 FORMAT(1H 12,1X16E8.3)
      WRITE(6, 393)
  393 PORMAT(1H12X 1 1 6X 19 115X 110 114X 111 114X 12 114X 13 114X 114 114X 15 114X 1
     1161/1 K1)
      D6 701 K-1,32
  701 WRITE(6, 392)K, (TRANS(I, K), I-9, 16)
      WRITE (6,394)
  394 FORMAT(//1H12X1117X117114X118114X119114X120114X121114X122114X12311
      14X1241/1 K1)
       D6 702 K-1,32
  702 WRITE (6,392)K, (TRANS(I,K), I-17,24)
      WRITE (6,395)
  395 FORMAT(//1H12X'I'7X'25'14X'26'14X'27'14X'28'14X'29'14X'30'14X'31'1
      14X 132 1/1 K1)
       D6 703 K-1,32
  703 WRITE(6, 392)K, (TRANS(I, K), I-25, 32)
       COMPUTE ACTUAL SPATIAL PREQUENCY INCREMENT (REDUCED INCREMENT IS
```

USED IN COMPUTATION OF OTF)

DELTXY-DELTA/(WAVEL-Z2)

IF(F6CUS .EQ. 1) G6 T6 705 IF PLANE OF BEST POCUS WAS DETERMINED, THEN DELTA, DELTXY, AND FNO C C MUST BE RECOMPUTED USING DISTANCE FROM EXIT PUPIL TO PLANE OF BEST **POCUS** C DELTA-(ZL-Z2BEST)+PHI DELTXY DELTA/(WAVEL+Z2BEST) PNGBST-0.5+Z2BEST/RADIUS PNG-FNGBST USE SUBROUTINE TO DETERMINE OPTICAL TRANSFER PUNCTION 705 CALL CORREL(MI, B, DELTA, OTF, DE, SUM) INDEX-1 WRITE(6,740) 740 FORMAT(1H1 VALUES OF THE OPTICAL TRANSFER PUNCTION, OTF, ARE PRINT 1ED BELOW - 1/// THE OTF IS A COMPLEX QUANTITY AND, THEREFORE, EAC 28 VALUE IS A PAIR OF NUMBERS 1/1 VALUES OF OTF(I,K) ARE PRINTED IN 3 8 BLCCKS OF 65(ROWS) BY 8(CCLUMNS)1///) 741 WRITE(6, 391) DØ 745 K-1,65 745 WRITE(6, 392)K,(6TF(1,K),1-1,8) WRITE(6, 393) D6 746 K-1,65 746 WRITE(6, 392)K, (GTP(I,K), I-9, 16) WRITE(6, 394) D6 747 K-1,65 747 WRITE(6, 392)K, (GTF(I,E), I-17,24) WRITE(6, 395) D6 748 K-1,65 748 WRITE(6, 392)K, (6TF(I,K), 1-25, 32) WRITE(6, 396) 396 FGRMAT(//1H12X1117X133114X134114X135114X136114X137114X138114X13911 14X 40 1/1 K1) D6 749 K-1,65 749 WRITE(6, 392)K, (GTF(I,K), I-33,40) WRITE(6,397) 397 FORMAT(//1H12X*I1*7X*41*14X*42*14X*43*14X*44**14X*45*14X*46*14X*47*1 14X 48 1/1 K1) D6 750 K-1,65 750 WRITE(6, 392)K, (6TF(I,K), I-41,48) WRITE(6, 398) 398 FGRMAT(//1H12X1117X149114X150114X151114X152114X153114X154114X15511 14X1561/1 K1) DØ 751 K-1,65 751 WRITE(6, 392)K,(GTF(I,K), I=49,56) WRITE(6, 399) 399 FORMAT(//1H12X'I'7X'57'14X'58'14X'59'14X'60'14X'61'14X'62'14X'63'1 14X 164 1/1 K1) D6 752 K-1,65 752 WRITE(6, 392)K, (OTF(1,K), 1.57,64) IP(INDEX .EQ. 2) G6 T6 765 DETERMINE MODULUS (MTF) AND PHASE (PTF) OF OPTICAL TRANSFER C

- C FUNCTION (STF)
- SAME VARIABLE, OTF, IS USED FOR COMPLEX NUMBER WHOSE REAL PART IS C
- C THE MTF AND TRE IMAGINARY PART IS THE PTF - THIS SAVES STORAGE D6 405 K-1,65

D6 405 J-1,65 DUNNY(1)-CABS(STF(J,K)) DUMMY(2)-0.0 DUM-REAL(GTF(J,K)) DUM-ABS(DUM) IF(DUM .LT. 10.E-6) GO TO 405 DUNNY(2)-ATAN2(AIMAG(GTF(J,K)), REAL(GTF(J,K))) 405 GTF(J,K) CMPLX(DUMMY(1),DUMMY(2)) INDEX-2 WRITE(6,760) 760 FORMAT(181 VALUES OF THE MODULUS (MTF) AND PRASE (PTF) OF THE OPTI ICAL TRANSFER FUNCTION ARE PRINTED BELOW -1/// THE MTF AND PTF' VA 2LUES ARE PRINTED AS A PAIR IN 8 BLOCKS OF 65(ROWS) BY 8(COLUMNS)4/ 3//) Q6 T6 741 765 CONTINUE SEARCH MI(I, K) VALUES TO DETERMINE PARAMETERS NS1 AND NS2 FOR C PLOTTING PROGRAM C NS1 -0 NS2-0 D6 435 K-1,32 D6 435 I-1,32 IP(NI(I,K) .EQ. 0) GG TG 435 IP(I .LE. NS1) G6 T6 430 NS1 - I 430 NS2 .K 435 CONTINUE WRITE INFORMATION GENERATED BY THIS PROGRAM ON TAPE FOR USE WITH PLOTTING PROGRAM WRITE TAPE 7. DEVMIN, DEVMAX, RADIUS, WAVEL, DELTA, DELTXY, DE, GTF, NS1, 1 NS2, FNO, RMSMAX ENDFILE 7 WRITE(6,440)DELTA, DELTXY, RADIUS, WAVEL, DEVMIN, DEVMAX, NS1, NS2, FN6,... 1 RUSHAX 440 FCRMAT(1H1 THE FCLLOWING PARAMETERS, IN ADDITION TO THE DE AND OTF 1 VALUES, ARE WRITTEN ON TAPE WHICH BECOMES INPUT TO THE PLOTTING 2PROGRAM'/ THIS LISTING SHOULD BE CHECKED BEFORE RUNNING PLOTTING 3 PREGRAM 1/// DELTA = 18.3,10x DELTXY = 18.3// RADIUS = 18.3,9

4X'WAVELENGTH - 'E9.4//' DEVMIN - 'F8.3,9X'DEVMAX - 'F8.3//' NS1 - 5'12,18X'NS2 - '12//' F/NUMBER - 'F8.3//' RMSMAX - LAMBDA/'F8.3)

STOP

```
1 PGSX, PGSY, XCEN, YCEN, B, WAVEL, PGCUS, THICK, Z2, SUM, PASS, CUBE, Z2 BEST,
  2 PNG, RMSMAX)
   DIMENSION B(23), B4 BEST(250), C(23,23), DE(32,32), DEL(32,32),
  1 DERNS(32,32), DUL(32), F(24), HD(32,32), NI(32,32), NII(32,32),
  2MI2(32,32); NAME1(23), NAME2(23), NAME3(23), NAME4(46), NAME5(46),
  3NAME6(46), POLYMX(23), Q(23), RMSDE(250), V(32, 32), VD(32, 32),
  4XGRID(33,33),X1(33),X2(33),YGRID(33,,ZZ2(250)
   INTEGER PASS, CUBE, FOCUS
   DATA NAME1/6HCGNSTA,6HX-TILT,6HY-TILT,6HFGCUS ,6HO DEG ,6H45 DEG,6
  1 HX-COMA, 6HY-COMA, 6HX-CLOV, 6HY-CLOV, 6HSPHFPI, 6HO DEG , 6H45 DEG, 6H
                 ,6HX-COMA,6HY-COMA,6HX-CLOV,6HY-CLOV,6H
    .6HSPHERI,6HSPHERI/
                       . 6H
                                 . 6H
   DATA NAME2/6HNT
                                          ,6HDEPECT,6HASTIG.,6H ASTIG,6
  1H(3RD),6H(3RD),6HER(3RD,6HER(3RD,6ECAL(3R,6HASTIG.,6H ASTIG,6H
       ,6H
                 ,6H(5TH),6H(5TH),6HER(5TH,6HER(5TH,6H
  3 .6HCAL(5T,6HCAL(7T/
   DATA NAME3/6H
                                          . 6H
                                                    .6H(3RD) ,6H.(3RD),6
                                 , 6H
                                       . 6HD )
                             ,6H)
  1 H
          . 6H
                    ,6H)
                                                ,6H(5TH),6H.(5TH),6H
                          , 6H
                                    , 6H)
                                             .6H)
                                                       .6H
                 ,6H
  2
              (HH6,
  3 ,6HH)
                                .6HX
                                                    , 6HY
   DATA NAME4/6 HCGNSTA, 6H
                                          , 6H
                                                             .6H 2
       • Y, 6H 2 5HX - Y, 6H 6H2 XY 6H 2 , 6HX(X • , 6H 6HY(X • , 6H 2 , 6HX(X - , 6H 2 , 6HY(3X , 6H 2 , 6H(X •
                                       ,6H2 XY ,6H 2 ,6HX(X +,6H
  1 HX • Y, 6H 2
  3,6H 4 ,6HX - Y,6H ,6H2 XY (,6H 4 ,6HX - 6,6H ,4H4 XY (,6H 2 ,6HX(X +,6H 2 ,6HX(X +,6H 5 ,6HX - 2,6H
       ,6H3X Y *,6H 5 ,6HX - 1,6H 4
                                            ,6H5X Y -,6H 2
  6 ,6H 2 ,6H(X + ,6H
                       . 6H
                                 , 6H
                                          ,6H
                                                    .6H
                                                             ,6H2
   DATA NAMES/6HNT
                              , 6H ·
           . 6H2
                    ,6H
                                       , 6H.
                                                 .6H 2
                                                          .6H Y )
                 .6H 2 ,6H 3Y ) ,6H 2
                                             .6H-Y),6H22 ,6HY)
  22
       ,6H Y )
                       6H 2 6HX • Y.6H 2 2 6H X Y ,6H 2
              ,6H
  3 .6H4
  4HX - Y,6H 2 2 ,6H Y ) ,6H 2 2 ,6H Y ) ,6H 3 2 ,6HX Y -,6H
  5 2 3,6H 2X Y ,6H 3 2 ,6H0X Y ,6H
                                           2 ,6H 10X Y,6H 2 3 ,6HY )
                        . 6H
  6,6H24,6HY)
                        . 6H
                                 .6H
                                          , 6H
                                                    ,6H
   DATA NAME6/6H
  1 H
                    .6H
                             , 6H
                                       , 6H
                                                 .6H
                                                                    ,6 H
           , 6H
                           .6H
                                    .6H
                 ,6H
                                              , 6H
                                                       , 6H
                                                                 , 6H
                             .6H )
                        ,6H2
                                                             .6H2
  3 ,6H
                                          , 6H
                    .6H
           . 6H
                                       , 6H
                                                 ,6H
                                                      4 ,6H 3XY
                                                                    ,6 H
  4H )
                 , 6H
                                                                 ,6 H
  5 5 .6H - Y
                          4,6H+ 5XY ,6H3
                                             5,6H . Y .6H
              .6H
  6 .6H
                        . 6H
    THE PUPIL-FUNCTION PHASE IS FIRST DETERMINED TO WITHIN A CONSTANT
     SELECT A GRID POINT (K1.K2) AT. OR NEAR, THE CENTER OF THE LENS
     APERTURE AND SET DEL - 0.0
     THEN SOLVE FOR DEL AT ADJACENT GRID POINTS FOR WHICH INTERPOLATED
     FRINGE DEVIATIONS ARE KNOWN
    K1 *( NSA+1 )/2
    K2-(NSA-1)/2
    ASSIGN 145 TO M
    DEL(K1, K2)-0.0
    MI(K1, K2)-1
    J-K1
    K-K2
142 J-J+1
    15 (K.GT. K2 )G6 T6 160
```

SUBROUTINE DEV(MI, DE, NSA, MI1, MI2, DEVMAX, DEVMIN, RADIUS, DELTA, HD, VD,

C

```
IF(K.LT.K2)G6 T6 165
161 IF(MI1(J,K).EQ.O) GG TG 143
    IF(MI(J-1, K). EQ. 0) GG TG 143
    DEL(J, K) - HD(J, K) + DEL(J-1, K)
    MI(J, K)-1
    GO TO 142
160 IF(M12(J,K).EQ.0)GG TG 161
    IF(MI1(J,K).EQ.0)G6 T6 162
    IF(MI(J-1, K). EQ. 0) G6 T6 162
    IF(MI(J, K-1).EQ.0) GG TG 161
    DEL(J, K) -. 5+ (DEL(J-1, K) + DEL(J, K-1) + HD(J, K) + VD(K, J))
    MI(J, K)-1
    GØ TØ 142
162 IF(MI(J, K-1).EQ.0) GG TG 142
    DEL(J,K)-DEL(J,K-1)+ VD(K,J)
    MI(J, K)-1
    GC TC 142
165 IF(MI2(J,K+1).EQ.0)GG TG 161
    IF(MI1(J,K).EQ.0)GO TO 166
    IP(MI(J-1,K).EQ.0) GO TO 166
    IF(MI(J, K+1).EQ.0) GG TG 161
    DEL(J, K) = .5 + (DEL(J-1, K) + DEL(J, K+1) + HD(J, K) - VD(K+1, J))
    MI(J,K)=1
    G6 T6 142
166 IF(NI(J, K+1).EQ.0) GG TG 142
    DEL(J,K)*DEL(J,K*1)*VD(K*1,J)
    MI(J, E)-1
    G6 T6 142
143 J-K1
144 J-J-1
    IF(K.GT. K2)G6 T6 170
    IF(K.LT. K2)G6 T6 175
167 IF(NI1(J+1, K). EQ. 0)GG TG M, (145, 147)
    IF(MI(J-1,K).EQ.O) GG TG M,(145,147)
    DEL(J, K) - DEL(J+1, K) - HD(J+1, K)
    MI(J, K)-1
    IF(NII(J,K) .EQ. 0) NI(J,K)-2
    G6 T6 144
170 IF(MI2(J,K).EQ.0)G6 T6 167
     IF(MI1(J+1,K).EQ.0)G6 T6 171
     IF(MI(J+1,K).EQ.0) GØ TØ 171
     IF(MI(J, E-1).EQ. 0) GO TO 167
    DEL(J, K)=(DEL(J+1, K)+DEL(J, K-1)+VD(K, J)-HD(J+1, K))/2
    MI(J, K)-1
    GG TG 144
171 IP(NI(J, K-1).EQ. 0) GO TO 144
     DEL(J,K)-DEL(J,K-1)+VD(K,J)
     MI(J,K)-1
    GØ TØ 144
175 IF(NI2(J.K-1).EO.0)G# T# 167
     IF(MI1(J.1, K). EQ. 0)G0 T0 176
     IP(NI(J+1,K).EQ.0) GG TG 176
     IF(MI(J, K-1). EQ. 0) GG TG 167
     DEL(J,K)=(DEL(J+1,K)+DEL(J,K+1)+HD(J+1,K)+VD(K+1,J))/2
     MI(J,K)-1
     GØ TØ 144
176 IF(NI(J, K+1).EQ.O) GO TO 144
     DEL(J,K)-DEL(J,K+1)-VD(K+1,J)
```

```
MI(J,K)-1
     G6 T6 144
 145 K-K-1
     J-K1
     IF(MI2(J,K) .EQ. 0) GG TG 146
     IF(NI(J; K-1).EQ.0) GG TG 146
     DEL(J,K)-DEL(J,K-1)+VD(K,J)
     MI(J, K)-1
     G6 T6 142
 146 E-K2
     ASSIGN 147 TO M
 147 J-K1
     IF(MI2(J,K) .EQ. 0) GG TG 150
     IF(MI(J, K). EQ. 0) GO TO 150
     DEL(J, K-1)*DEL(J, K)-VD(K, J)
     MI(J,K-1)-1
     IF(MI2(J,K) .EQ. 0) MI(J,K-1)=2
     K-K-1
     G6 T5 142
 150 CONTINUE
     WRITE(6, 499), K1, K2
 499 FORMAT(1H1 VALUES OF DEL(I,K) ARE PRINTED BELOW -1/// DEL(112,1,1
    112, 1) WAS SET EQUAL TO ZERO 1//1 THE EXPERIMENTAL CONSTANTS B1, B2(X
     2 TILT), AND B3(Y TILT) ARE UNKNOWN AT THIS POINT AND, THEREFORE, 1/1
     3 HAVE NOT BEEN REMOVED FROM THE COMPUTED DEL VALUES 1///)
     WRITE(6,66)
      D6 500 K-1,32
 500 WRITE(6,68)K,(DEL(J,K),J=2,17)
      WRITE(6,69)
      D6 501 K-1,32
  501 WRITE(6,68)K, (DEL(J,K), J-18,33)
      BOLVE FOR ABERRATION COEFFICIENTS IN ACTUAL LENS COORDINATES WHERE
C
      Y-O AND X-O AT LENS CENTER (XCEN, YCEN).
      THIS CHOICE OF COORDINATE-SYSTEM ORIGIN INSURES THAT THE PUPIL
C
      FUNCTION IS CENTERED AT LENS CENTER, THEREBY EQUAL TO ZERO AFTER,
C
      SUBTRACTING THE WAVEFRONT CONSTANT B(1).
       DO 40 MM-1,23
       D6 40 L-1,23
   40 C(NM, L)=0.0
      DO 20 K-2, NSA
      D6 20 1-2, NSA
      IF(MI(I,K).EQ.0) G6 T6 20
      Y-(K-2)+DELTA+POSX - YCEN
      X- (I-2)*DELTA * POSY - XCEN
      F(1)-1.0
      F(2) -X
      P(3)-Y
      P(4)*F(2)*F(2)*F(3)*F(3)
      F(5)=F(2)+F(2)-F(3)+F(3)
      F(6)=F(2)+F(3)+2
      F(7)=F(2)=F(4)
      F(8)*F(3)*F(4)
      F(9)=F(2)=(2+F(5)-F(4))
      F(10)=F(3)+(2+F(5)+F(4))
      F(11)=F(4)=F(4)
      F(12)*F(4)*F(5)
      F(13)-F(4)+F(6)
```

```
P(14)=F(5)+F(5)-F(6)+F(6)
     P(15)=2+F(6)+F(5)
     F(16)=F(2)+F(11)
     F(17)-F(3)+F(11)
     F(18)*F(4)*F(9)
     F(19)*F(4)*F(10)
     P(20)*F(2)*(F(11)-2*F(12)*2*F(14!)
     P(21)*F(3)*(F(11)*2*F(12)*2*F(14))
     P(22) -F(4) +F(11)
     F(23)-F(11)-F(11)
     DUL(I)-DEL(I,K)
     P(24) DUL(1)
        Dd 151 L-1,23
     Q(L)-Q(L)+F(L)+F(24)
      DO 151 NN-L, 23
      C(MM, L) = C(MM, L) + F(L) + F(MM)
 151 C(L,NM) = C(NM,L)
  20 CONTINUE
      CALL SUBROUTINE TO INVERT MATRIX C(L,M)
      CALL INVERT(C, 23)
      D6 60 I-1,23
      B( I )-0.
      D6 61 K-1,23
  61 B(I)=B(I)+C(I,K)+Q(K)
   60 CONTINUE
      IF( CUBE .EQ. 1 ) G6 T6 62
      DETERMINE VALUES OF ABERRATION COEFFICIENTS INTRODUCED BY CUBE
C
C
      THESE ABERRATIONS ARE SYMMETRICAL AND DO NOT INCLUDE THOSE
      INTRODUCED BY TILTING THE CUBE - ALSO, THESE ABERRATIONS ARE
C
      COMPUTED FOR THE INDEX OF REFRACTION OF THE CUBE EQUAL TO 1.46008
C
      FOR DOUBLE-PASS SYSTEMS, ONLY 1/2 OF CUBE ABEFRATIONS ARE
      COMPUTED BECAUSE THE EARLIER DIVISION OF FRINGE DEVIATIONS (WHICH
C
      INCLUDE CUBE ABERRATIONS) BY 2 HAS ELIMINATED THE OTHER HALF
      B4CUB-665.534+(THICK/WAVEL)+((1.0/Z2)++2)+0.5461E-3
      GØ TØ 395
   62 B4CUB - 0.0
  395 B11CUB - -425.550+(THICK/WAVEL)+((1.0/22)++4)+0.5461E-3
      E22CUB-252.000+(THICK/WAVEL)+((1.0/22)++6)+0.5461E-3
      B23CUB-94.600+(THICK/WAVEL)+((1.0/Z2)++8)+0.5461E-3
      BAMAX = B4 CUB + RADIUS + + 2
      B11MAY - B11CUB+RADIUS++4
      B22MAX * B22CUB*RADIUS**6
      B23MAX *B23CUB*RADIUS**8
      WRITE(6, 400) B4CUB, B4NAX, B11CUB, B11MAX, B22CUB, B22MAX, B23CUB, B23MAX
  400 FORMAT(1H1 THE COEFFICIENTS AND MAXIMUM VALUES OF THE ABERRATIONS
     1 INTRODUCED BY THE CUBE INTERFEROMETER ARE LISTED BELOW! ////14X COE
     2FFICIENT'8X'MAX. VALUE 12X'TYPE'//2X'B(4)'7XE11.6,7XF12.7,7X'DEFEC
     4T OF FOCUS 1//2X B( 11 ) 6 XE11.6, 7XF12.7, 7X 3RD FROER SPHERICAL 1//2X 1
     5B(22) 6XE11.6,7XF12.7,7X 5TH GRDER SPHERICAL //2X B(23) 6XE11.6,7X
     6F12.7, 7X '7TH ORDER SPHERICAL'///)
      WRITE(6, 401) FNG, THICK, WAVEL
  401 FORMAT(1H TEST-LENS F/NO. - F5.2,15X CUBE TRICKNESS - F7.3, MM
     1 15X TEST-LIGHT WAVELENGTH . 'E10.4, ' MM')
      WRITE(6, 402)
  402 FORMAT(///1H INGTE - ONLY ONE-HALF OF EACH OF THE ABOVE ABERRATIO
     INS IS REMOVED IF THE TEST SYSTEM IS DOUBLE PASS!)
```

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IF THE CHOSEN VALUE OF RADIUS IS SMALLER THAN THE PULL TEST
C
      APERTURE, THEN THE EFFECTIVE P/NG. IS INCREASED.
C
C
      THE MI(I,K) MATRIX IS CHANGED TO CORRESPOND TO THE SMALLER
      APERTURE BY CHOOSING A SMALLER RADIUS IN THE EXIT PUPIL PLANE
C
      WHERE CENTERING OF THE APERTURE IS AT (XCEN, YCEN).
C
C
      ABERRATION COEFFICIENTS DETERMINED FOR FULL APERTURE ARE USED FOR
      CONSTRUCTING THE WAVEFRONT FROM THE SMALLER APERTURE.
      D6 700 K-2, NSA
      D6 700 I =2, NSA
      IF(MI(I,K) .EQ. 0) G6 T6 700 -
      X- (I-2) DELTA . POSY - XCEN
      Y-(K-2)+DELTA + POSX - YCEN
      XX - X+X
      YY-Y+Y
      R - XX · YY
      RR-SQRT(R)
      IF(RR .GE. RADIUS) MI(I,K)-0
  700 CONTINUE
C
      CALCULATE PUPIL-FUNCTION PHASE (DE) USING ABERRATION COEFFICIENTS
      TT-0.0
      AY-0.0
      TT1 -0.0
      AV1 -0.0
      TT2-0.0
      AV2 -0.0
      SUMA-0.0
      D6 70 K-2, NSA
      DO 70 1-2, NSA
      DE( I, K )=0.0
      IF(MI(I,K).EQ.0) G6 T6 70
      X - (I-2) DELTA . POSY - XCEN
      Y-(K-2)+DELTA+PGSX - YCEN
      XX - X+X
      YY-Y+Y
      R - XX . YY
      DE(I,K)=B(4)+R+B(5)+(XX-YY)+B(6)+
     1 2*X*Y*B(7)*X*R*B(8)*Y*R*B(9)*X*(XX-3*YY)
     2 *B(10)*Y*(3*XX-YY)*B(11)*R*R*B(12)*(XX-YY)*R*B(13)*
     3 2+X+Y+R+B(14)+(XX+XX-6+XX+YY+YY)+B(15)+4+X+
      4 Y+(XX-YY)+B(16)+X+R+R+B(17)+Y+R+R
     5+B(18)*X*R*(XX-3*YY)*B(19)*Y*R*(3*XX-YY)
     6+B(20)*X+(XX+XX-10*XX+YY+5+YY+YY)+B(21)*Y+(5*XX*XX
      7-10+XX+YY+YY+YY)+B(22)+R+R+R+B(23)+R++4
       RENOVE SYMMETRICAL CUBE ABERRATIONS FROM DE AND DEL VALUES
C.
      DE(I,K)=DE(I,K)-(1./PASS)+(B4CUB+R+B11CUB+R+R+B22CUB+R+R+R+B23CUB+
      1 R++4)
       DEL(I, K) - DEL(I, K) - (1./PASS) + (B4CUB+R+B11CUB+R+R+B22CUB+R+R+B23CU
      1 8#R##4 )
       TT1 - TT1 - DE( I, K ) + DE( I, K )
       AV1 - AV1 - DE( I, K)
       REMOVE CONSTANT AND X AND Y TILTS FROM DEL VALUES
C
       DEL( I, K) *DEL( I, K) - B( 1 ) - B( 2 ) * X - B( 3 ) * Y
       AV2-AV2+DEL(I,K)
       TT2-TT2-DEL(I,K)+DEL(I,K)
       CALCULATE DIFFERENCE BETWEEN INPUT AND GUTPUT WAVEFRONTS
       V( I, K) - DEL( I, K) - DE( I, K)
       TT-TT-V( I, K )+V( I, K )
```

AV-AV-V(I,K) SUMA-SUMA-1. 70 OUNTINUE

WRITE(6,300)

300 FORMAT(1H1 RESIDUAL VALUES (V(I,K)), THAT IS, THE DIFFERENCES BETW 1EEN THE INPUT WAVEFRONT (DEL VALUES) AND GUTPUT WAVEFRONT (DE VALUES) 1/1 ARE PRINTED BELOW - 1/1 SYMMETRICAL ABERRATIONS INTRODUCED 3BY CUBE HAVE BEEN REMOVED 1//)

WRITE(6,66) DG 301 K-1,32

301 WRITE(6,68)K,(V(I,K),I=2,17)
WRITE(6,69)
D6 302 K=1,32

302 WRITE(6,68)K,(V(I,K),I=18,33)

RMSS=SQRT((TT2/SUMA)-(AV2+AV2)/(SUMA+SUMA))

RMSS=1.0/RMSS

WRITE(6,112)RMSS

112 FORMAT(///1H 'RMS OF INPUT WAVEFRONT (DEL VALUES) WITH B(1), B(2), 1B(3), AND CUBE ABERRATIONS, IF ANY, REMOVED = LAMBDA/ F8.5//)

RMS - SQRT((TT1/SUMA)-(AV1+AV1)/(SUMA+SUMA))
RMS - 1.0/RMS

WRITE(6, 114)RMS

114 FORMAT(1H 'RMS OF ANALYTIC WAVEFRONT (DE VALUES) WITH B(1),B(2),B(13), AND CUBE ABERRATIONS, IF ANY, REMOVED - LAMBDA/'F8.5//)
RMSR-SORT((TT/SUMA)-(AV+AV)/(SUMA+SUMA))
RMSR-1.0/RMSR
WRITE(6,113)RMSR,WAVEL

113 FORMAT(1H 'RMS OF RESIDUAL WAVEFRONT (DEL-DE) = LAMBDA/ F8.3///30 1X'WHERE LAMBDA = 'E9.4, 2X'MM')

C CALCULATE ABERRATION TERMS AT EDGE OF LENS APERTURE

C FIRST, REMOVE EFFECT OF CUBE FROM APPROPRIATE ABERRATIONS IF(CUBE .EQ. 1) GO TO 79
B(4)-B(4)-(1./PASS)+B4CUB

79 B(11)=B(11)-(1./PASS)*B11CUB B(22)=B(22)-(1./PASS)*B22CUB B(23)=B(23)-(1./PASS)*B23CUB

> R1 - RADIUS POLYMX(1)-B(1) POLYMX(2) B(2) R1 PGLYMX(3)=B(3)*R1 PGLYMX(4)=B(4)+R1++2 POLYMX(5)=B(5)+R1++2 POLYMX(6)*B(6)*R1**2 PGLYMX(7)=B(7)*R1**3 PdLYMX(8)=B(8)+R1++3 PGLYMX(9)=B(9)+R1++3 PGLYMX(10)=B(10)+R1++3 PCLYMX(11)=B(11)+R1++4 POLYMX(12)-H(12)+R1++4 PGLYNX(13)=B(13)=R1=4 POLYMX(14)=B(14)*R1**4 POLYMX(15)=B(15)+R1++4 POLYMX(16)*B(16)*R1**5

```
PGLYMX(17)-B(17)+R1++5
      PGLYMX(18)-B(18)+R1++5
     PGLYMX(19)-B(19)+R1++5
     POLYMX(20)=B(20)+R1++5
      PGLYMX(21)=B(21)*R1**5
      PGLYMX(22)-B(22)+R1++6
     PGLYMX(23)=B(23)#R1##8
      WRITE(6,80)
     D6 82 I-1,23
  80 FGRMAT(1H1 THE COEFFICIENTS B("I) FOR THE SET OF 23 POLYNOMIALS WHI
     1CB DESCRIBE LENS ABERRATIONS ARE LISTED BELOW-1//1 CUBE ABERRATION
     28, IF ANY, HAVE BEEN REMOVED FROM BOTH THE COEFFICIENTS AND THE MA
     3X VALUES 1///12X B(I) 7X MAX VALUE OF ABERRATION 14X ABERRATION 29
     4x'PGLYNGMIAL'/' I'19x'( B(I)+RADIUS++N N-1,...,8)'//)
     WRITE(6,83)I,B(I),POLYMX(I),NAME1(I),NAME2(I),NAME3(I),NAME4(I+I-1
     1 ), NAMES( I+I-1 ), NAME6( I+I-1 )
   83 FGRMAT(1H I2,2XE14.6,7XF9.4,26X3A6,20X3A6)
  82 WRITE(6,84)NAME4(2+1),NAME5(2+1),NAME6(2+1)
   84 FORMAT(1H 98X3A6)
      EXTRAPOLATE DE VALUES
      EFFECT OF CUBE HAS ALREADY BEEN REMOVED BY PREVIOUS ADJUSTMENT OF
C
      APPROPRIATE CUEFFICIENTS
      COORDINATES OF GRID POINTS ARE DETERMINED IN A COORDINATE SYSTEM
C
      WITH AMES TANGENT TO THE FULL CIRCULAR APERTURE
      YBOUNI -YCEN-RADIUS
      YBOUN2 - YCEN - RADIUS
      D6 420 K-2, NSA
       YGRID(K)-POSX+(K-2.0)+DELTA
      D6 420 I-2, NSA
      IF(YGRID(K) .LT. YBGUN1) GG TG 418
      IF(YGRID(E) .GT. YBGUN2) GG TG 418
      X1(K)=XCEN-SQRT(RADIUS**2 + 2.*YGRID(K)*YCEN -YCEN*2-YGRID(K)**2)
      X2(K) *XCEN * SQRT(RADIUS ** 2 . *YGRID(K) *YCEN -YCEN ** 2 - YGRID(K) ** 2)
      XGRID(I, K) POSY+(I-2) DELTA
      IF(XGRID(I,K) .LE. X1(K)) G6 T6 418
      IF(XGRID(I, K) .GE. X2(K)) G6 T6 418
      IF(NI(I,K) .EQ. 1 .GR. NI(I,K) .EQ. 2) GG TG 420
      Y-(K-2)+DELTA+P6SX - YCEN
      X- (1-2)+DELTA + POSY - XCEN
      YY-Y+Y
      XX -X+X
      R - XX · YY
      DE( I, K) = B( 4 ) + R + B( 5 ) + ( XX - YY ) + B( 6 ) +
     1 2*X*Y*B(7)*X*R*B(8)*Y*R*B(9)*X*(XX-3*YY)
     2 *B(10)*Y*(3*XX-YY)*B(11)*R*R*B(12)*(XX-YY)*R*B(13)*
     3 2*X*Y*R*B(14)*(XX*XX-6*XX*YY*YY*YY)*B(15)*4*X*
     4 Y+(XX-YY)+U(16)+X+R+R+B(17)+Y+R+R
     5+B(18)+X+R+(XX-3+YY)+B(19)+Y+R+(3+XX-YY)
     6+B( 20 )#X#( XX#XX-10#XX#YY+5#YY#YY )+B( 21 )#Y#( 5#XX#XX
     7-10+XX+YY+YY+YY)+B(22)+R+R+R+B(23)+R++4
      MI(1,K)-2
      GG TG 420
  418 DE(I,K)=0.0
      MI(I,K)=0.0
  419 IF(MI(I,K) .EQ. 0) XGRID(I,K)=0.0
  420 CONTINUE
  360 WRITE(6, 396)
```

C

```
396 PORMAT(1H1, COORDINATE VALUES DEFINING LENS APERTURE ARE PRINTED B
    1 PLOW - 1/1 X1 AND X2 ARE APERTURE BOUNDARIES FOR A PARTICULAR Y OR
    2 SCAN VALUE 1///)
     D6 398 K-1,NSA
 398 WRITE(6, 395)K, YGRID(K), X1(K), X2(K)
 399 FORMAT(180 SCAN 12,7X 'Y - 1F8.3,7X 1X1 - 1F8.3,7X 1X2 - 1F8.3)
     SUMA-0.0
     SUMB-0.0
     D6 25 E-1,32
     D6 25 J-1,32
     IF(MI(J. K) .EO. 0) G6 T6 25
     IF(MI(J, K) .EQ. 1) GO TO 18
     SUMB-SUNB-1.0
     Q6 T6 25
  18 SUMA-SUMA-1.0
  25 CONTINUE
     SUM-SUMA+SUMB
     ISUM-SUM
     I SUMA - SUMA
     ISUMB-SUMB
     WRITE(6, 890)
 690 FORMAT(1H1 VALUES OF MI(I, K) ARE PRINTED BELOW -1//1 MI - 1 INDIC
    1ATES THAT A VALUE OF FRINGE ORDER P(J.K.N) WAS INTERPOLATED AT GRI
 , 2D POINT(I,K)
                                       . 11
                    1/1 MI = 2179H
                                                11
                   II PETRAPOLATED II II
                                               11//)
    311
     WRITE(6,891)MI
 891 PORMAT(1H0,3213)
     WRITE(6,50)ISUN, ISUNA, ISUNB
  50 FORMAT(// TOTAL NUMBER OF GRID POINTS IN THE CLEAR LENS APERTURE
    118 '15, ' OF WHICH'//10X15, WERE INTERPOLATED AND '15, WERE
    2EXTRAPGLATED 1)
     WRITE(6,211)
 211 FORMAT(1H1 VALUES OF THE PUPYL-FUNCTION PHASE ARE PRINTED BELOW -
    1/1 TERMS INVOLVING B(1), B(2), AND B(3) HAVE BEEN SUBTRACTED FROM
    2DE VALUES'/' DE . 0.0 AT THE CENTER OF THE LENS APERTURE'/' THES
    3E VALUES OF DE DO NOT, GENERALLY, REPRESENT THE PUPIL FUNCTION IN
    4THE PLANE OF BEST FOCUS 1///)
     WRITE(6,66)
  66 FGRMAT(1H 2X114X1217X1317X1417X1517X1617X1717X1817X1916X11016X111
    1 6x 12 6x 13 6x 14 6x 15 6x 16 6x 17 / K1)
     D6 761 K-1,32
 761 WRITE(6,68)K,(DE(1,K),1-2,17)
 '68 FORMAT(1H 12,1X16F8.3/)
     WRITE(6,69)
  69 FORMAT(//1H 2X1J13X11816X11916X12016X12116X12216X12316X12416X12516
    1X12616X12716X12816X12916X13016X13116X13216X1331/1 K1)
     DØ 762 K-1,32
 762 WRITE(6,68)K,(DE(I,K), I-18,33)
      IF( P6CUS .EQ. 1 ) G6 T6 430
C
      CALCULATE PUPIL-FUNCTION PHASE FOR PLANE OF BEST FOCUS
      FIRST, CALCULATE RMS OF DE VALUES, INCLUDING EXTRAPOLATED VALUES,
C
      FOR PREVIOUS VALUE OF B(4)
      AV3-0.0
      TT3-0.0
```

D6 250 K .2,32

```
DØ 250 1-2,32
      DERMS(I, K) DE(I, K)
      IF(MI(I, K) .EQ. 0) G6 T6 250
      AV3 - AV3 - DE(I,K)
      773-773-DE( I, K)+DE( I, K)
  250 CONTINUE
      RNSDE(1) * SQRT((TT3/SUN) - (AV3+AV3)/(SUN+SUN))
      RMSDE(1)-1.0/RMSDE(1)
      THE FOCAL POSITION ALONG THE OPTICAL AXIS WILL BE CHANGED IN
C
      INCREMENTS OF THE RAYLEIGH TOLERANCE ON DEFOCUSSING AND THE
C
      RESULTING CHANGE IN B(4) WILL BE CALCULATED
      RAYLGH-3.2*(WAVEL/6.283185)*(Z2/RADIUS)**2
      FRACT-0.0
  299 D6 298 K-2,32
      D6 298 1-2,32
  298 DE(I,K)-DERMS(I,K)
      WRITE(6, 254 )RAYLGH
  254 FORMAT(1H1 RAYLEIGH TOLERANCE ON DEPTH OF FOCUS FOR TEST LENS IS .
     1 GR - 'E9.3, ' MM'///)
      WRITE(6, 255)
  255 FORMAT(1H COEFFICIENT FOR DEPECT OF FOCUS, CORRESPONDING DISTANCE
     1 TO FOCAL PLANE, AND RMS OF RESULTING WAVEFRONT ARE LISTED BELOW -
     21///5x INDEX PARAMETER, MILLX B(4) 13X 22(MM) 11X RMS(LAMBDA/VALUE
     3)1/./)
      M- 1
      WRITE(6, 256 )M, B(4), Z2, RMSDE(1)
  256 FGRMAT(1H 12XI3,16XE11.6,7XF8.3,12XF10.5/)
      B4BEST(1)*B(4)
      SIGN-1.0
      FRACT-FRACT . 0.10
      ZZ2(1)*Z2
  257 Dd 270 Nº2,250
      ZZ2(M) -ZZ2(M-1)-(SIGN+FRACT+RAYLGH)
      B4BEST(M)=B4BEST(M-1)+(SIGN+FRACT+RAYLGH)/(2.0+ZZ2(M)+WAVEL+
     2(ZZ2(M)+SIGN+FRACT+RAYLGH))
      AV4 - 0. 0
      TT4-0.0
      D6 260 K-2,32
      DØ 260 I-2,32
      IF(MI(1, K) .EQ. 0) G6 T6 260
      X . (1-2) DELTA . POSY - XCEN
      Y=(K-2)+DELTA+PGSX - YCEN
      YY-Y+Y
      XX - X+X
      R . YY .XX
      DE(I,K)-DE(I,K)+(B4BEST(M)-B4BEST(M-1))+R
       AV4 = AV4 + DE(I,K)
       TT4-TT4-DE( I, K)+DE( I, K)
  260 CONTINUE
      RMSDE(M) - SORT((TT4/SUN)-(AV4+AV4)/(SUM+SUM))
       RMSDE(M)-1.0/RMSDE(M)
      WRITE(6, 256)M, B4BEST(M), ZZ2(M), RMSDE(M)
       IF(M .NE. 125) GO TO 270
  258 SIGN -- 1.0
      B4BEST(125)-B4BEST(1)
      ZZ2(125)-ZZ2(1)
      D6 259 K-2,32
```

D6 259 1-2,32

```
259 DE(I.K)-DERMS(I.K)
    WRITE(6, 263)
263 PORMAT(/IH 'FOCUS SHIFT IS SUBSEQUENTLY MADE TO OPPOSITE SIDE OF T
  1EST FOCUS POSITION 1/)
270 CONTINUE
    MMAX-1
    RMSMAX - RMSDE(1)
    D6 265 Nº2, 250
    RMSMAX -AMAX1 (RMSMAX, RMSDE(M))
    IRMSMX * RMSMAX # 1.0E6
    IRMSDE-RNSDE(M)+1.0E6
    IF(IPMSDE .GE. IRMSMX) MMAX .M
265 CONTINUE
    WRITE( 6, 266 ) RMSMAX, MMAX, FRACT
266 FORMAT(///IH THE MINIMUM RMS FROM THE VALUES LISTED ABOVE IS LAMB
   1DA/ F8.3. FOR M - 13///18 THE FOCAL POSITION, Z2, ALONG THE OP
   2TICAL AXIS WAS CHANGED IN INCREMENTS OF 1F5.2, OF THE RAYLEIGH TO
   3LERANCE ON DEPTH OF FOCUS 1/1H !HOWEVER, IF M = 125 OR 250, THE INC
   AREMENT WILL BE DOUBLED AND THE SEARCH FOR MAXIMUM LAMBDA/RMS REPEA
   STED!)
    IF(NMAX.EQ.125 . GR. NMAX.EQ.250) GG TG 299
    AV4 - 0. 0
    TT4-0.0
    DØ 269 K-2,32
    D6 269 1-2,32
    IF(NI(I,K) .EQ. 0) GG TG 269
    X • (I-2) * DELTA • POSY - XCEN
    Y.(K-2)+PELTA.POSX - YCEN
    YY-Y+Y
    XX . X+X
    R - YY - XX
    DE(I,K) = DERMS(I,K) + (B4BEST(MMAX) - B4BEST(1)) +R
     AV4 - AV4 + DE( I, K)
     TT4-TT4-DE( I, K)+DE( I, K)
269 CONTINUE
     RMSMAX - SQRT((TT4/SUM)-(AV4+AV4)/(SUM+SUM))
     RMSMAX-1.0/RMSMAX
    DEFFOC*B4BEST( NMAX )*RADIUS**2
    WRITE(6,440)RNSMAX, DEFFEC
440 FORMAT(1H1 VALUES OF THE PUPIL-FUNCTION PHASE FOR PLANE OF BEST FO
   1CUS ARE PRINTED BELOW - 1/1 TERMS INVOLVING B(2) AND B(3) AND CUBE
   2ABERRATIONS, IF ANY, HAVE BEEN SUBTRACTED FROM DE VALUES ANDI/ DE
   3-0 AT THE CENTER OF THE LENS APERTURE 1// THE RMS OF THIS WAVEFPON
   4T IS LAMBDA/ F8.3, WITH A REMAINING MAXIMUM F6CUS DEFECT OF F9.3
    5//)
     WRITE( 6, 66 )
     D6 441 K-1,32
 441 WRITE(6,68)K,(DE(I,K),I=2,17)
     WRITE(6,69)
     D6 442 K-1,32
 442 WRITE(6,68)K,(DE(I,K), I=18,33)
     SET DEFECT OF FOCUS COEFFICIENT EQUAL TO VALUE OBTAINED FOR
     WAVEFRONT WITH MINIMUM RMS SO THAT OTF WILL BE CALCULATED IN PLANE
     OF REST FOCUS
     B(4) B4BEST(NMAX)
     SET FOCAL DISTANCE EQUAL TO DISTANCE TO PLANE OF BEST FOCUS
```

Z2BEST-ZZ2(MMAX)

```
430 WRITE(6,421)
 421 FORNAT(1H1 COORDINATES OF THE GRID POINTS AT WHICH DE(I,K) WAS DET
    PERMINED ARE PRINTED BELOW - 1/// NOTE - COORDINATE VALUES OF 0.0 I
    2NDICATE THAT THE GRID POINT WAS OUTSIDE THE LENS APERTURE 1///)
     WRITE(6, 422)
 422 FGRMAT(63X'X-VALUE'/13X'1'5X'2'6X'3'6X'4'6X'5'6X'6'6X'7'6X'8'6X'9'
    15X 110 5X 111 5X 112 5X 113 5X 114 5X 115 5X 116 5X 117 1/2X K 12X 1 - VALUE 1)
     D6 423 K-2,17
 423 WRITE(6,424)K, YGRID(K) .(XGRID(I,K),1-2,17)
 424 FGRNAT(1XI2, F8.2, 4X16F7.2/)
     DG 425 K-18,33
 425 WRITE(6, 424)K, YGRID(K), (XGRID(I,K), 1-2,17)
      WRITE(6,426)
 426 FGRMAT(//63X'X-VALUE'/13X'I'5X'18'5X'19'5X'20'5X'21'5X'22'5X'23'5X
     1 124 15x 125 15x 126 15x 127 15x 128 15x 129 15x 130 15x 131 15x 132 15x 1331
     2X'K'2X'Y-VALUE')
     D6 427 K-2,17
 427 WRITE(6,424)K, YGRID(K), (XGRID(I,K), I-18,33)
      DO 428 K-18,33
  428 WRITE(6, 424)K, YGRID(K), (XGRID(I,K), I=18,33)
      DETERMINE MAXIMUM AND MINIMUM VALUES OF DE TO BE USED IN
C
      SUBSEQUENT PLOTTING PROGRAMS
C
      DO 450 I-2, NSA
      D6 450 J-2, NSA
      DEVNAX -AMAX1 (DEVNAX, DE(I,J))
  450 DEVMIN-AMIN1(DEVMIN, DE(I,J))
  560 RETURN
      END
```

```
SUBROUTINE CORRELL MI, B, DELTA, STF, DE, SUM)
      THIS SUBROUTINE CALCULATES THE OTF BY PERFORMING THE
C
      AUTOCORRELATION OF THE PUPIL PUNCTION
      DIMENSION B(23), DE(32,32), MI(32,32)
      COMPLEX V, OTF(65,65)
      REAL KY, KY, KXY
      SUM6=B(17) + 3.*B(19) + 5.*B(21)
      SUN7-B(16) - 3.+B(18) + 5.+B(20)
      SUM8-B(16) - B(18) - 5.#B(20)
      SUN9-B(17) + B(19) - 5.+B(21)
      DIP4+B(13) - 2-+B(15)
      DIF5-B(11) - 3.4B(14)
      DO 10 L-1,65
      EX-DELTA+(L-33)
      A2-KX++2
      43-42+KY
      44"A3+KX
     A5-A4+KX
     A6"A5+KX
     A7=A6+KX
     A8-A7+KX
     TERM1 = B( 22 ) +6. +KX
     TERM3=B( 23 )+8. +KX
     D6 10 M-1,33
     EY *DELTA*( M-33)
     B2=KY++2
     B3 - B2 + KY
     B4 * B3 * KY
     B5-B4+KY
     B6 * B5 * KY
     B7 * B6 * KY
     B8 - B7 + KY
     KXY - KX + KY
    B2X - B2 + KX
    B3X - B3 + KX
    B4X = B4 + KX
    B2Y - B2 + KY
    B3Y - B3 + KY
    B4Y = B4 + KY
    A2 B2 * A2 # B2
    A3B2 = A3# B2
    A4 B2 = A4 # B2
    A2B3 -A2+B3
    A284 - A2 # B4
    DIF1 "A2-B2
    SUM1 =A2+B2
    454 - 45 + KA
    A3Y"A3+KY
    A4Y = A4 * KY
   DIF2-B2-A2
   SUM2 -5. + A2 + B2
   SUN3-A2 + 5. +B2
   SUN4 - A3 + 3. + B2X
```

SUN5-3. * A2Y * B3 DIF3-A3 - 3. * B2X

```
TERM5-24.+B(22)+KXY
C2 = 2.4KX*(B(4) + B(5)) + B(6)*2.*KY + 2.4KXY*(B(8) + 3.*B(10))
   * B{7}*(3.*A2 * B2 ) * B(9)*3.*DIF1 * B(11)*4.*(A3 * B2X)
   * B(12)*4.*A3 * B(13)*2.*SUN5
                                          * B(14)*4.*DIF3
   * B(15)*(12.*A2Y - 4.*B3) * B(16)*(5.*A4 * 6.*A2B2 * B4)
   * B(17)*4.*(A3Y * B3X) * B(18)*(5.*A4 - 6.*A2B2 - 3.*B4)
   * B(19)*(12.*A3Y * 4.*B3X) * B(20)*5.*(A4 - 6.*A2B2 * B4)
   + B(21)+20.+(A3Y - B3X) + B(22)+6.+(A5 + 2.+A3B2 + B4X)
   * B(23)*8.*(A7 * 3.*A5*B2 * 3.*A3*B4 * KX*B6)
C3 * B(6)*2.*KX * 2.*KY*(B(4) - B(5)) * 2.*KXY*(B(7) - 3.*B(9))
   * B(8)*(A2 * 3.*B2) * B(10)*3.*DIF1 * B(11)*4.*(A2Y * B3)
   - B(12)+4.+B3 + B(13)+2.+SUM4
                                          * B(14)#4.#(B3 - 3.#A2Y)
   • B(15)+4.+DIF3
                            * B(16)*4.*(B3X * A3Y)
   * B(17)*(A4 * 6.*A2B2 * 5.*B4) - B(18)*4.*(3.*B3X * A3Y)
   + B(19)+(3.*A4 + 6.*A2B2 - 5.*B4) + B(20)+20.*(B3X - A3Y)
   * B(21)*5.*(A4 - 6.*A2B2 * B4) * B(22)*6.*(A4*KY * 2.*A2B3 *B5)
   * B(23)*8.*(A6*KY * 3.*A4*B3 * 3.*A2*B5 * B7)
C4 = 2.*KX*(B(8) * 3.*B(10)) * 2.*KY*(B(7) - 3.*B(9))
   . 8. KXY+DIF5
                                * B(13)*6.*SUM1 * B(15)*12.*DIF1
   + B(16)+4.+SUN5
                             * B(17)+4. *SUM4
   - B(18)+12.+(A2Y + B3) + B(19)+12.+(A3 + B2X)
   • B(20)*20.*(B3 - 3.*A2Y) • B(2.)*20.*DIF3
   * B(22)*24.*(A3Y * B3X) * B(23)*48.*(A5*KY * 2.*A3*B3 * KX*B5)
C5 - 3.*KX+(B(7) + B(9)) + KY+(B(8) + 3.*B(10))
    + 6.*EXY*(B(13) + 2.*B(15)) + B(11)+2.*(3.*A2 + B2)
   * B(12)*6.*A2 * B(14)*6.*DIF1 * B(16)*(6.*B2X * 10.*B3)
    * B(17)*2.*SUN5
                            + B(18)*(10.*A3 - 6.*B2X)
   * B(19)*2.*(9.*A2Y * B3) * B(20)*10.*(A3 - 3.*KXY)
   + B(21)*10.*(3.*A2Y - B3) + B(22)*3.*(5.*A4 + 6.*A2B2 + B4)
   + B(23)+4.+(7.+A6 + 15.+A4B2 + 9.+A2B4 + B6)
C6 = KX*(B(7) - 3.*B(9)) * 3.*KY*(B(8; - B(10))
   * 6.*KXY+DIF4
                                * B(11)*2.*(A2 * 3.*B2)
   - B(12)+6.+B2 + B(14)+6.+DIF2 + B(16)+2.+SUM4
2
    * B(17)*(6.*A2Y * 10.*B3) - B(18)*2.*(9.*B2X * A3)
   + B(19)+(6.*A2Y - 10.*B3) + B(20)+10.*(3.*KXY - A3)
    * B(21)+10.+(B3 - 3.+A2Y) * B(22)+3.+(A4 * 6.+A2B2 * 5.+B4)
    * B(23)*4.*(A6 * 9.*A4B2 * 15.*A2B4 * 7.*B6)
 C7 = 4.*KX*(B(11) * B(12) * B(14)) * 2.*KY*(B(13) * 2.*B(15))
    . 4. * KXY + SUM6
                                           . B(16)+2.+SUM2
    * B(18)+2.+(5.+A2 - B2) * B(20)+10.+DIF1
    + B(22)*(20.*A3 + 12.*B2X) + B(23)*(56.*A5 + 80.*A3B2 +24.*B4X)
C8 - 2.+KX+DIF4
                               + 4. *KY*(B(11) - B(12) + B(14))
    * 4.* KXY + SUM7
                                           . B(17)+2. +SUM3
1
    * B(19)*2.*(A2 - 5.*B2) * B(21)*10.*DIF2
    + B(22)+(12.+A2Y + 20.+B3) + B(23)+(24.+A4Y + 80.+A2B3 +56.+B5)
 C9 = 6.*KX*(B(13) * 2.*B(15)) * 4.*KY*DIF5
```

TERM2-B(22)+6.+KY TERM4-B(23)+8.+KY

* B(19)*3.*(6.*A2 * B2) * B(21)*30.*DIF1

. B(17)+6.+SUM1

. 12.*KXY*SUN8

```
* B(22)*12.*(3.*A2Y * B3) * B(23)*24.*(5.*A4Y * 6.*A2B3 * B5)
  3
                                   . 6.*KY*(B(13) - 2.*B(15))
   C10 - 4. *EX*DIF5
       + 12. * KXY + SUN9
                                             . B(16)+6.+SUN1
  1
       - B(18)+6.+(A2 + 3.+B2) + B(20)+30.+DIF2
       * B(22)+12.+(A3 * 3.+B2X) * B(23)+24.+(A5 * 6.+A3B2 * 5.+B4X)
   C11 . 6. *( EX+SUN8 . EY+SUN9 ) . B(22)*18. *SUN1
       * B(23)*(60.*A4 * 216.*A2B2 * 60.*B4)
   C12 - 5. *KX*(B(16) * B(18) * B(20)) * KY*SUN6 * B(22)*3. *SUN2
       * B(23)*(70.*A4 * 60.*A2B2 * 6.*B4)
   C13 - KX+SUN7 + 5.*KY+(B(17) - B(19) + B(21)) + B(22)+3.*SUN3
       * B(23)*(6.*A4 * 60.*A2B2 * 70.*B4)
   C14 - 4.*(KX+SUN6 + KY+SUN8) + B(23)*(96.*B3X + 160.*A3Y) + TERM5
   C15 - 4.*( EX*SUN9 * EY*SUN7 ) * B(23)*(160.*B3X * 96.*A3Y) * TERMS
   C16 - TERM1 . B(23)*(56.*A3 . 24.*B2X)
   C17 * TERM2 * B(23)*(24.*A2Y * 56.*B3)
   C18 - 2. *TERM1 + B(23)*(80. *A3 + 144. *B2X)
   C19 - 2.*TERN2 + B(23)*(144.*A2Y + 80.*B3)
   C20 - TERM2 . B(23)+24.+(5.+A2Y . B3)
   C21 * TERM1 * B(23)+24.*(A3 * 5.*B2X)
    C22 - B(23)+4.+(7.+A2 + B2)
   C23 - B(23)+4.+(A2 + 7.+B2)
   C24 - B(23)+48.+EXY
    C25 - C24
    C26 * B(23)*(60.*A2 * 36.*B2)
    C27 - B(23)+(36.+A2 + 60.+B2)
    C2B - TERM3
    C29 - TERMA
    C30 . C29
    C31 - C28
    C32 . 3. +C28
    C33 * 3.*C29
    C34 - C33
    C35 - C32
100 CONTINUE
    D6 10 J-1,32
    X-DELTA+(J-13)
    X2-X+X
    X3-X2+X
    X4-X3-X
    X5-X4+X
    X6-X5+X
    X7-X6+X
    DO 10 K-1,32
    IF(MI(J, K) .EQ. 0) GO TO 10
    IN-J+L-33
    IF(IN.GT.32 .dR. IN.LT.1) Gd Td 10
    IM-K-M-33
    IF(IM.GT.32 .dR. IM.LT.1) Gd T6 10
    IF(MI(IN, IN) .EQ. 0) GO TO 10
    Y-DELTA+(K-13)
    72-Y-Y
```

73-Y2+Y

```
T4-T3-Y
  Y5-Y4+Y
  76-Y5-Y
  Y7-Y6+Y
  XY-X-Y
  XX2-X-XS
  XY2-X-Y2
  X2Y2-X2+Y2
  TX3-T+X3
  XY3-X+Y3
  X3Y2-X3+Y2
  X2Y3-X2+Y3
  XY4-X+Y4
  X4Y-X4+Y
  X2Y4 - X2 + Y4
  X4Y2-X4+Y2
  X3Y3*X3*Y3
  XY5-X+Y5
  X5Y-X5+Y
  X275-X2+Y5
  X5Y2 • X5 * Y2
  XY6 - X + Y6
  X6Y-X6+Y
  VV - 6.283185+(DE(IN,IN) - DE(J,K))
  A+C6S( YY )
  D-SIN(VV)
  V-CMPLX(A,D)
  V1 = 6.283185+(C2 * C4*Y * C10*Y2 *C15*Y3 *C21*Y4 * C25*Y5 *C31*Y6
     * 2.*(C5*X * C9*XY * C11*XY2 * C19*XY3 * C27*XY4 * C33*XY5)
     * 3.*(C7*X2 * C14*YX2 * C18*X2Y2 * C35*X2Y4)
     . 4.*(C12*X3 . C20*XX3 . C26*X3X5 . C34*X3X3)
     * 5.*(C16*X4 * C24*X4Y * C32*X4Y2)
     . 6.*(C22*X5 . C30*X5Y) . 7.*C28*X6)
  D1 - V1 - DELTA/2.0
  DI ABS-ARS( DI )
  IF(DIABS .LE. .001) GO TO 6
  IF(DIABS .GE. 1.0E+3) G6 T6 10
  SINC1-SIN(D1)/D1
  GO TO 7
6 SINC1-1.00
  GO TO 7
7 V2 = 6.283185*(C3 * C4*X * C9*X2 *C14*X3 *C20*X4 *C24*X5 * C30*X6
     + 2.*(C6*Y + C10*XY + C11*YX2 + C18*YX3 + C26*X4Y + C32*X5Y)
     * 3.*(C8*Y2 * C15*XY2 * C19*X2Y2 * C34*X4Y2)
      * 4.*(C13*Y3 * C21*XY3 * C27*X2Y3 * C35*X3Y3)
     • 5.*(C17*Y4 • C25*XY4 • C33*X2Y4)
      . 6.*(C23*Y5 . C31*XY5) . 7.*C29*Y6)
  D2-V2-DELTA/2.0
  D2ABS-ABS(D2)
   IF( D2ABS . LE. . 001 ) G6 T6 8
   IF(D2ABS .GE. 1.0E+3) G6 T6 10
   SINC2-SIN( D2 )/D2
   G6 T6 9
 8 SINC2-1.00
  GO TO 9
9 GTF(L, M) -GTF(L, M) . V+SINC1+SINC2
10 CONTINUE
```

C USE SYMMETRY OF MTF ABOUT L=33, M=33 TO DETERMINE OTHER HALF OF OTF VALUES

DC 60 J=1,33

DC 60 I=1,65

F=REAL(GTF(65-I+1,33-J+1))

G=-AIMAG(GTF(65-I+1,33-J+1))

60 GTF(I,33-J-1)=CMPLX(P,G)

DC 40 M=1,65

DC 40 L=1,65

40 GTF(L,M)=GTF(L,M)/SUM

RETURN

END

```
SUBROUTINE INVERT (A,N)
      MATRIX INVERSION BY GAUSS-JORDAN ELIMINATION
C
      DIMENSION A(23,23), B(23), C(23), LZ(23)
      D6 10 J - 1,N
   10 LZ(J) - J
      DØ 20 I - 1,N
      K - I
      Y - A(I, I)
                               .
      LP - I - 1
      IF (N - LP) 14,11,11
   11 D6 13 J - LP,N
      W = A(I,J)
      IF (ABS(W) - ABS(Y)) 13,13,12
   12 K - J
      Y - W
   13 CONTINUE
   14 D6 15 J - 1,N
      C(J) = A(J,K)
      A(J,K) = A(J,I)
      A(J, I) = -C(J) / Y
      A(I,J) - A(I,J) / Y
   15 B(J) - A(I,J)
      A(I,I) - 1.0 / Y
      J . LZ(1)
      LZ(I) . LZ(K)
      LZ(E) - J
      D6 19 E - 1,N
      IF (I - E) 16,19,16
   16 De 18 J - 1,N
      IF (I - J) 17,18,17
   17 A(K,J) = A(E,J) - B(J) + C(K)
   18 CONTINUE
   19 CONTINUE
   20 CONTINUE
      D6 200 I - 1,N
       IF (I - LZ(I)) 100,200,100
  100 K - I - 1
       D6 500 J . E,N
       IF (I - 12(J)) 500,600,500
  600 M - LZ(I)
       1Z(I) . IZ(J)
       12(J) - H
       D6 700 L - 1,N
       C(L) - A(I,L)
       A(I,L) . A(J,L)
   700 A(J,L) - C(L)
   500 CONTINUE
   200 CONTINUE
       RETURN
```

END .

```
SUBROUTINE SPLICO(X,Y,M,C)
      THIS SUBROUTINE DETERMINES CONSTANT COEFFICIENTS C(I, K) OF SPLINE-
C
      PITTED CURVE WHICH PASSES THROUGH DATA POINTS
      DIMENSION X(32), Y(32), D(32), P(32), E(32), C(4,32), A(32,3), B(32),
     12(32)
       MK-K-1
       D6 2 K-1, NM
       D(K)-X(K+1)-X(K)
       P(K.) - D(K)/6.
    2 P(K)-(Y(K+1)-Y(K))/D(K)
       D6 3 K-2, MM
    3 B(K)-E(K)-E(K-1)
       A(1,2)--1.-D(1)/D(2)
       A(1,3)-D(1)/D(2)
       A(2,3)=P(2)-P(1)+A(1,3)
       A(2,2)-2.*(P(1)-P(2))-P(1)*A(1,2)
       A(2,3)-A(2,3)/A(2,2)
       B(2)-B(2)/A(2,2)
       D6 4 K-3, NW
       A(K,2)-2.+(P(K-1)-P(K))-P(K-1)+A(K-1,3)
       B(K)-B(K)-P(K-1)+B(K-1)
       A(K,3)-P(K)/A(K,2)
      B( E )-B( E )/A( E, 2 )
       Q-D(M-2)/D(M-1)
        A(M,1)-1.+0+A(M-2,3)
        A( W, 2 ) -- Q-A( M, 1 ) + A( W-1, 3)
        B(M)-B(M-2)-A(M,1)+B(M-1)
       Z(N)-B(N)/A(N,2)
       MN-M-2
        D6 6 I-1, MN
        K-N-I
     Z(K)=B(K)-A(K,3)+Z(K+1)
        Z(1) -- A(1,2)+Z(2)-A(1,3)+Z(3)
        D6 7 K-1, MM
        Q-1./(6.+D(K))
        C(1,K)-Z(%)+Q
        C(2,K)-Z(K+1)+Q
        C(3,K)-Y(K)/D(K)-Z(K)+P(K)
        C(4,K)-Y(K-1)/D(K)-Z(K-1)+P(K)
        RETURN
        FORMAT( 2E12.4)
   101
```

END

```
SUBROUTINE SPLINE(X,Y,M,C,XINT,YINT,4,N,KDUM)
      THIS SUBROUTINE USES COEFFICIENTS FROM SUBROUTINE SPLICE TO
C
      CONSTRUCT CURVE THROUGH DATA AND THEREPRON TO INTERPOLATE FRINGE
      DEVIATIONS AT SELECTED GRID POINTS
C
      DIMENSION X(32), Y(32), C(4, 32)
      ME-KDUM
       IF(XINT-X(1))7,1,2
      YINT-Y(1)
       RETURN
       K-1
      JP(XINT-X(K+1))6,4,5
       TINT-Y(K-1)
       RETURN
      K-K-1
      IF(XINT-X(X))3,8,7
       YINT-(X(K+1)-XINT)+(C(1,K)+(X(K+1)-XINT)++2+C(3,K))
       YINT-YINT-(XINT-X(K))+(C (2,K)+(XINT-X(K))++2+C(4,K))
    8 TINT-YOU)
      RETURN
    7 WRITE(6, 101 )XINT, KE, N
  101 FORMAT(18 'XINT - 'F7.3,5X'FOR SCAN '12, ' AND FRAME' 12/)
       RETURN 7
       END
```

```
SUBROUTINE SPECSP(X,Y,M,C,XINT,YINT,N,KDUM)
     THIS SUBROUTINE USES COEFFICIENTS FROM SUBROUTINE SPLICO TO
      CONSTRUCT CURVE THROUGH DATA FOR SPECIAL CASE IN WHICH ONLY TWO
      FRINGE-PEAK LOCATIONS EXIST FOR A SCAN AND THEREFROM TO
C
      IPTERPOLATE FRINGE DEVIATIONS AT SELECTED GRID POINTS
C
      DIMENSION X(32),Y(32),C(4,32)
      KK-KDUM
       IF(XINT-X(1))7,1,2
       TINT-Y(1)
       RETURN
      K-1
      IF(XINT-X(K+1))6,4,5
       TINT-Y(K-1)
        RETURN
     5 K-K-1
       IF(K .LT. M) GG TG 3
       YINT-(X(K+1)-XINT)+(C(1,K)+(X(K+1)-XINT)++2+C(3,K))
        YINT-YINT*(XINT-X(K))+(C (2,K)+(XINT-X(K))++2+C(4,K))
        RETURN
     7 K-1
       Q6 T6 6
       END
```

THE FOLLOWING PRINT GUT RESULTS FROM A COMPUTER DATA REDUCTION OF TWO INTERFEROGRAMS OBTAINED BY TESTING THE

CCLLIMATOR F/8.7 (TEST 3)

ON THE WAVEFRONT SHEARING INTERFERONETER (USI) TEST SYSTEM

VALUES AND DEFINITIONS OF PHOGHAM PANAMETENS ANE PHINTEO BELOW -NOTES (1) X AND V AXES ARE COORDINATE SYSTEM OF SCANNER
(2) DISTANCE VALUES ARE IN MN UNLESS SPECIFIED OTHEWHISE

INPUT # 1 INDICATES THAT INPUT DATA WAS FRINGE-PEAK POSITIONS OBTAINED FROW MANUAL SCAN PASS = 2 INDICATES THAT TEST SYSTEM WAS DOUBLE PASS

FRAME 1 IS X-SHEARED INTERFERDGRAM AND FRAME 2 IS V-SMEARED INTERFERDGRAM

										2						
										EST-						
		_	N							-				_		
		DISTANCE ALONG Y-AXIS BETWEEN FIRST SCAN POSITION AND X-AXIS IN FRANE	FHAME							DISTANCE ALONG OPTICAL AXIS BETWEEN BACK FACE OF CUBE INTERFEROMETER AND TEST-LENS				MACHIFICATION OF INTERFERENCE PATTERN OCCUMING IN SCAMED INTERFEROGRAM		
-	N	Z								ETE				-		
¥	y	=	•							ě				2		
4	7.	X	:											=		
×		Ž								Ž				0		
N	3MANE	2	:							=				Į.		
DISTANCE ALONG X-AXIS DETWEEN V-AXIS AND APERTURE EDGE IN FRAME	•	2	•							9				×		
¥		2								Ŭ				Z		
2	:	150	:							8				2		
		7								A				1		
9		3	:							×		2		S		
4	:									BAC		SHEAR ANGLE OF CUBE INTERFERONETER		0		
2		E	:						441	2		0	ini	E E		
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2		9		2					i.	A		M	8			
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*	:	-		T	1		3	** FRAME 2	£	Ę	-	W	Ŧ	Z	5	151
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1		W		5	N N	:	ANS			1	STA	¥	WAVELENGTH OF LIGHT SOURCE	¥	WSI CUBE THICKNESS	COMPUTED SHEAR DISTANCE
Ž		Z	:	AO	2		8	:	9	Ž	5	₩.		2	3	7
1	:	510			0	:	6	:	Ž	2	2			Ž		Į
10				22.533 RADIUS OF TEST-LENS APERTURE	MANBEN OF FAINCES IN FHAME		MANBER OF SCANS IN FRAME !	:	MAXIMUM NUMBER OF SCANS IN EITHER FRAME	5	INAGE DISTANCE OF TEST LENS	BAD	WAVEL = .6328-03 HH	Ž	I	5
			.913	2	Ĭ	:	3	•	E							
		.913	=	2.3	Z		*		ž	0	•	-07	28		8	2
150.03	.26	•	•	~						29 .040	9	.4550-02	.63	.390	13.000	
:	107.268				2	22	20	2	3	2	22 = 1000.000	•				DELTA - 1.026
				5						_	=		بر		*	
. 5	* 5	PCSX =	POSY =	- SULIDE	-	- 23	MSH .	MSV .	N.S.	21 =	~	ŧ	AVE	XMAG =	THICK .	EL.
J	0		•		Z	Z	Z	z	2	N	N	•	•	×	-	٥

FRINGE SPACING FOR IDEAL LENS

FREPAC =

FOCUS

INGE-PEAK POSITIONS K(J.K.M) AS SCANNED (IMPUT DATA) ANE PRINTED BELOW IN PHINGE NO. K = SCAN NO.

7	15 23
EACH P	FRAME
5	-
BLOCKS	ALLOWED
2	CANS
MINTED	9 440
A	FRINGE
VALUES OF XIJ.K.N) ARE PRINTED IN 2 BLOCKS FOR EACH FRAME	HAXIMUM NUMBER OF PRINCES AND SCANS ALLOWED PER FRAME IS 29
3 04	3
VALUE	PAX 18

	0		n i	0		_	2.0	2				2 :	0		ų !		n :	0 9		0	0	d	2	2	0	0	0	ò	0	0	0										
•	.000	90.00	95.553	95.553	8.51	95.511	95.497	04.402	96. 608			20.00	95.470	40.00	330.00	100.00	25.4.2	2000	95.389	95.390	95.346	95.334	95.333	95.297	.000	.000	.000	000	.000	.000	. 000										
5	. 000	93.582	93-583	93.526	93.548	93.537	01.10	03.658	03.643	000000	000.00	93.597	263.56	93.576	03.613	93.624	93.591	93.53	93.503	93.465	93.451	93.436	93.436	93.412	93.268	• 000	. 000	000	000	000.	. 000										
=	91.556	91.582	91.663	91.653	91.633	91.627	623	0.0	410	000.14	91 - 625	91.625	109.16	91.616	619-16	619.16	91.658	91.626	91.591	91.543	91.516	91.557	919-16	91.435	91.392	.000	.000	000	000	000.	.000										
13	161.68	89.730	89.763	89.721	89.724	89.690		500.60	00000	700.60	269.68	869.68	89.641	609.60	89.675	89.684	80.716	99-692	89.675	89.627	89.586	89.578	89.555	69.537	89.512	.000	.000	.000	.000	000.	.000	53	.000	. 000	000	.000	0000	000-	000	000	.000
21	87.800	87.763	87.741	87.761	67.773	87.762			2010	167.78	67.733	87.761	87.763	87.770	87.77	87.751	87.135	87.748	87.728	67.693	87.6A2	87.687	87.674	67.630	87.608	.000	000.	000-	.000	•000	.000	92	• 000	000	•000	• 000	• • • • •	.000	000	000	000
=	86.058	85.967	85.946	616.58	85.859	05.8.88		90.00	120.00	65.783	85.602	85.832	829.58	65.655	95.619	929.59	65.763	85.796	85-802	85.778	85.738	85.738	85.688	99-100	85.664	.000	000.	000	0000	000	.000	27	.000	000	0000	.000	000	.000	000	000-	. 000
9	84.074	83.991	83.948	63.955	63.922	110.14	07000	630.013	83.500	83.872	83.653	83.863	83.892	63.971	63.866	83.635	83.845	83.843	83.853	83.822	63.786	63.603	83.763	83.769	83.736	.000	0000	.000	.000	.000	.000	2	.000	000	000-	.000	.000	.000	0000	000	. 000
•	.000	85.025	62.012	82.022	81.990		200.20	2.003	81.966	81.946	61.932	81.908	169-19	81.897	81.894	199-19	61.932	968-19	81.680	01.877	01.076	81.861	91.010	61.623	61.855	.000	.000	. 000	.000	.000	• • • • •	2	.000	• • • • •	.000	.000	.000	. 000	000	000	. 000
	.000	80.189	60.156	80.119	80.072		90.00	E0.00	80.08	80.053	80-019	70.976	79.953	79.949	79.979	79.988	79.992	79.970	79.997	79.966	79.965	79.929	79.928	70.676	000	000	000	.000	.000	.000	000-	2	.000	.000	.000	.000	.000	.000	•000	. 000	• • • •
•	. 000	000	78.318	78.252	78.218		76.193	78.156	78.082	78.073	76.078	78.062	78.059	78.039	78.062	76.063	78.061	78.067	78.036	78.053	78.013	77.583	78.010	78.004	000	000	000	000	000	000	.000	23	000	.000	.000	000.	.000	.000	•000	.000	.090
•	.000	.000	76.463	76. 103	76.266		16.182	76.171	76.186	76.163	76.132	76.158	76.133	76.126	76.100	76.152	76.110	76.106	76.187	76.108	76.100	76.103	70 003	000	000	000	000	000	000	000	. 000	22	000	.000	.000	0000	.000	.000	000	106-077	106.986
m	.000	000	000	74. 485	74.200		74.286	74.268	74.193	74.297	74.219	74.176	74.182	74.198	74.187	74.188	74.173	74.168	74.136	74.137	74.130	7	76.363	000	000	000		000	000	000	. 000	23	000	000	.000	000	000	104.892	195.003		
•	.000	000	000	000			72.416	72.315	72.398	72.291	72.283	72.289	72.289	72.290	72.271	72.273	72.247	72.201	72.201	72.227	72.10	72.482	000	000	000	000		000		000	000	50	000	000	000	0000	103.072	.203	.200	200	-200
m	.000	000	000	000			10.721	70.517	70.397	70.390	70.340	70.346	70.333	70.368	70.346	70.334	70.292	70.309	70.337	70.438	900		000			000				000	000	•	000	000	000	101-101					
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NCBHALLIZED FRINGE POSITIONS X(J.K.N) ARE PRINTED BELOW - J = FRINGE NO. K = SCAN NO.

VALUES OF X(J.K.N) ARE PRINTED IN 2 BLOCKS OF 32(ROWS) BY 16(COLUMNS) FOR EACH FRAME NOTE - THE FIRST FRINCE WAS ASSIGNED J.3 AS INPUT DATA. THE RECOND FAINGE J.A. ETC.

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11.411	11.398	11.402	11.398	11.403	11.392	11.394	11.416	11.412	11.427	11.433	111-467	11.462	11.476	.000	.000		.000	. 000	• • • • •	. 000	.000	56	• • • •	. 000	• • • • •	• • • • •	.000
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THE FOLLOWING GRID POINTS XINT. IF ANY, LIE INGIDE LENG APERTURE BUT OUTSIDE REGION OF INTERPOLATION

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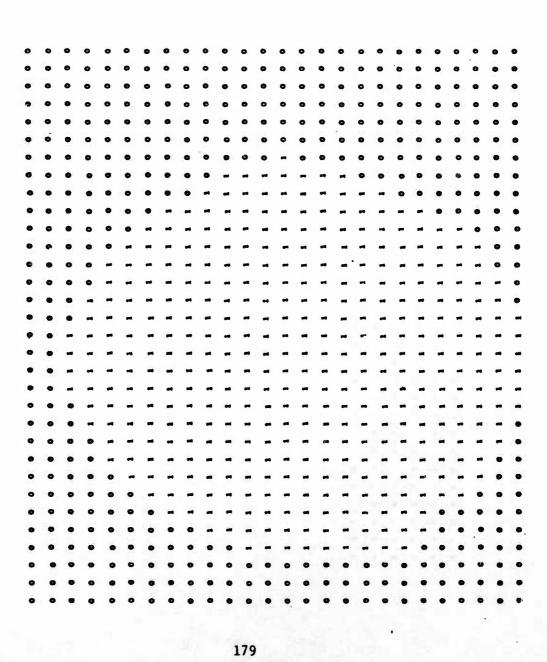
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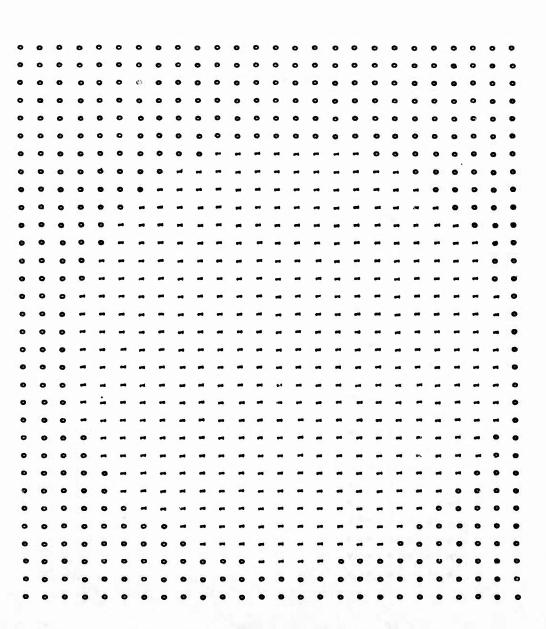
TOR SCAN 12 AND FRAME FOR SCAN 10 AND FRAME FOR SCAN 10 AND FRAME FOR SCAN 11 AND FRAME TOR SCAN 12 AND FRAME TOR SCAN 11 AND PRAPE FOR SCAN FOR SCAN OR SCAN FOR SCAN OR SCAN 4.500 20.500 3.500 22.500 2.500 23.500 23.500 1.500 24.500 3.500 1.500 2.500 1.500 24.500 24.500 25.500 1.500 24.500 25.500 * INT * A THIX ALM . = Lulx KINT . MINT . MINT . KINT . KINT & MINT . KINT . * INIX XINT .

FOR SCAN 14 AND FRAME 2 FOR SCAN 14 AND FRAME 2 FOR SCAN 14 AND FRAME 2 FOR SCAN 15 AND FRANE 2 FOR SCAN 15 AND FRAME 2 FOR SCAN 16 AND FRAME 2 FOR SCAN 17 AND FRAME 2 FCR SCAN 17 AND FRAME 2 FOR SCAN 18 AND FRAME 2 FOR SCAN 20 AND FRAME 2 FOR SCAN 21 AND FRAME 2 FOR SCAN 22 AND FRAME 2 FOR SCAN 24 AND FRAME 2 FOR SCAN 15 AND FRAME 2 FOR SCAN 16 AND FRAME 2 FER SCAN 17 AND FRAME 2 FON SCAN 20 AND FHAME 2 FOR SCAN 21 AND FRAME 2 FOR SCAN 22 AND FRAME 2 FOR SCAN 23 AND FRAME 2 FOR SCAN 18 AND FRAME 2 FOR SCAN 19 AND FRAME 2 FOR SCAN 19 AND FRAME 2 FOR SCAN 24 AND PRANE 32.500 25.500 1.500 24.500 25.500 24.500 2.500 23.500 2.500 23.500 3.500 3-500 4.500 5.500 1.500 .500 24.500 24.500 23.500 21.500 20.509 19.500 XINT . XINT . AINT = XINT = XINT . MINT . * INT X INT = X INT . KINT = A INT . * INIX MINT # KINT = MINT . XINT . XINT = MINT . XINT . XINT = X INT = X INT . X INT =

HIS = 1 INDICATES THAT A VALUE OF PRINCE OMDER P(J.K.W) WAS INTERPOLATED AT GRID POINT (1+2.K+2) IN X-SMEARED INTERFERDGRAN VALUES OF MIMICH ARE PRINTED BELOW -



MIZ = 1 INDICATES THAT A VALUE OF FHINGE CHOEM P(J.K.N) WAS INTEMPOLATED AT GRID POINT (K+2.1+2) IN Y-SHEARED INTERFEROGRAM VALUES OF HIZIFOR) ARE PRINTED BELOW -



FRINGE-OADER DEVIATIONS P(J,K,M) DETERMINED AT GAID POINTS BY INTERPOLATION FROM ADJACENT ORDER VALUES ARE PRINTED BOLOW J = COLUMN NO. OF GRID POINT K = RCW NO. OF GRID POINT

NGTE - VALUES AT GRID PCHITS FOR WHICH Jan (NOT PRINTED). Jaz. AND AT GRID POINTS FOR WHICH K=1. K=2. MAVE BEEN SET EGUAL TO 0.0 VALUES OF PILITAN ARE PRINTED IN 2 BLOCKS OF 32(ROWS) BY 16(COLUMNS) FOR EACH FRANK

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.000 .000 1.060 1.071 1.063 1.030 1.021	1.060 1.071 1.063 1.030	1.071 1.063 1.039	1.063 1.039	1.030		1.02	_	.997		.974	.955	.934	-912	£60°	.075	
.800 .800 1.025 1.064 1.064 1.047 1.001	1.025 1.044 1.044 1.047	1.044 1.044 1.047	1.064 1.047	1.047		1.00		1.002	-200-	. 15	. 955	.930	.915	. 897	.880	9
.000 .000 .000 1.034 1.057 1.044 1.021	.000 1.034 1.057 1.046	1.034 1.057 1.044	1.057 1.046	1:04		1.02	~	1.000	•	.977	196	.937	.922	•	. 693	. 80
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VALUES OF DEL(I.K) ANE PHINTED BELOW +

THE EMPERIMENTAL CONSTANTS BI-B2(X TILT).AND B3(Y TILT) AME UNKNOWN AT THIS POINT AND, THEMEFONE. Mave not ceen removed from the computed del valués DEL(13.12) WAS SET EQUAL TO ZERO

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•	000	.000			.000	.000	. 000	-10.368	-9.445	-8.508	-7.581	-6.690	-5.793	-4.693	6000	-3.12
	000	.000			.000	-11.508	-10.545	-9.500	-6.657	-7.708	-6.777	-5.878	-4.973	-4.070	-3.194	-2.31
v	. 600	.000	000	.000	-11.786	-10.705	-9.800	-0.831	-7.874	-6.919	-5.984	-5.080	-4.172	-3.272	-2.392	16.1-
•	•000	000-	. 000	.000	-11.077	-10.060	-9.054	-8.073	-7.100	-6.152	-5.214	-4.305	-3.396	-2.504	-1.624	
•	.000	.000	.000	-11.364	-10.352	-9.336	-8.320	-7.332	-6.363	-5.402	-4.464	-3.553	-2.648	-1.750	867	.00
•	.000		.000 -11.675	-10.663	-9.625	-8.602	-7.586	-09-9-	-5.636	-4.676	-3.739	-2.819	-1.912	-1.011	127	*7.
•	. 000	.000	.000 -10.999	2.944	-16.9	-7.685	-6.873	-5.678	606-1-	-3.957	-3.023	-2.087	-1-173	274	\$09.	1.0
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2	.000	.000 -10.682	-0.643	-6.580	-7.532	4.497	-5.483	-4.086	-3.508	-2.542	-1.595	665	.243	1-131	2.003	2.85
m	-300	-500 -10-037	-6.967		-6.867	-5-831	-4.823	-3.627	-2.041	-1.869	923	•000	906.	1.796	2.671	3.52
:	. 000	-9.388	-8.308	-7.248	-6.211	5.175	-4.165	-3-175	-2-191	-1.219	273	.654	1.558	2.451	3.332	4.18
5	.000	-8.726	-7.665	-6.609	-5.573	-4.545	-3.536	-2.542	-1.556	586	.364	1.268	2.192	3.094	3.981	. 03
:	. 000	-0.101	-7.650		4.965	-3.936	-2.921	-1.926	943	.024	.976	1.907	2.811	3.710	4.597	6.4.0
17	.000	-7.520	-6.443	-5-394	-4.358	-3-328	-2.320	-1.324	344	.621	1.574	2.504	3.412	4.314	5.194	• 0
	000	-6.927	-5.860	608-	-3.775	-2.746	-1.737	740	.239	1.203	2.154	3.084	3.991	4.884	5.757	6.61
2	•000		-5.271	-4.244	-3.205	-2-179	-1.168	177	100.	1.767	2.717	3.546	4.555	5.442	6.319	7.16
64	.000		4.747	-3.663	-2.651	-1.623	636	.376	1.349	2.320	3.273	4.201	5.112	6.003	6.881	7.7
12	.000		-4.208	-3.172	-2.114	-1.093	086	. 403	1.006	2.054	3.807	4.730	5.655	6.551	7.430	8.
22	. 000	. 000	.000	•00•	-1-615	569	.430	1.428	2.403	3.374	4.330	5.275	6.191	7.090	7.970	9.93
2	000	-000	.000	.000	-1.125	08	. 932	1.920	2.00	3.684		5.791	6.109	7.615		9.35

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23	• • • • • • • • • • • • • • • • • • • •		10.001	11.610	12.399	13.177	13.921	. 000	.000	.000	. 000	• 000	• 000	000.	000	000
23	2.00	_	11.346	12.153	12.943	13.716	.000	000	.000	••••	• • • •	.000	000.	• 000	• • • •	000.
23	10.218	11.056	11.878	12.668	13.505	.000	. 000	000	.000	.000	000-	. 000	• 000	000•	000-	.000
52	10.724	11.571	12.422	13.251	. 000	.000	.000	• • • • • • • • • • • • • • • • • • • •	.000	•000-	000-	000	• 000	• • • •	. 000	000
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THE COEFFICIENTS AND MAXIMUM VALUES OF THE ABBMMATIONS INTRODUCED BY THE CUBE INTERFEROMETER ARE LISTED BELOW

. 6328-03 H	TEST-LIGHT MAVELENGTM 6328-03 M	13.000 HH	CUSE THICKNESS = 13.000 MM	36 00	TEST-LENS F/NO. = 0.65	TEST-LEN
		TTH GROER SPIERICAL	4	. 000000	.106130-20	E(23)
		STH ORDER SPHERICAL	91 N	.0001052	.282715-14	8(22)
		300 DRDER SPHERICAL	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0532007	477419-08	E(11)
		DEFECT OF FOCUS	DEFECT	• • • • • • • • • • • • • • • • • • • •	. ecooo	•
		TYPE	•	MAX. VALUE	COEFFICIENT	

- ONLY DISCHALF OF EACH OF THE ABOVE ABERRATIONS IS MEMOVED IT I'VE LEST STREM LA DOUBLE THE

MESIDUAL VALUES (V(1.K.)). THAT 15. THE DIFFERENCES BETWEEN THE IMPUT WAVEFRONT (DEL VALUES) AND CUTPUT WAVEFRONT (DE VALUES) FRE PRINTED BELOW --SYMMETRICAL ABERRATIONS INTHODUCED BY CUBE HAVE BEEN MEMOVED

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5	.000	+10	100	•00•	- 002	. 000	.003	001	• • • •	•00•	-005	005	.000	600	900	00
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22	23	2	\$2	2	2	5	52	96	31	32

PHS OF ANALYTIC BAVEFRONT (DE VALUES) WITH BILL.BI21.8131. AND CUBE ABERRATIONS. IF ANY. REMOVED . LAMBOLL 3.10436 RMS OF IMPUT WAVEFRONT (DEL VALUES) WITH BILL-BIZZ-BIZZ- AND CUBE ABEMMATIONS. IF ANY. MEMOVED # LAMBDA/ 3-10505 MPS OF MESIDUAL MAVEFRONT (DEL-DE) = LANBOA/ 94.088

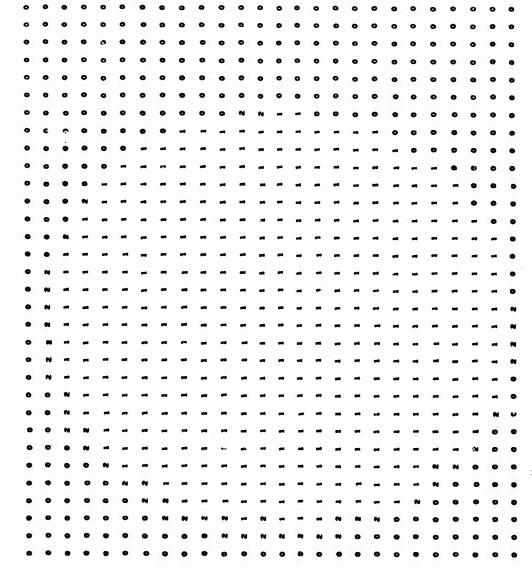
MENE LAMBOA = .6328-03 MM

THE COEFFICIENTS B(1) FON THE SET OF 23 POLYNOMIALS WHICH DESCRIBE LENS ABERRATIONS ARE LISTED BELOY-CUBE ABERRATIONS. IF ANY, MAVE BEEN REMOVED FROM BOTH THE CORFFICIENTS AND THE MAN VALUES

POLYNOH 1AL		CONSTANT	× ,	~,	~ ~ ,		2 2 2 3 3	2 2 X	X X X XX	4 A T ME 24			~ ;	2 2		2 2 2 3	2 2 2	~ ~	A - 2X V = 3XV	- ~	_	2 2 3	* * * * *
A 8678 A 7 104	CONSTANT	1111-1	4714-4	FOCUS DEFECT	O DEG ASTIGACINOS	48 DEG ASTIG. (340)	K-COMA(3MD)	V-CORAC SMO.	H-CLOVER(380)	V-CLOVER(310)	SPICE RICAL (380)	• DEC ASTIG.(STN)	45 DEG ASTIG.(STH)	10 10 10		H-COMP (HAM)	HIE SECONA	A-CLOSTER STATE	A Doverties			SPIESTICAL (STR)	SPERICAL (TTN)
MAX VALUE OF ABERRATION (B(1) PRADIUS ON N=1	1.3104	11.1.00	7.586.	-1.5404	1000	.000	******	1701	N ** 0 *		. 75.27	70R0	.0328	5920	0:20	1372	1907		0677	M8 00 - 1		-1.266	****
:	.131938+01	.192824+00	-137761+00		-117267-94	.290217-05	.931223-06	-023523-36	-230 880 -06	-578237-07	79-918060	272394-00	. 294 494-08	237421-04	472053-06	213678-09	29¢ 166-99	102269-05	136 140-09	030024-11	. 256566-10	341389-10	*1-622 9C9-
	•	*	•	•	•	•	•	•	•	:	=	:	2	:	:	•	-	:	2	0 2	12	~	2

CCONDINATE VALUES DEFINING LENS APERTURE ARE PRINTED PELOW -- XI AND X2 ARE APERTURE ECUNCARIES FOR A PARTICULAR Y OR SCAN VALUE

••••	74.057	65.385	92.642	40.00	102.395		108.674																		
	2	x2 .	X 2	×2×	x 2 =	x = x			¥2 #			*		•	• .		X2 =	x2 =	¥2 •		X2 =				•
ī		: :	:	- x					•	* - ×	•	•	•					×	•	×	•	× 1×	* :×	· ×	×
•	2.341	7.023					30.434																		
													•		•							•	•		•
_										•					•	•							•	-	
_	_	_	_	_		ш	_	ĺ	=	-	=	-	=	-	=	=	=	=	8	Ñ	N	ä	Ň	Ä	Ň
SCAN	SCAN	SCAR	SCAR	SCAR	SCAN	SCAN	SCAN	8624	SCAN	SCAN	SCAR	SCAN	SCAN	SCAN	SCAR	SCAN	SCAN	SCAN	SCAN	SCAN 21	SCAN 22	SCAN	SCAN 24	SCAN 25	SCAN 26



MUMBER OF GRID POINTS IN THE CLEAR LENS APERTURE IS

VALUES OF THE PUBIL FUNCTION PHASE ARE PRINTED BELOW TEAMS INVOLVING B(1).B(2). AND E(3) HAVE BEEN SUBTRACTED FROM DE VALUES
DE = 0.0 AT THE CENTER OF THE LENS APERTURE
THESE VALUES OF DE DO NOT, GENEMALLY, REPRESENT THE PUBIL FUNCTION IN THE PLANE OF BEST FOCUS

11	000. 000.	1.239 -1.256	-1.084 -1.111	919952	761796	.616653	486525	.372412	274316	191239	126171	079126	052 099	160*- **0*-	056102	087131	134176	-196235	270301	355390	.452484	559589	.678 706	607631	939 957
15 16	. 000	- 022.	-1.050 -1.	868	735	290	460	345	346	162	960	8+0	021	6119	020	050	101	171-	246	336	434	544	939	198	930
•	.000	-1.202 -1	-1.043 -1	9.6	720	9.2		333	233	150	- , 583	035	900		•10	041	. 160	162	. 241	330	431	544	668	500	. 948
:	.000	-1.107	-1.034	672	717	576		336	236	155	080	045	014	001	021	054	•01	170	249	340	443	558	687	626	976
2	.000	-1.176	-1.032	077	728	1.590	466	356	260	179	115	068	041	034	041	079	129	104	273	365	70	568	720	•	-1.019
=	.000	-1-167	-1.036	694	751	618	400	392	299	221	159	814	087	080	092	123	171	235	314	90 • • -	512	634	770	921	-1.077
9	.900	.000	-1.051	921	787	199	546	•	355	281	221	177	-,152	14	155		230	293	370	463	571	696	637	001	-1 - 1 50
•	.000	. 000	-1.067	956	636	710	610	513	4 20	357	300	258	233	225	234	261	306	366	443	-, 536	646	77.	919	-1.077	-1.234
•	.000	. 00	-1.080	166		70	688	596	516		***	354	329	321	329	33A	396	455	532	626	739	670	-1.010	-1.175	000
•	.00	. 000		-1.036	958	866	778	**	619	555	503		0 * * * -	431	436	462	503	196	637	733		981	-1.129	-1.200	000
•	.000	. 000	.000	000	-1.01	952		802	73k	674	625	586	565	555	562	584	624	682	759	856	972	-1.104	-1.246		000
w	800	• • • •	.000	.000	000	-1.030	977	17	858	804	759	724	702	693	699	721	760			166	-1-105	-1.231	• • • • • • • • • • • • • • • • • • • •	.000	900
•	.000	.000	000	000	.000	.000	-1.065	-1.020	08	9.0	104	670	849		6.7	869	908	965	-1.040	-1.131	-1.236		000	8	900
n	.000	.000	. 000	000	.000	.000		7	-1-096	-1.066	-1.040	-1.015		943	-1.000	-1.021	-1.058	-1-111	-1.179	.000				.000	
		2	- 000	.000	. 000	.000	• 000	8	• 000	.000	136	-1-103	134	132	-1-140	-1.159	-1.191	.000	. 900	.000	.000	90	.000	. 000	
~	. 600	000	٠	٠	٠	۲	•	•	•	•	-1.136	-	-1.134	-1-132	÷	÷	÷	•	٠	•	•	•	•	•	

• • • • 000. 000. .000 .000 .000 .000 .000 .000 .000 .000 .000 .000 .000 .000 -1.155 -1-000 -1.109 -1.128 -1.01000 ... 8 .000 .000 . 000

FICIENT FOR DEFECT OF FECUS. COPRESPONDING DISTANCE TO FOCAL PLANE, AND RHS OF RESULTING WAVEF	RMS(LaMODA/VALUE)	2.03786	J.0026.	3.07091	3.10106	3.21511	9.29269	3.37406	3.45949	3.54029	18646.0	3.74341	3.848.5	9.45958	4.07711	2010B	4.33392	4.47456	4.62438	4.78429	4.95531	5.13861	8.339+8	8.5.7.8	5.77622	
ING DISTANCE TO FOCAL PI	Z 2 (MM)	3000.000	000.000	100.000	999.971	999.961	999.952	546.646	999.932	999.923	699-913	600,000	468.666	498.606	999.875	598-666	999.855	949.646	966.836	909.826	499.817	999.807	190.191	999.708	909.778	
T OF FCCUS. CORRESPOND	•		45 3980-03	446351-03	438722-03	431094-03	423465-03	41 5635-03	408206-03	400577-03	39 29 47-03	365317-03	377687-03	370057-03	362427-03	354797-03	347166-03	339536-03	331905-03	324274-03	316643-03	309012-03	301380-03	293749-03	286117-03	
FICIENT FOR DEFEC	INDEX PARAMETER. H	•	•	•	•	m	•		•	¥	•	=	13		:	5.	•		€ Seri	•	20	12.	22	53	*	

6.29238 4.62144 6.00368 7.25294 7.63655 16440. 4.58467 12650.0 0.52661 10.26430 10.98229 12.67870 13.67030 15.92641 18,33438 19.40187 20.62523 20.05549 14.50094 11.78440 17.14103 20.20937 20.57031 19.17624 18.06665 16.84260 15.65360 14.75762 999.749 966.739 999.643 999.633 999.624 999.508 909.537 999.527 ***** 999.759 999.730 999.720 999.710 \$50.053 *09.666 999.585 949.575 104-66 200.000 549.672 299.665 *19.666 666.646 999.566 966.986 949.546 169.666 115.644 -- 141087-03 -.270853-03 -.255586-03 -. 240324-03 -- 21 74 25-03 -- 202159-03 -. 194525-03 -- 163990-03 -.146722-03 --133452-03 -.263221-03 -. 247956-03 -- 232691-03 -. 225056-03 -. 209 792-03 -- 186892-03 --179258-03 -. 171624-03 -- 156356-03 -. 125el 8-03 -- 118183-03 -- 110548-03 -. 102913-03 -- 952772-04 -.076416-04 -- 8000000-04 -. 723702-04 --647342-04

J.

6.51360 11.59230 10.80000 1.48571 ...2004 9.41388 7.95718 7.54378 7.16630 4.02627 5.96331 5.72020 5.09333 4.91292 4.74451 4.58697 . 30064 4.17020 4.04727 3.93126 3.62159 6.22693 5.49540 13.43456 10.10979 5.28700 12.46914 4.43931 999.315 999.257 449.247 989.210 ****** 999.392 999.373 999.353 999.308 999.286 999.276 999.238 922.000 **** 996.479 ****** ****** 160.000 120.000 204-446 305.000 999.383 999.300 999.334 999.324 117.000 199.267 **** .133A52-03 .650995-04 .803769-04 .118573-03 . 126212-03 -. 494619-04 --41 6255-04 -. 341890-84 -. 26 5523-04 -- 109150-04 -- 11 2785-04 -- 364132-05 .399596-05 .116334-04 . 1927 10-04 .269087-04 .345469-04 .421846-04 .49 6227-04 . 574610-04 .727381-04956548-04 .103294-03 .110923-03 .141:92-03

	-164413-03	400.204	3.61935
•	.172053-03	000-100	3.5290
:	. 179690-03	000.100	\$14E+*E
:	.187335-03	999.180	3.35267
•	. 194976-03	040-170	3.27218
:	.202617-03	999.160	3.19542
:	.210258-03	999-151	3.12214
•	.217900-03	999.141	3.05211
•	. 22 5 5 4 1 - 0 3	***************************************	2.96511
9.5	.233163-03	999.122	2.92096
6.0	. 240825-03	999-112	2.05949
:	.246467-03	999.102	2.80052
r	. 256109-03	000.000	162-14391
:	.263751-03	600.000	2.68953
•	.271394-03	***************************************	2.63724
•	. 279036-03	*90.66	2.58693
	. 286679-03	*50°646	2.53649
001	.294322-03	\$40.045	2.49101
101	. 301965-03	***************************************	2.44681
102	.309606-03	. 520*666	2.40339
103	. 31 72el-03	900-666	2.36147
	.324895-03	900.000	2.32098
105	.332536-03	966.966	2.20105
901	.340182-03	*******	2.24401
101	.347826-03	998.977	2.20739
•	.355470-03	496.864	2.17194
•	.363114-03	999-958	2-13761
110	.370759-03	******	2.10434
111	.378403-03	966.936	2.07208

2.04079	2.0104 J	66096.1	1.95232	1.92450	1.89744	1.07117	1.8455	1.62070	1.79646	1.77204	1.74987	1.72741	1.70563	5	2.87579	2.01627	2.75914	2.70427	2.69151	2.60077	2.55191	2.50484	2.45946	2.41569	2.37344	2.33264	2.29321	2.25500
959.66	910-010	404-804	004.844	048.890	000.000	170.000	190.064	***************************************	200.000	998.R32	998.823	*******	608.803	TEST FOCUS POSIT	010.0001	1000.014	1000.020	1000.039	9.0.0001	1000.056	990.0001	1000.077	1000.087	1000.001	1000-100	1000.114	1000.125	1000.135
														11TE SIDE OF	1000										-			
NO-84048N.	80-800866.	. 40 L338-03	.408883-03	.416628-03	.424273-03	.431919-03	. 439565-03	. 447211-03	.45685-03	. 462503-03	.470149-03	. 477795-03	.485442-03	US SHIFT IS SUBSEQUENTLY MADE TO OPPOSITE SIDE OF TEST FOCUS POSITION	469236-03	476865-03	484493-03	492120-03	499748-03	507376-03	515003-03	522630-03	530257-03	537884-03	545511-03	853138-03	560764-03	E0-16695-03
11.8	113	*:	511	•::	11.7	• * * * * * * * * * * * * * * * * * * *	111	120	121	. 221	123	124	129	US SHIFT IS SA	126	127	120	¥.	130	131	132	133	134	135	136	137	130	139

140	576017-03	1000-145	2.21619
1•1	503643-03	1000154	2.16248
7.	591269-03	1000.164	2-14790
	50 8 695-03	1000.174	2.11439
:	606520-03	1000.183	2.00191
145	614146-03	1000.193	2.05040
•	621771-03	1990-203	2.01983
1.7	629396-03	1000.212	1.9901
•	637021-03	1000.222	1.96134
•••	644646-03	1000.232	1.93334
150	652271-03	1000.241	1.90612
131	699696-03	1000.251	1.87966
152	667520-03	1000.261	1.06393
153	675145-03	1000.279	1.62000
154	662769-03	1000.280	1.80450
155	690393-03	1000.290	1.78076
156	698017-03	1000.299	1.75763
181	105640-03	1000.300	1.73510
150	ED-+92614*-	1000.310	1.71313
159	720687-03	1000.320	1.69171
0.	726511-03	1000.338	1.67082
	736134-63	1000.347	1.65044
162	74 3757-03	1000.357	1.63055
163	751 380-03	1000.367	1-61113
<u>3</u>	759002-03	1000.376	1.59217
591	766625-03	1000.396	1-57365
9	774247-03	1000.396	1.5555
101	781869-03	1000.405	1.53786
:	78948-03	1000.415	

1.1465	1000.695	10 10 47- 02	-
1 - 1 963	1300.685	100265-02	:
1-1663		995233-03	5
1-1765		987615-03	*
1.1868		979996-03	50
1.1973	1000.647	972378-03	92
		E0-054490	=
		957141-03	
•		949522-03	3
	809-2001	941903-03	:
	1000.598	934284-03	6
		926664-03	
	1000.579	919045-03	
		911425-03	\$
	1000.560	403805-03	2
	1000.550	E0-901968*-	2
1.3266	1000.540	888565-03	5
1.3397	1000-531	880945-03	
		673325-03	170
	1000.512	865704-03	2
	1000.502		1
		E0-590000	4
	1000.463	842842-03	75
		635221-03	*
	1000.463	827600-03	2
1.4551	1000.454	819978-03	17.2
1.470	1000.	812357-03	17.
		804735-03	10
	1000.425	797113-03	•

		123132-02	226
.0265	1000.965	122371-02	22.2
		121609-02	ż
		120646-02	223
		120087-02	222
		119325-02	221
		11886-02	220
		11 7802-02	513
		117041-02	218
		116279-02	217
,		115810-02	912
		114756-02	215
		113595-02	214
		113233-02	213
		112472-02	212
		111710-02	12
		110049-02	072
		110187-02	5
		109426-02	. 02
		10868-02	2
		107002-02	206
		107141-02	202
			204
			202
,		104856-02	202
		10 4044-02	2
			200
			199
		101809-02	2

. 91 398	•010••	.00178	00560.	16600.	• • • • • • • • • • • • • • • • • • • •	.67634	.87267	C0400	.06155	. 6560		8054B*	. 1040.	*0***	.62961	.82475	.61975	.61481	£6600°	. 80510	*6008*	. 79563	19061
1000.994	1000.994	1001-004	1001-013	1001-023	1001.033	1001.042	1001.052	1001 -062	1001-011	1001 -001	1001-001	1001-100	1001.110	1001-120	1001 -129	1001-139	1001-148	1001-150	1001.160	1001.177	1001 -187	1001-197	1001.200
123894-02	20-559521	125416-02	12417-02	126939-02	127700-02	128461-02	129223-02	129984-02	130745-02	131506-02	132267-02	133029-02	133790-02	134551-02	135312-02	138073-02	136834-02	137595-02	138356-02	139117-02	139878-02	140639-02	141400-02
227	228	**	230	231	232	233	234	235	236	237	236	239	2	241	25	200	**	5•2	9.2	247	:	•	250

THE MINIMUM MAS FROM THE VALUES LISTED ABOVE IS LAMBOA. 20-625 FOR M = 46

THE FOCAL POSITION. 22. ALONG THE OPTICAL AXIS WAS CHAMGED IN INCREMENTS OF .10 OF THE RAYLEIGH TOLERANCE ON DEPTH OF FOCUS HOUSEVER. IF H = 125 OR 250. THE INCREMENT WILL BE DOUBLED AND THE SEARCH FOR MAXIMUM LANGOA/HMS HEPEATED

			000.	125	151	147	133	115	- 00 -	080	064	640	036	025	610	016	-101	021	026	030	031	029	023	013	100.	.021	.056
		•	. 000	140	164	155	137	110	099	080	062	5.0.	030	018	011	600	110	017	024	030	520	035	160	023	011	. 005	• 63•
		<u>.</u>	.000	154	166	155	136	117	160	078	059	1 40	025	013	005	E00°-	900	013	025	031	037	0.00	038	032	020	110	.012
		•	000	147	158	149	132	113	095	076	057	039	022	010	-005	000	•00	011	025	032	0.00	0	045	045	037	028	010
JES AND	305	13	.000	127	•• 1 ••	136	124	901	160	074	056	039	023	011	₩00*-	005	005	013	024	034	043	6.00-	052	150	050	. 00.	033
H OE VALUES		12	.000	095	122	123	111	101	089	073	058	043	028	-101	010	000	110	019	026	038	1.00-	054	058	061	063	064	056
SUBTRACTED FROM	DEFECT OF	=	•000	051	093	10+	105	095	085	074	062	6.0	037	027	021	019	021	027	035	0	052	090	066	072	07	083	079
	F0C US	•	• • • • •	• • • •	036	160	080	087	083	076	068	650		1.00-	035	033	034	030	040	150	050	066	074		**	103	-101
PAVE BEEN	G MA KINUM	(. •)	.000	.000	900	051	071	079	1.00.	000	076	069	063	056	051	0.0		050	054	050	066	074	• 00 • -	001	1111	123	120
	ž						_	_				=		N	24	3	79	2	3	c	2	•	•			_	
IF ANY.	MENA II	•	.000	.000	.061	011		069	079	083	083	08	076	072	067	064	062	062	064	068	075	084	0%	112	129		. 800
<u> </u>	WITH A REMAINING	•	000.	000.	190.	.005011	017	053069	07307	08508	80 060	160	09007	08607	08304	0 070	0760	6790	675 0	078	0820	095	11009	128112	14512	151141	000
ABERRATIONS. IF	20.625 WITH A	•				•	•							'											•		
ABERRATIONS. IF	LAMBDA/ 20.625 WITH A		000.	. 000	000.	- 640-	110	053	073	085	060*- 560*- 660*-	160	000-	086	003	070	076	079	075	078	107 096 085	117107095	110	128	149	151	000
ABERRATIONS. IF	15 LANBDA/ 20.625 WITH A	6 h	000. 000. 000. 000.	000.	000. 000. 000.	- 500 000.	.032017	026053	036 062 073	083085	095090	100 001		- 1115 1111 100	097083	093 079	100 089 001	067075	086 075	840 680	107 096 085	117107095	131 123 110	141 140 128	152165	151 000. 000. 000.	000.
ABERRATIONS. IF	15 LANBDA/ 20.625 WITH A		000. 000. 000.	000. 000. 000.	000. 000.	- 500. 000. 000.	***************************************	.021026053	036062073	072083085	060*- 560*- 660*-	105100091	110102090	1111 100 086	108 067 063	108112104093079	-105106100089	098087075	2.097 086 075	100089078	107 096 085	117107095	131 129 110	14114012B	152 145	.000 .000	000. 000. 000.
BILL AND BILL AND CUBE ABERATIONS. IF	LAMBDA/ 20.625 WITH A	•	000. 000. 000. 000.	000. 000. 000. 000.	000. 000. 000.	- 5.0. 000. 000. 000.	.000 .000 .032017	.000 .021026053	.016036062073	042072083085	078093095	100103100		- 1115 1111 100		112104093079	-105106100089	105096075	104097086075	106100008	110107096085	1171171095	12:13!129110	.000141140128	.000 .000152145	151 000. 000. 000.	990. 900. 900.

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CODADINATES OF THE GAID POINTS AT WHICH DECLIAR) WAS DETENMINED ANE PAINTED BELOW -

WOTE - CCONDINATE VALUES OF 6.0 INDICATE THAT THE GRID POINT WAS OUTSIDE THE LENS APERTURE

11	72.57	72.57	72.57	72.57	72.57	72.57	72.57	72.57	72.57	72.57	72.57	72.57	72.57	72.57	72.57	72.57	15.51	72.57	72.57	72.57	72.57	72.57	72.57	72.57
•	67.89	67.89	67.89	61.89	67.89	67.89	67.89	61.89	67.89	61.89	64-69	67.89	67.89	67.89	64.49	67.89	67.89	67.89	67.89	67.89	61.69	67.69	61.00	67.69
5	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21	63.21
=	56.53	56.53	56,53	58.53	58.53	58.53	56.53	58.53	58.53	58.53	58.53	58.53	58.53	58.53	58.53	56.53	58.53	58.53	58.53	56.53	58.53	58.53	58.53	58.53
2	53.84	53.84	93.84	53.64	53.64	53.84	53.64	53.84	53.84	53.84	53.84	53.64	53.84	53.64	53.84	53.84	53.64	53.64	53.84	53.64	53.84	53.84	53.84	53.84
12	49.16	49.16	49.16	9	49.16	49.16	49.16	49.16	91.60	49.16	49.16	49.13	91.6	49.16	49.10	49.16	49.10	49.16	49.10	49.16	49.16	49.16	49.10	*0.10
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2	0	39.80	39.60	39.80	39.80	39.00	39.80	39.60	39.80	39.80	39.80	39.80	39.80	39.80	39.90	39.80	39.80	39.80	39,80	39.80	39.60	39.80	39.00	39. 80
X-VALUE	00.	35.12	35.12	35-12	35.12	35.12	35-12	35.12	35.12	35.12	35.12	35.12	35.12	35.12	35.12	35.12	35.12	35.12	35.12	35.12	35.12	35-12	38-12	35.12
¥ •	00.	30.43	30 .43	30.43	30.43	30.43	30.43	30.43	30.43	30.43	30.43	30.43	30.43	30.43	30 .43	30.43	30.43	30.43	30 .43	30.43	30.43	30.43	30.43	•
•	0	00.	25.75	25.75	25.75	25.75	25.75	25.75	25.75	25.75	25.75	25.78	25.75	25.75	25.75	25.75	25.75	25.75	25.75	25.75	25.75	26.75	25.75	0
•		00.	00.	21.07	21.07	21.07	21.07	21.07	21.07	21.07	21-07	21.07	21.07	21.07	21.07	21.07	21.07	21.07	21.07	21.07	21.07	21.07	00.	•
¥.		00.	.00	00.	16.39	16.39	16.39	16.39	16.39	16.39	16.39	16.39	16.39	16.30	16.39	16.39	16.39	16.39	16.39	16.39	16.39		8	
•	8	8	.00	.00	.00	11.71	11.71	11.71	11.71	11.71	11.71	11.71	11.71	11.71	11.71	11.71	11.71	11.71	11.71	11.71		.00		8
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ES OF THE PUPIL FUNCTION THANSLISK) ANE PHINTED BELOW -

THE PUPIL FUNCTION IS A COMPLEX GUANTITY AND. THEREFORE, EACH VALUE IS A PAIR OF VALUES OF THANSLIK!) AND PHINTED IN 4 BLOCKS OF 32(HOWS) BY BICOLUMNS!

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VALUES OF THE HODULUS (HTF) AND PHASE (PTF) OF THE OPTICAL TRANSFER FUNCTION ARE PRINTED BELOW -

THE NTF AND PTF VALUES ANE PHINTED AS A PAIN IN & BLOCKS OF 65 (NOVS) BY BICCLUMMS

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FOLLOWING PARAMETERS. IN ADDITION TO THE DE AND OTF VALUES. ARE WRITTEN ON TAPE WHICH BECOMES INPUT TO THE PLOTTING PHOGHAM IS LISTING SHOULD BE CHECKED REFORE RUNNING PLOTTING PROGRAM

TTING PROGRA			
THIS LISTING SHOULD BE CHECKED RETORE RUNNING PLOTTING PROGRA	DELTXY = 7.399	MAVE, ENGTH # . 6328-03	
TING SHOULD B	0.9.4	57.777	
THIS LIST	DELTA .	PADIUS = 57.777	

RPSMAX = LAMEDA/ 20.625

FANNER =

SEREPT PRINTS

APPENDIX B

COMPUTER PROGRAM TO PLOT WSI TEST DATA

The computer program used to generate machine plotting of WSI test data is presented. An outline of program operation is given together with an input description, auxiliary definitions of program variables, listing of subroutines, computational program listing, and a sample printout.

Outline of Program Operation

The program uses a set of subroutines, termed the Graphical Display System, to produce graphic elements which are independent of any given display device. These graphic elements, or plotter directives, are placed in intermediate drum storage, and for the present program, these directives are transferred to actual plotter commands by two other independent programs called the PRINTER post-processor and the CALCOMP (California Computer Products, Inc., Anaheim, Ca.) post-processor. The PRINTER post-processor provides plots on a standard computer line printer, and the CALCOMP post-processor provides plots on an incremental pen-and-ink device. The printer plots provide an inexpensive and speedy set of plots for general inspection. The CALCOMP plots are high quality and suitable for final presentation in reports or slides. Examples of both types of plots are given later in the sample printout.

- A. Input data magnetic tape containing parameters, pupil function, and OTF as generated by WSI data-reduction program
- B. Calculations
 - 1. Compute coordinates of circular lens aperture
 - 2. Compute coordinates of grid values at which pupil function is known
 - 3. Compute contour levels for plotting pupil function
 - 4. Determine normalized MTF
 - 5. Compute spatial-frequency coordinates at which MTF is known
 - 6. Compute contour levels for plotting MTF

- 7. Determine PTF relative to value at maximum MTF
- 8. Compute contour levels for plotting PTF
- 9. Determine tangential and sagittal MTF and spatial-frequency coordinates at which the MTF is known
- 10. Determine tangential and sagittal PTF

C. Output data

- Paper printout (See sample printout.)
 - a. Parameters and pupil function written on input tape
 - b. Contour levels for pupil function
 - c. Contour levels for MTF
 - d. Contour levels for PTF
 - e. Spatial-frequency cut-off for diffraction-limited lens of same f/number as test lens
 - f. Printout plot (See sample printout.)
 - (i) Contour map of pupil function
 - (ii) Contour map of MTF
 - (iii) Contour map of PTF
 - (iv) MTF vs spatial frequency for test lens (0 to diffraction-limited spatial-frequency cut-off)
 - (v) MTF vs spatial frequency for test lens* (0 to lowest spatial frequency at which MTF is less than 0.05)
 - (vi) MTF vs spatial frequency for diffractionlimited lens of same f/number as test lens
 - (vii) PTF vs spatial frequency for test lens

^{*}This plot is optional; for highly aberrated lenses for which the RMS of the wavefront is greater than 2.00, this plot will be generated with an expanded scale for low values of spatial frequency.

2. Magnetic tape containing plotting directives for CALCOMP plotters; the resulting plots will be versions of the printer plots f.(i) through f.(vii) listed above.

Input Description

The input quantities for the plotting program exist on magnetic tape generated by the data-reduction program. The FORTRAN program statement for reading these unformatted data on tape unit 7 or A is given below to indicate presence and order of the variables.

READ TAPE 7, DEVMIN, DEVMAX, RADIUS, WAVEL, DELTA, DELTXY, DE, OTF, NS1, NS2, FN0, RMSMAX

Auxiliary Definitions

Variables which are common to the data-reduction and plotting programs and have been defined previously are not listed below unless a different symbol is used in the plotting program.

FORTRAN Variable	Description
BUFX(500)	Array of 500 consecutive words provided as work region for routine to process data
BUFXY (LENGTH)	Variable-sized array of words provided as work region for routine to process data
BUFY (500)	Array of 500 consecutive words provided as work region for routine to process data
DL(I)	Values of MTF for diffraction-limited lens with f-number equal to that of test lens
DY	Coordinate increment along y-axis
GIVEN(I)	Parameters specify maximum and minimum values of given x and y ordinate ranges and upper limit to number of scale subdivisions; used by subroutines to plot linear x and y-axes
LENGTH	Size of array BUFXY; LENGTH = 10,000 is recommended for present program
MTF(J,K)	Modulation transfer function
PHIMAX	Maximum value of PTF
PHIMIN	Mirimum value of PTF
PTF(J,K)	Phase transfer function
SPECS(I)	Array of values that specify construction parameters necessary to produce various plot components
SF(1)	Spatial frequency
SFCTOF	Spatial-frequency cut-off for diffraction- limited lens with f-number equal to that of test lens
x	x-coordinate of plotted values
XCONTR	Length (inches) of x-scale in plot of pupil- function phase

FORTRAN Description Variables difference XINCRE Incremental between plotted contour levels X1 x-coordinate of circular lens aperture Y y-coordinate of plotted values YCONTR Length (inches) of y-scale in plot of pupilfunction phase **Y1** y-coordinate of circular lens aperture Y2(I) Tangential MTF or tangential PTF Y3(I) Sagittal MTF or sagittal PTF Values of plotted contour levels

ZLEVEL(I)

Subroutines

A list of the subroutines used in this program is presented below.

FORTRAN Name	Called by	Function
PLOTPU	MAIN	Provide directives for plot of isocontour values of pupil-function phase
GDLILI	PLOTPU, PLTMOD	Construct rectangular grid having linear subdivisions of both axes
TITLET	PLOTPU, PLTMOD	Construct lines of text above plot
FABLIX	PLOTPU, PLTMOD	Determine linear scale for x-ordinate range
FABLIY	PLOTPU, PLTMOD	Determine linear scale for y- ordinate range
NODLIL	PLOTPU, PLYMOD	Construct linear numeric scale to left of plot
NODLIB	PLOTPU, PLTMOD	Construct linear numeric scale below plot
AXLILI	PLOTPU, PLTMOD	Construct pair of axes having linear subdivisions
TITLEB	PLOTPU, PLTMOD	Construct lines of text below plot
TITLEL	PLOTPU, PLTMOD	Construct lines of text to left of plot
PFLILI	PLOTPU, PLTMOD	Construct a trend curve through set of points in linear rectangular system
CONLI	PLOTPU, PLTMOD	Construct contour lines from rectangular grid of values
PLTMOD	MAIN	Provide directives for plots of MTF, PTF, and isocontour values
NXTFRM	PLTMOD	Initiate a new frame
GDSEND	PLTMOD	Terminate plotting

Computation Program Listing

CALL PLOTPU(DE, NS1, DELTA, DEVNAX, DEVNIN, RADIUS, NS2)

NSMAX-MAXO(NS1,NS2)

CALL PLIMOD(OTF, DELTXY, NSMAX, VAVEL, FNO, RMSMAX)

STOP

END

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THIS SUBROUTINE PROVIDES 1 PRINTER PLOT (FRAME) PLUS GENERATES
      C
      C
           PUPIL FUNCTION IS PLOTTED IN ACTUAL LENS COORDINATES
     C
           SUBROUTINE PLOTPU( DE, NS1, DELTA, DEVNAX, DEVNIN, RADIUS, NS2 )
           DIMENSION BUPX(500), BUFY(500), BUFXYZ(10000), DE(32,32), GIVEN(3),
          1 SPECS(35), X(32), X1(122), Y(32), Y1(122), ZLEVEL(10)
           WRITE( 6, 211)
       211 PORMAT( 1H1 * VALUES OF DE( I, K) FOR THE BEST FITTING WAVEFRONT ARE
          1PRINTED BELOW -1/// TERMS INVOLVING R(1), B(2), B(3), B(4) HAVE BEEN
         2 SUBTRACTED FROM DE VALUES!// ALSO, THE VALUE OF DE AT THE CENTE
         JR OF THE APERTURE HAS BEEN SUBTRACTED FROM THE DE VALUES!//! THESE
         4 DE VALUES SHOULD COMPARE EXACTLY WITH THE DE VALUES GENERATED BY
         STHE WAIN PROGRAM FOR REDUCING INTERFEROGRAMS AND! / TRANSFERRED TO
       66 FORMAT(1H 2X114X1217X1317X1417X1517X1617X1717X1817X1916X11016X111
     761 WRITE(6,68)K, (DE(I,K), I=2,17)
      68 FORWAT(1H 12, 1X16F8.3/)
         WRITE(6,69)
      69 FGRNAT(//1H 2X'J'3X'18'6X'19'6X'20'6X'21'6X'22'6X'23'6X'24'6X'25'6
        1x 26 6x 127 6x 128 6x 129 6x 130 6x 131 6x 132 6x 1331/1 KI)
     762 WRITE(6,68)K, (DE(I,K), I-18,33)
        SET UP COORDINATES, X1 AND Y1, FOR CIRCULAR LENS APERTURE IN SAME
  C
         SYSTEM AS COORDINATES FOR PUPIL PUNCTION TO BE PLOTTED, I.E.
  C
  C
        DY-(2. *RADIUS/60.0) - 0.001
        D-0
        D6 10 1-1.61
        Y1( %)-D
        Y1(E)-Y1(I)
        X1(1)=(RADIUS - SQRT(2.*RADIUS*D - D**2))
       X1(K)=(RADIUS + SQRT(2. *RADIUS*D - D**2))
    10 K-K-1
       DRAW A BOX AROUND THE PLOTTING AREA
       SET UP XDIST AND YDIST (IN INCHES)
       SPECS(1)=2.0
       SPECS( 2 ) -2.0
       SET UP XLENGTH AND YLENGTH (IN INCHES)
C
      SPECS(8)-5.50
      SET UP GRIDLESS CONTOURING AREA, XDIV AND YDIV -1
C
      SPECS( 10 )-1.
      SET UP PRINTING TOOL (ONLY ONE AVAILABLE AT NBS)
C
C
      SET UP TAPE NUMBER
      SPECS( 12 )-8.
     CALL COLILI( SPECS)
```

```
SET SPECS TO PRINT TITLE
       SPECS( 17 ) -. 2
       SPECS(18) -. 2
       SPECS(19)-0.0
        SPECS(21)-1.0
        RPECS( 25 )=0.75
       CALL TITLET(27HPHASE OF THE PUPIL PUNCTION, SPECS)
       SET UP X AND Y ARRAYS (LENS COORDINATES OF PUPIL-FUNCTION VALUES)
       D6 30 I-1,32
       X(I) = DELTA = (I-1)
    30 Y(I)-X(I)
        SET SPECS TO DETERMINE X,Y COORDINATES FOR A LINEAR SCALE.
        GIVEN(1)-2. + RADIUS
        GIVEN( 2)-0.0
        GIVEN(3)-6
        FALBLIX SETS SPECS(3), SPECS(4), AND SPECS(9).
        CALL FABLIX(GIVEN, SPECS)
        GIVEN(1)-2.*RADIUS
 C
        FABLIY SETS SPECS(5), SPECS(6), AND SPECS(10).
        CALL FABLIY(GIVEN, SPECS)
, C
        SET SPECS TO CONTRUCT NUMERICAL SCALES ALONG X AND Y AXES.
        SPECS( 17 )-0.15
        SPECS(18)=0.15
        SPECS( 20 )=0.0
        SPECS( 26 )-0.1
        SPECS(28)-0.0
        CALL NODLIL(SPECS)
        SPECS(24)-0.1
        CALL NODLIB( SPECS)
 C
        RESET THE NUMBER OF DIVISIONS FOR TICK MARKS
        SPECS(9)-2. + SPECS(9)
        SPECS(10)-2. + SPECS(10)
        CALL AXLILI(SPECS)
  C
        LABEL X AND Y AXES
        CALL TITLEB(6HX (NM), SPECS)
        CALL TITLEL(6HY (MM), SPECS)
        SET UP SPECS TO PLOT CIRCULAR LENS APERTURE
  C
        SPECS( 13 )-122
        SPECS( 14 )-1.
        SPECS( 15 )-1.
        CALL PFLILI(X1, Y1, BUFX, BUFY, SPECS)
        COMPUTE LEVELS AT WHICH CONTOURS ARE TO BE MADE
        XINCRE-(DEVMAX-DEVMIN) +.1
        ZLEVEL(1)-DEVMIN-XINCRE
        Dd 40 1-2,9
     40 ZLEVEL(I) - ZLEVEL(I-1) - XINCRE
        WRITE(6,8)
      8 FORMAT(//// CONTOUR LEVELS COMPUTED FOR THE PUPIL-PUNCTION PHASE(
       1DE) ARE -1/)
        WRITE(6,6) (ZLEVEL(1), I-1,9)
      6 FGRMAT(9F11.3)
```

```
C
      SET REMAINING SPECS NECESSARY FOR CONTOURING SUBROUTINE -
       (1) CONTOUR PLOTTING AREA AS MEASURED IN INCHES ON PLOT PAPER IS
C
          DETERMINED BY SPECS(7) AND SPECS(8)
C
       (2) ARRAY VALUES OF PUPIL-FUNCTION PHASE USED IN CONTOUR
          SUBROUTINE ARE LIMITED BY SPECS(4), SPECS(6), AND NEWLY
C
          COMPUTED VALUES OF SPECS(3) AND SPECS(5)
C
      ICONTR • (2. *RADIUS/SPECS(3)) *SPECS(7)
      SPECS(7) *XCONTR
      YCONTR - ( 2. *RADIUS/SPECS( 5 ) ) * SPECS( 8 )
      SPECS(8)-YCONTR
      RESET SPECS(3), SPECS(4), SPECS(5), AND SPECS(6)
      SPECS(3)-X(NS1)
      SPECS(4)-X(2)
      SPECS(5)-Y(NS2)
      SPECS(6)=Y(2)
      SET UP SCRATCH TAPE OR DRUM
C
      SPECS( 30 )-12.
C
      SET UP XCOLMS
      SPECS( 31 )-32.
C
      SET UP YROWS
      SPECS( 32 )- 32.
C
      SET UP NUMBER OF CONTOURS
      SPECS(33)-9.
      LENGTH -10000
      CALL THE CONTOURING SUBROUTINE
      CALL CONLI(X,Y,DE,ZLEVEL,BUFXYZ,LENGTH,SPECS)
```

100 RETURN END

```
THIS SUBROUTINE PROVIDES 5 PRINTER PLOTS (FRAMES) PLUS GENERATES
      CODE FOR CAL-COMP PLOTTER
      SUBROUTINE PLINED (OTF, DELTXY, NSMAX, WAVEL, FNG, RMSMAX)
      DIMENSION BUFX(500), BUFY(500), BUFXYZ(10000), DL(24), GIVEN(3),
     1 PTF(65,65), SF(24), SPECS(35), X(65), Y(65), Y2(32), Y3(32), ZLEVEL(10)
      COMPLEX STF(65,65)
      REAL MTF(65,65)
      COMPUTE CUTOFF SPATIAL PREQUENCY FOR DIFFRACTION-LIMITED CASE
      SFCTGF = 1.0/(WAVEL+FNG)
      THE FOLLOWING SPECIFICATIONS ARE COMMON TO THE REMAINING 4 PLOTS
      SET UP IDIST AND YDIST (INCHES)
      SPECS(1)=2.0
      SPECS(2)-2.0
      SET UP XLENGTH AND YLENGTH (INCHES)
      SPECS(7)-5.50
      SPECS(8)-5.50
      SET UP PRINTING TOOL
C
      SPECS( 11 )-1.0
      SET UP TAPE NUMBER
C
      SPECS(12)-8.0
      SET SPACER
      EPECS(19)-0.0
      SPECS(20)-0.0
      SET PONTNO
      SPECS(21)-1.0
      SET UP SCRATCH TAPE OR DRUM
      SPECS( 30 )-12.0
      ALTHOUGH SPECS(24), SPECS(25); AND SPECS(26) HAVE THE SAME VALUE
C
      FOR EACH FRAME, THESE SPECS MUST BE REPEATED PRIOR TO EACH FRAME-
OTHERWISE THEIR VALUES ARE INCREMENTED SUCCESSIVELY FROM THE
C
C
      INITIAL VALUE
C
      BEGIN COMPUTATIONS FOR PRAME 2 (ISOCONTOURS OF MIF)
C
      FIND MAXIMUM VALUE OF THE REAL PART OF THE OTF AND RECORD THE
C
       SUBSCRIPTS
      XM1 -0
      XN2-0
      DØ 10 K-1,65
       D6 10 J-1,65
       MTF( J, K) =0
       XM1 - AMAX1(XM1, REAL(GTF(J,K)))
       IP(XM1 .LE. XM2) G6 T6 10
       XM2-XM1
       JORD-J
       KORD-K
   10 CONTINUE
       CALCULATE NORMALIZED MTF
C
       DO 20 K-1.65
       D6 20 J-1,65
   20 MTF(J, K) - REAL(GTF(J, K)) / REAL(GTF(JGRD, KGRD))
C
       SET UP X AND Y ARRAYS
```

DØ 25 1-1,65

X(I)*(I-KORD)*DELTXY 25 Y(1)-Y(1) COMPUTE LEVELS AT WHICH CONTOURS ARE TO BE MADE C Z-0 D6 35 1-1.5 ZLEVEL(I)-Z*.1 35 Z-Z+.2 WRITE(6, 36) 36 FORMAT(//// CONTOUR LEVELS COMPUTED FOR THE MTF ARE -1/) WRITE(6, 37) (ZLEVEL(1), 1-1,5) 37 FORMAT(1X,6F10.3) CALL NXTFRM(SPECS) C SET UP GRIDLESS CONTOURING AREA, XDIV-YDIV-1 SPECS(9)-1. SPECS(10)-1. DRAW A BOX AROUND CONTOURING AREA C CALL GDLILI(SPECS) C SET UP XRIGHT AND XLEFT GIVEN(1)-SFCTOF GIVEN(2) -- 1. *SFCTOF GIVEN(3)-10 CALL FABLIX(GIVEN, SPECS) C . SET YTOP AND YBOTTON CALL PABLIY(GIVEN, SPECS) CONSTRUCT SCALE VALUES AT REGULAR INTERVALS ALONG THE AXES C SPECS(17)-.15 EPECS(18) .. 15 SPECS(28)-0.0 SPECS(26)=0.10 CALL NODLIL(SPECS) SPECS(24)-0.10 CALL NODLIB(SPECS) RESET THE NUMBER OF DIVISIONS FOR TICK MARKS **SPECS(9)=2.#SPECS(9)** SPECS(10)=2. + SPECS(10) CALL AXLILI(SPECS) SPECS(17) .. 2 SPECS(18) .. 2 SPECS(25)*0.75 CALL TITLET(28HOF OPTICAL TRANSFER FUNCTION, 7HMODULUS, SPECS) SPECS(17) -. 15 SPECS(18) -. 15 CALL TITLEB(29HSPATIAL FREQUENCY (CYCLES/MM), SPECS) CALL TITLEL (29 BSPATIAL FREQUENCY (CYCLES/NM), SPECS) SET UP XCOLMS C SPECS(31)-65. SET UP YROWS C SPECS(32) 65. SET UP NUMBER OF CONTOURS SPECS(33).5. LENGTH -10000

BEGIN COMPUTATIONS FOR FRAME 3 (ISOCONTOURS OF PTF)

CALL CONLI(X,Y,NTF,ZLEVEL,BUFXYZ,LENGTH,SPECS)

CALCULATE PTF RELATIVE TO VALUE AT MAXIMUM MTF

CALL THE CONTOURING SUBROUTINE

C

```
PHIMIN-0
      PHIMAX . O
      D6 55 K-1,65
      D6 55 J-1,65
      PTF( J, K) =0
      PTF(J, E) -AIMAG(GTF(J, E))-AIMAG(GTF(JGRD, EGRD))
      PHIMIN - AMINI (PHIMIN, PTF(J, K))
      PHIMAX - AMAX1(PHIMAX, PTF(J, K))
   55 CONTINUE
      COMPUTE CONTOUR LEVELS FOR THE PHASE PLOT
C
      XINCRE-(PHIMAX-PHIMIN)+.15
      ZLEVEL(1)-PHIMIN-XINCRE
      D6 30 I-2,6
      ZL -ZLEVEL( I-1 ) - XINCRE-AIMAG( GTF( JGRD, KGRD ) )
      IP(ABS(ZL) .LE. 1.0E-6) GO TO 28
      ZLEVEL( I )-ZLEVEL( I-1 ) *X INCRE
      GO TO 30
   28 ZLEVEL( I ) - ZLEVEL( I - 1 ) - 2 + XINC RE
   30 CONTINUE
      WRITE(6, 38)
   38 FORMAT(//// CONTOUR LEVELS COMPUTED FOR THE PTF ARE -1/)
      WRITE(6,37) (ZLEVEL(I), I-1,6)
      CALL NXTFRM( SPECS)
      SET UP GRIDLESS CONTOURING AREA
C
       SPECS( 9 )-1.
       SPECS( 10 )-1.
      CALL GDLILI(SPECS)
      CALL FABLIX(GIVEN, SPECS)
       CALL FABLIY(GIVEN, SPECS)
        SET UP NUMBER OF CONTOUR LEVELS TO BE PLOTTED
C
       SPECS( 33 )-6.0
       SPECS( 17 ) .. 15
       SPECS(18)-.15
       SPECS( 24 )-0.1
       CALL NODLIB( SPECS)
       SPECS( 26 )-0.1
       CALL NODLIL(SPECS)
       RESET THE NUMBER OF DIVISIONS FOR TICK MARKS
       SPECS(9) = 2. * SPFCS(9)
       SPECS(10)-2. - SPECS(10)
       CALL AXLILI(SPECS)
       SPECS(17) .. 2
       SPECS(18)-.2
       SPECS( 25 )-0.75
       CALL TITLET(28HOF OPTICAL TRANSFER FUNCTION, 5HPHASE, SPECS)
       SPECS( 17 ) -. 15
       SPECS(18)-.15
       CALL TITLEB(29HSPATIAL FREQUENCY (CYCLES/NN), SPECS)
       CALL TITLEL(29HSPATIAL FREQUENCY (CYCLES/NM), SPECS)
       CALL' CONLI(X,Y,PTF,ZLEVEL, BUFXYZ,LENGTH, SPECS)
       BEGIN COMPUTATIONS FOR FRAME 4 (MTF VS. SPATIAL PREQUENCY)
    75 JROW-JORD
       KCGL-KGRD
       NSMAX-NSMAX+2
       DO 80 1-1, NSMAX
```

```
Y3(I) PREAL( GTF( JGRD, ECGL))/REAL( GTF( JGRD, EGRD))
      X(I) - DELTXY + (I-1)
      JROW-JROW-1
   80 ECGL-ECGL-1
      CALL NXTFRM( SPECS)
C
      DETERMINE LINEAR SCALE FOR X AXIS
      GIVEN(1)-SFCTOP
      GIVEN(2)=0.0
      GIVEN(3)-10
      CALL FABLIX(GIVEN, SPECS)
C
      DETERMINE LINEAR SCALE FOR Y AXIS
      GIVEN(1)-Y2(1)
      GIVEN(2)-Y2(NSMAX)
      GIVEN(3)-6
      CALL FABLIY(GIVEN, SPECS)
C
      SET UP SPECS ARRAY TO PLOT TWO DIMENSIONAL MTP
      SPECS(13)-NSMAX
      SPECS( 14 )-1.
      SPECS( 15 )-1.
      CALL GDLILI(SPECS)
C
      SET FONTB AND FONTH
      SPECS( 17 )-. 15
      SPECS( 18 ) -. 15
      SPECS( 24 )=0.1
      CALL NODLIB( SPECS)
      SPECS( 26 )-0.1
      SPECS(28)-1.
      CALL NODLIL( SPECS)
      CALL TITLEB(29HSPATIAL FREQUENCY (CYCLES/NM), SPECS)
      CALL TITLEL(28HNGDULATION TRANSFER FUNCTION, SPECS)
C
      PLOT TANGENTIAL NTF
      CALL PFLILI(X, Y2, BUFX, BUFY, SPECS)
      SPECS(17)-0.2
      SPECS(18)-0.2
      EPECS(25)=0.75
      CALL TITLET( 32HOF THE OPTICAL TRANSFER FUNCTION, 31HTANGENTIAL AND
     1 SAGITTAL MODULUS, SPECS)
       SPECS(6) T3(NSMAX)
      PLOT SAGITTAL MTF
C
      CALL PFLILI(X, Y3, BUFX, BUFY, SPECS)
       IF( RMSMAX.GT. 2.00) GO TO 84
      BEGIN COMPUTATION FOR OPTIONAL FRAME (EXPANDED PLOT OF MTF VS.
       SPATIAL FREQUENCY) - THIS FRAME. IS PLOTTED FOR HIGHLY ABERRATED
C
C
       TEST LENS
       LIMIT-NSMAX
       D6 800 I-NSMAX,1,-1
       IF(Y2(1) .GT. 0.05) GC TO 800
      LIMIT-I
  800 CONTINUE
       CALL NXTFRM( SPECS)
       DETERMINE LINEAR SCALE FOR X AXIS
       GIVEN(1)-X(LIMIT)
       GIVEN( 2 )-0.0
       GIVEN(3)-10.
       CALL FABLIX(GIVEN, SPECS)
```

Y2(I) - REAL(GTF(JRdW, EGRD))/REAL(GTF(JGRD, EGRD))

```
C
      DETERMINE LINEAR SCALE FOR Y AXIS
      GIVEN(1)-Y2(1)
      GIVEN(2)-Y2(NSMAX)
      GIVEN(3)-6.
      CALL FABLIY(GIVEN, SPECS)
      SPECS(13)-LIMIT
      SET UP SPECS ARRAY TO PLOT TWO DIMENSIONAL MTF
      SPECS( 14 )-1.
      SPECS(15)-1.
      CALL GDLILI(SPECS)
      SET PONTE AND PONTE
      SPECS( 17 ) -. 15
      SPECS( 18 )-. 15
      SPECS(24)-0.1
      SPECS(28)-0.0
      CALL NODLIB( SPECS )
      SPECS( 26 )-0.1
      SPECS( 28 )-1.
      CALL NODLIL( SPECS)
      CALL TITLEB(29HSPATIAL FREQUENCY (CYCLES/NM), SPECS)
      CALL TITLEL(28HM6DULATION TRANSPER FUNCTION, SPECS)
      PLOT TANGENTIAL MTF
      CALL PFLILI(X, Y2, BUFX, BUFY, SPECS)
      SPECS( 17 )=0.2
    , SPECS(18)-0.2
      SPECS( 25 )=0.75
      CALL TITLET(3286F THE SPTICAL TRANSFER FUNCTION, 31 HTANGENTIAL AND
     1 SAGITTAL MODULUS, SPECS)
      SPECS(6) TY3(NSMAX)
      PLOT SAGITTAL NTF
      CALL PFLILI(X, Y3, BUFX, BUFY, SPECS).
   84 CONTINUE
C
      BEGIN COMPUTATIONS FOR FRAME 5 (DIFFRACTION-LIMITED MTF VS.
C
      SPATIAL FREQUENCY)
      ENTER DIFFRACTION-LIMITED MTF VALUES FOR FRAME 5
C
      SCURCE - L. LEVI AND R. AUSTING, APP. CPT. 7, 967(1968)
      DATA DL(1), DL(2), DL(3), DL(4), DL(5), DL(6), DL(7), DL(8), DL(9), DL(10),
     1DL(11), DL(12), DL(13), DL(14), DL(15), DL(16), DL(17), DL(18), DL(19), DL(
      220), DL(21), DL(22), DL(23), DL(24)/1.000, .936, .873, .810, .747, .685, .64
     34,.564,.505,.447,.391,.337,.285,.235,.188,.144,.104,.068,.037,.027
      4..017,.010,.003,.000/.SF(1),SF(2),SF(3),SF(4),SF(5),SF(6),SF(7),SF
      5(8), SF(9), SF(10), SF(11), SF(12), SF(13), SF(14), SF(15), SF(16), SF(17),
     6SF(18), SF(19), SF(20), SF(21), SF(22), SF(23), SF(24)/.00,.05,.10,.15,.
      720,.25,.30,.35,.40,.45,.50,.55,.60,.65,.70,.75,.80,.85,.90,.92,.94
      8,.96,.98,1.00/
       CONVERT NORMALIZED SPATIAL FREQUENCY TO VALUES WITH UNITS OF
       CYCLES/NN
       D6 85 I-1,24
   85 SF( I ) - SF( I ) + SFCT6F
       WRITE(6,86)SFCTOF
    86 FORMAT(/// CUTOFF FREQUENCY FOR DIFFRACTION-LIMITED PERFORMANCE I
      1S 'F8.2, 1X 'CYCLES/NX')
       CALL NXTFRM( SPECS)
 C
       USE SAME VALUES OF GIVEN AND SPECS AS THOSE USED FOR FRAME 4
```

EXCEPT WHERE NOTED OTHERWISE

```
GIVEN( 1 )-SF( 24 )
     GIVEN(2)-SF(1)
     GIVEN( 3)-10
     CALL FABLIX(GIVEN, SPECS)
     GIVEN( 1 )-DL( 1 )
     GIVEN(2)-DL(24)
     QIVEN(3)=6
     CALL FABLIY (GIVEN, SPECS)
      SPECS(13)-24
      CALL GDLILI(SPECS)
      SPECS( 17 )-. 15
      EPECS( 18 ) -. 15
      SPECS( 24 ) -. 1
      SPECS( 28 )-0.0
      CALL NODLIB(SPECS)
      SPECS( 26 )-.1
      SPECS(28)-1.0
      CALL NODLIL(SPECS)
      CALL TITLE B(29HSPATIAL FREQUENCY (CYCLES/NN), SPECS)
      CALL TITLEL (28HMODULATION TRANSFER FUNCTION, SPECS)
      CALL PFLILI(SF, DL, BUFY, BUFY, SPECS)
      SPECS( 17 )-0.2
      SPECS(18)-0.2
      SPECS( 25 )-0.75
      CALL TITLET(31HDIPFRACTION-LIMITED PERFORMANCE, 30H OPTICAL TRANSFE
     1R FUNCTION FOR 19H
                               MEDULUS OF THE SPECS)
      BEGIN COMPUTATIONS FOR FRAME 6 (PTF VS. SPATIAL FREQUENCY)
      RESET PARAMETERS TO PLOT TWO DIMENSIONAL PHASE
      JRCW-JCRD
      KCGL-KGRD
      PHIMIN- 0
      PHIMAX .O
      D6 90 I-1, NSMAX
      Y2(I) AIMAG(GTF(JROW, KORD)) - AIMAG(GTF(JORD, KORD))
      Y3(I) - AINAG(OTF(JORD, KCOL)) - AINAG(OTF(JORD, KORD))
      JRGW - JRGW - 1
      KCGL-KCGL-1
      PHININ-AMINI(PHININ, Y2(I), Y3(I))
   90 PHIMAX - AMAX1 (PHIMAX, Y2(I), Y3(I))
      CALL NXTFRM( SPECS)
      DETERMINE LINEAR SCALE FOR X AXIS
C
      GIVEN(1)-SFCTOF
      GIVEN(2)-0.0
      GIVEN(3)-10
      CALL FABLIX(GIVEN, SPECS)
C
      DETERMINE LINEAR SCALE FOR Y AXIS
      GIVEN(1) "PHIMAX
      GIVEN(2)-PHIMIN
      GIVEN(3)-6
      CALL FABLIY (GIVEN, SPECS)
      SPECS(13) - NSMAX
      CALL GDLILI(SPECS)
      SPECS( 25 )-0.75
      CALL TITLET( 32HOF THE OPTICAL TRANSFER FUNCTION, 29HTANGENTIAL AND
     1 SAGITTAL PHASE, SPECS)
      SPECS(17)-0.15
```

SPECS(18)=0.15
SPECS(26)=0.1
CALL NGDLIL(SPECS)
SPECS(24)=0.1
SPECS(28)=0.0
CALL NGDLIB(SPECS)
CALL TITLEB(29MSPATIAL FREQUENCY (CYCLES/MM),SPECS)
CALL TITLEL(29MBASE TRANSFER FUNCTION (RAD),SPECS)
CALL PFLILI(X,Y2,BUFX,BUFY,SPECS)
CALL PFLILI(X,Y3,BUFX,BUFY,SPECS)

C THIS IS LAST CALL IN GDS PLOTTING CALL GDSEND(SPECS)

NETURN
END

DELTA = 4.660 DELTXY = 7.399

RADIUS = 57.777 VAVELENGTH = .6326-03

DEVMIN = -.166 DEVMAX = .126

NSI = 26

NS = 26

HSM1: # LAMBDA/ 20.6

F/NUMBER

VALUES OF DE(1+K) FOR THE BEST FITTING MAVEFHONT ARE PRINTED BELOW -

THESE DE VALUES SMOULD COMPARE EXACTLY WITH THE DE VALUES GEMENATED BY THE MAIN PROGRAM FOR REDUCING INTERFERDGRAMS AND TRANSFERRED TO THIS PROGRAM BY A TAPE UNIT ALSO, THE VALUE OF DE AT THE CENTER OF THE APERTURE HAS BEEN SUBTRACTED FROM THE DE SALUES TERMS INVOLVING B(1).8(2).8(4) MAVE BEEN SUBTRACTED FROM DE VALUES

	• 000	125	151	107	133	115	1.001	080	064		036	023	010	016	017	1200-	026	030	031	020	023	013
4	• • • •	148	164	155	137	119	•60 •-	080	062	045	030	010	011	000	011	017	024	030	038	035	031	023
5	000.	154	166	155	136	117	097	078	020	1.00.1	620	613	008	100	*****	013	022	031	037	040	030	032
:	.000	147	158	149	135	113	095	076	057	039	022	010	002	000	+00	011	022	032	040	•••	5+0+1	
51	• 000	127	1	136	124	-108	160	₹0	036	039	023	011	***	005	005	013	024	034	043	6.0	052	190
12	• 000	095	122	123	-111	101		073	050	043	028	110	010		110	010	028	030	041	054	080	061
11	.000	150	093	104	102	095	085	074	062	6+0	037	027	021	010	120	027	035	0	08	060	066	072
•	.000	• • • • • •	056	190	088	087	063	076	068	059	049	1.0	035	033	034	038	0	150	0	066	07	
•	.000	.000	006	150	1.00-	079	001	000	075	069	063	050	160	040		050	054	050	046	074	084	007
•	.000	.000	.061	011	0.0	069	079	083	003	001	076	2.012	067	004	062	062	00+	040	078	00	096	112
•	••••	.000	.000	.048	017	053	073	085	060	100	000	086	083	079	9.0	075	075	070	00	095	110	-: 120
•	.000	.000	.000	.000	.032	020	062	083	095	100	102	100	160	093	080	007	••0••	••••	••••	107	123	140
10	.000	••••	000	.000	.000	.021	036	072	093	105	011	1111	108	104	100	090	1.007	100	101	1117	131	-1.1
•	.000	.000	.000	• • • • • • • • • • • • • • • • • • • •	•••	000	910.	042	078	100	111	115	119	112	100	109	8	106	110	117	121	•000
n	000	• 000	.000	• • • • • • • • • • • • • • • • • • • •	000	.000	.000	-026	035	072	050	105		-110	105	101	09	•• 0 • •	+00	• 000	000.	•
~	. 600	• 600	. 000			000	000	000.	.000	000	034	062	074	077	074	00.	000	000		13	000	.08
•	×	N	n	•	•	•	•	•	•	•	-	12	77	=	5	•	1.1	=	2	2	=	22

.001	.021	.056	• 000	• 000	• • • •	• 000	• 000	• • • •	• • • • • • • • • • • • • • • • • • • •	;	}		000	• 000	• 000	• 000	.000	• 000	. 000	.000	• • • •	.000	• 000	•000	• 000	• 000	•000	• • • •
110	• 005	.034	• • • •	000	• 000	• • • •	• • • • •	000	000.	ï	;	000	000	• 000	000	.000	• 000	.000	• • • •	.000	000.	000.	• 000	• 000	.000	• 000	.000	• • • • •
024	110	.012	• 062	000	.000	000.	••••	• • • • •	000	į	;	• • • • •	• 000	• 000	.000	• 000	.000	000.	• • • •	• • • •	• • • •	• 000	.000	• 000	• 000	.000	• • • •	• 000
037	028	010	.032	• • • • •	• • • •	• • • •	.000	• • • • •	• • • • • • • • • • • • • • • • • • • •	1	e e	000	000	• • • •	.000	• • • •	000.	• 000	• • • •	• • • •	• 000	• 000	• • • •	• 000	.000	000,	• 000	• 000
0.00	045	033	•00•	• • • •	• 000	• 000	• 000	• 000	000		S	.000	• • • •	• • • • •	.00	• • • • •	• 000	• 000	• • • •	• 000	.000	• 000	.000	• • • •	• 000	• • • •	.000	
063	• 00 • 1	056	023	.000	. 000	.000	• 000	• 000	000	1	92	• 000	• 000	• • • •	0000	.000	.000	• • • •	• • • • •	• 000	• • • •	• 000	.000	.000	.000	.000	.000	.000
078	083	640	• • • •	• • • • • •	• 000	• 000	• 000	• • • •	•		22	• 000	• • • •	• 000	•000	• 000	.000	• 000	.000	.000	.000	• 000	• 000	.000	• 000	• 000	.000	.000
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	123	120	.000	.000	.000	• 000	.000	. 000	•		2	• 000	• 000	• • • •	.000	.000	.000	. 000	• • • •	.10	.062	.032	.010	000	022	034	049	050
-129	141	000	000	000	.000	.000	.000	.000			54	.000	.000	• 000	000.	• • • •	.000	.126	.077	9.0.	.024	.000	003	012	020	027	032	037
149	151	000	000	• • • •	000	• • • •	000	.000	.000		6	• • • •	.000	• • • • •	.000	.000	.090	.040	.024	.010	100.	005	010	014	018	021	024	026
152	• 000	000	.000	• 000	000	• 000	.000	.000	.000		22	• 000	• 000	.000	• • • •	.052	.015	003	011	015	017	010	018	019	019	020	020	020
000	.000	000	000	•000	000	000	.000	.000	000		21	• 000	.000	000	.036	020	034	036	037	034	1:0	028	026	024	023	022	021	020
000	000	000	000	000	000	000	000	000	.000		92	.000	• 000	000	053	068	.060	063	056	640.	045	036	031	028	026	025	020	023
000	000	000	000	000	000	000	000	000	• • • •		9.	• • • •	000	078	100	100	092	080	069	058	048	000-	033	028	026	025	025	025
900	000	000		000	900	900	000	000	000		91	• • • •	• 000	124	130	121	- 106	160	077	063	050	039	031	025	022	022	024	027
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710	026	039	5.045	• • • •	000	.000	• 000	• • • • •	.000	• 000	• 000
011013	3 022	0.030	.000	.000	.000	. 000	• 000	000	• • • • •	000	.000
	010 8	.000	. 000	• 000	.000	• 000	• • • •	• • • •	• • • • •	• 000	000
.009 .012 .012	710. 3	• • • • •	000.	• 0 00	• 000	• • • • •	.000	000	• 000	• 000	• 000
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PIL-FUNCTION P	•
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COMPUTED P	101
CNTOUR LEVELS COMPUTED FOR THE PUPIL-FUNCTION PHASE(DE) ARE -	136

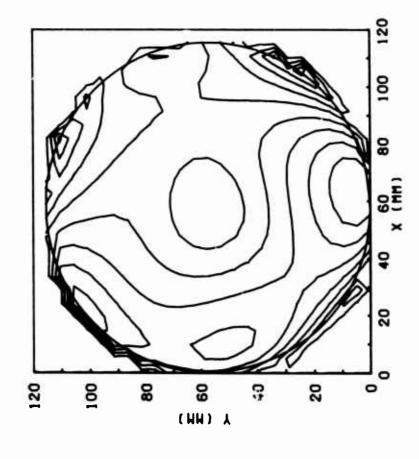
CENTOWN LEVELS COMPUTED FOR THE RTF AME --

CCMTQUA LEVELS COMPUTED FOR THE PTF AME --2-194 -1-254 --313 -627 1-567 2

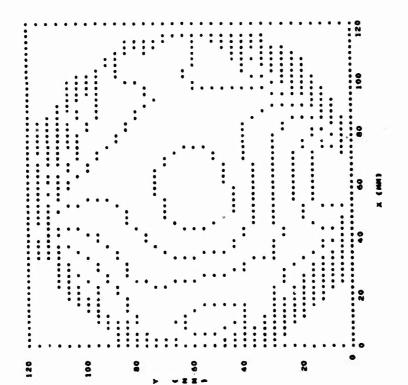
CUTOFF FREQUENCY FOR DIFFRACTION-LIMITED PERFORMANCE IS 182.69 CYCLES/MM

PHASE OF THE PUPIL FUNCTION

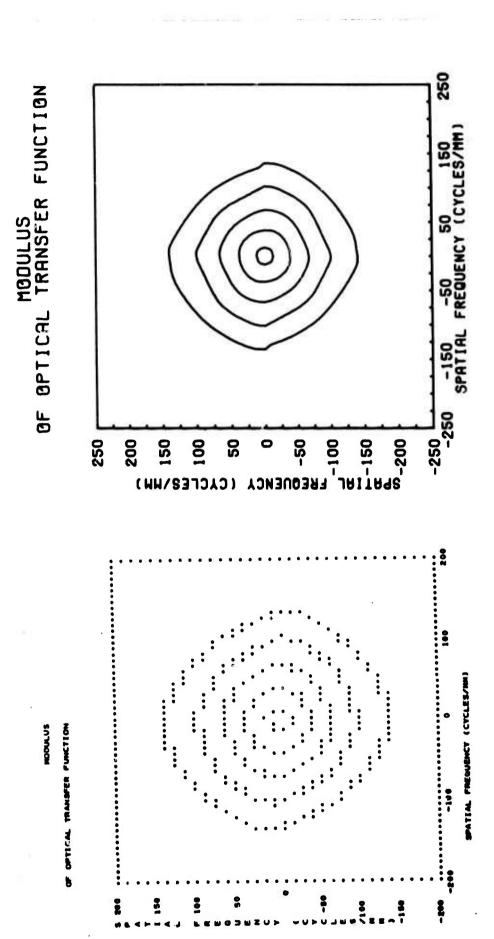
PHASE OF THE PUPIL FUNCTION



CALCOMP Plot

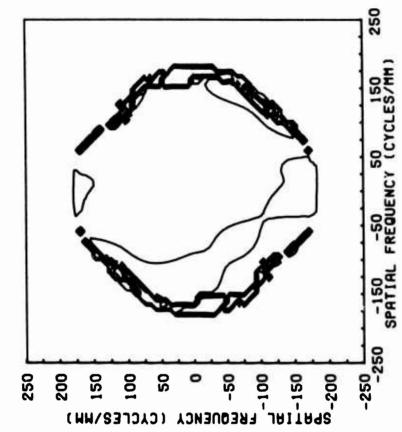


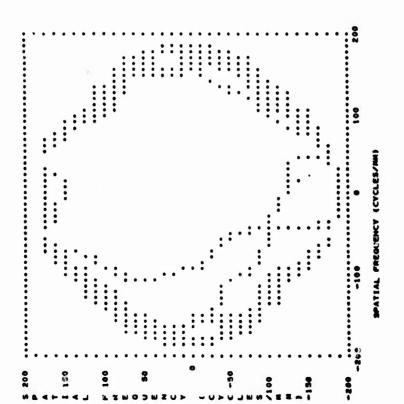
Printer Plot



CALCOMP Plot Printer Plot

PHASE OF OPTICAL TRANSFER FUNCTION PHASE OF OPTICAL TRANSFER FUNCTION



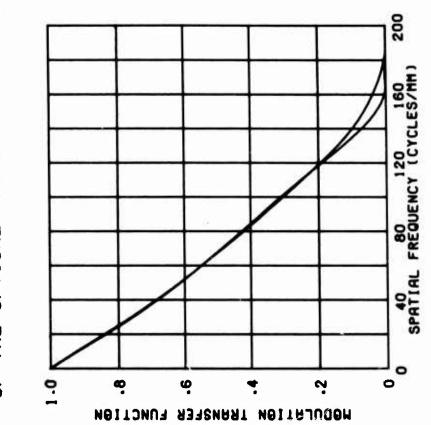


Printer Plot

CALCOMP Plot

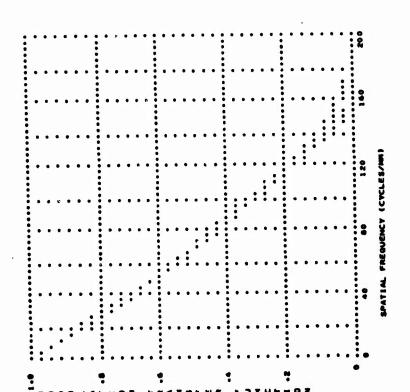
TANGENTIAL AND SAGITTAL MODULUS OF THE OPTICAL TRANSFER FUNCTION

TAMEENTIAL AND SAGITTAL MODULUS OF THE OFFICAL TRANSFER FUNCTION

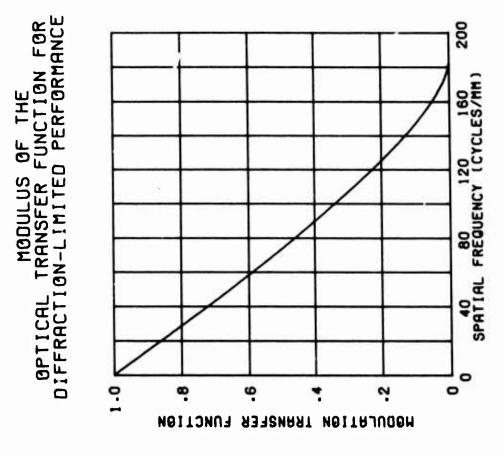


Printer Plot

CALCOMP Plot



DIFFRACTION-LIMITED PENFORMANCE OPTICAL TRANSFER FUNCTION FOR



CALCOMP Plot

Printer Plot

SPATIAL FREGUENCY (CYCLES/MM)

TANGENTIAL AND SAGITTAL PHASE OF THE OPTICAL TRANSFER FUNCTION

TANGENTIAL AND SAGITTAL PHASE OF THE OPTICAL TRANSFER FUNCTION 200 40 80 120 160 SPATIAL FREQUENCY (CYCLES/MM) TRANSFER FUNCTION (RAD) 2.0 32AH9 20 -3.0

CALCOMP Plot

Printer Plot

SPATIAL FREQUENCY (CYCLES/MM)

-3.0

APPENDIX C

COMPUTER PROGRAM TO OBTAIN WSI FRINGE DATA FROM AUTOMATIC-SCANNER DENSITY DATA

The computer program used to obtain fringe data from photographic-density data generated by automatic scanning of WSI interferograms is presented in part. The present version is neither a complete program nor a final version. This version consists of three subroutines that require the development of a main program by the user to read the density data and to call these subroutines; in addition, the user must already have available certain external subroutines for "unpacking" and reading density data stored on magnetic tape. The additional programming required depends on the particular scanning procedures and data format of the user's automatic scanner. Furthermore, the present version has been used very infrequently and may contain deficiencies which could be uncovered during extended usage.

The three subroutines are used to obtain fringe-peak coordinates, fringe-order numbers, and the coordinates of the test-lens aperture The basic input data are gray levels corresponding to density values generated on magnetic tape by automatic raster scanning with prepared interferogram transparencies microdensitometer. Since these subroutines involve the reading of magnetic tapes, alterations in some statements may be required in order to render the programming compatible with the user's computer Furthermore, these subroutines could be eliminated facilities. entirely in a computer-controlled scanning system with internal programming to determine the fringe and lens-aperture parameters required for the WSI data-reduction program.

The following description of each of the three subroutines includes a brief discussion of calculations, definitions of inputoutput arguments, and a listing of additional external subroutines required. A computational program listing for each subroutine is given. A sample printout resulting from a main computer program that uses the three subroutines to generate WSI fringe data is also presented. The subroutines assume the following: (1) one magnetictape file contains all the scans from one interferogram; (2) lens aperture is circular and unobscured; (3) a hole with a diameter roughly equal to a fringe width has been punched at both terminals of every fringe on the interferogram; and (4) one scan does not contain density data from more than one profile on the same fringe, i.e., closed or looped fringes cannot be treated.

A. Subroutine SEARCH

This subroutine locates the x and y coordinates of the center of the circular holes punched at the fringe terminals on interferogram. These holes serve to identify the fringe boundaries and the lens aperture. The subroutine first skips a selected number (NBORD) of density values at the beginning of each scan and then tests every other density value in order to locate zero values which may correspond to the punched holes. If the number of adjacent zero density values in less than a selected number (NCT), the location is considered to be noise, such as a film pinhole, and the search for the punched holes continues. Upon locating a punched hole from one scan, the density values from the next scan are tested to determine if part of the hole is also located along that next scan. This procedure continues until the extent of the hole is completely known. The search also continues on the other side of the hole since another hole may lie along these same scans. Eventually, all of the x and y coordinates (BOUNDX and BOUNDY) of the punched holes are determined.

Caution: The holes should be punched to follow closely the circular arcs of the lens aperture. Otherwise, the subroutine may miss one or more of these holes and thus, lead to an error in the ordering of fringes in the subroutine SORT.

If a device error (hardware, parity, or specification of illegal unit) occurs while reading the magnetic tapes in subroutines SEARCH and PEAKS, an error message (ERROR1) is printed and program execution stops. Furthermore, if an end-of-file mark is encountered before the physical end of the file, an error message (ERROR9) is printed and program execution stops. Therefore, the user should ideally use new magnetic tape for recording density values, and the tape transport unit used to transfer data from the scanner to the tape should be in good working condition.

FORTRAN Variable	Source	Definitions
NS	input	Total number of scans; in present version, every other scan is used (this may be altered to fit needs of user)
ND	input	Number of density values in each scan
NBORD	input	Number of density values skipped at beginning of each scan
NBUF	input	Density value; accessed through subroutine SUNPAC
BOUNDX	output	Average x-coordinate of center of punched hole denoting fringe terminus
BOUNDY	output	Average y-coordinate of center of punched hole denoting fringe terminus

FORTRAN

Variable Source

Definition

LL

output

Total number of punched holes

The following list of external subroutines called by SEARCH must be provided by the user; a computational listing of those subroutines as used at the NBS is not available for the present report.

FKCE	rnal	subrout1	ne
and	argum	ents	

Function

NTRAN (8, 7, N)

Position tape by skipping N records (scans)

NTRAN (8, 2, N, IWORD, L)

Reads N words from tape into array IWORD

NTRAN (8, 22)

Assures that all previous operations on tape unit are completed before returning control to user; this feature allows programs to be swapped in multiprogrammed computer system

NTRAN (8, 24)

Allows a record (scan) which has incomplete words to be read without stopping on an error; the automatic scanner used in the present report generates an incomplete word at the end

of each record

SUNPAC (IWORD, NBUF, NW)

Unpacks density values from every other word on tape; one density value is put into one storage location of array NBUF

B. Subroutine SORT

This subroutine associates the punched-hole coordinates (BOUNDX and BOUNDY) with the proper fringes and assigns fringe-order numbers. As noted earlier, the punched-hole coordinates obtained from subroutine SEARCH locate the fringe terminals as well as the test-lens aperture boundary. It is assumed in SORT that all punched holes located above the center of the frame (interferogram) denote the top of a fringe and those located blow the frame center denote the bottom of a fringe. The fringes are assigned increasing order numbers in the direction of increasing x-coordinate (BOUNDX) of the punched holes.

FORTRAN Variable	Source	Definition
NS	input	Total number of scans from interferogram
BOUNDX	input	See SEARCH
BOUNDY	input	See SEARCH
LL	input	See SEARCH
J2	output	Total number of fringes

No external subroutines are used by SORT.

C. Subroutine PEAKS

This subroutine determines the fringe-peak locations which are the basic input data for the WSI data-reduction computer program. subroutine starts by curvefitting two circular arcs to the x and ycoordinates (BOUNDX and BOUNDY) of the punched holes; one arc is fit to the coordinates on the left side of the frame (interferogram), and the other arc is fit to the coordinates on the right side of the The x and y-coordinates of the center and the radius of each of these arcs is determined, and their average values are used as the center coordinates and radius for a circular aperture of the test lens. From this circular aperture, the boundaries (LIMLOW and LIMUP) for fringe scanning are set. Three scans are then read consecutively, and their density values are averaged. An approximate fringe peak (AVG) is located, and this resulting fringe profile is autoconvolved to give a far more accurate location (PKS) of the fringe peak. the fringe order associated with each peak is determined by finding the coordinates of the nearest punched hole. In addition, the fringes are checked by comparing adjacent fringe peaks with the first set of fringe peaks. Finally, cards are punched that contain the fringe-peak coordinates required for the WSI data-reduction program. appendix A.) Values of the radius (RAD) of the test-lens aperture and the parameters NF1 or NF2, NSX or NSY, CX or CY, and POSY or POSY are determined in this subroutine; these values are also required for the WSI data-reduction program.

This subroutine also uses a set of subroutines, termed the Graphical Display System, to produce one plot on both a computer line printer and an incremental pen-and-ink device. (See appendix B.) The plots show two circular apertures and the location of their centers; each circle is an extension of the circular arcs discussed above. The location of the fringe peaks (PKS) and the punched holes (BOUNDX and BOUNDY) are also plotted. Examples of both types of plots are included in the sample printout.

Caution: If holes are punched too far outside of the lens aperture, the aperture boundary may be interpreted as fringe peaks by this subroutine, particularly if diffraction fringes are significant. In an effort to reduce this possibility, the subroutine discards apparent fringe peaks which lie outside of the circular aperture determined from curvefitting of the punched-hole coordinates.

FORTRAN Variable	Source	Definition
variable	bource	Delatite
ND	input	See SEARCH
Ј2	input	See SORT
IDELTA	input	Number of scans contained within shear distance as measured on interferogram, i.e., shear distance/scan raster
PKS	output (printout and punched cards)	<pre>x-coordinates (x-sheared interferogram) or y-coordinates (y-sheared interferogram) of fringe peaks</pre>
NS	input	See SORT
BOUNDX	input	See SEARCH
BOUNDY	input	See SEARCH
TEST1	input	Identifies test lens and test number or date
TEST2	input	Identifies frame, i.e., x-sheared or y-sheared
I FRAME	input	Identifies frame IFRAME = 1 for x-sheared interferogram IFRAME = 2 for y-sheared interferogram

The following list of external subroutines called by PEAKS must be provided by the user. Some of these subroutines are similiar to those listed previously for SEARCH.

External subroutine and arguments	Function								
NTRAN (8, 7, NSKIP)	See SEARCH								
UNPACK (IWORD, NBUF1, ND)	Same as SUNPAC in SEARCH except that density values are unpacked from every other word on tape								
NTRAN (8, 2, 750, IWORD, L)	See SEARCH								

External subroutine and arguments	Function
NTRAN (8, 22)	See SEARCH
NTRAN (8, 24)	See SEARCH
GJR*	Solve simultaneous equations by method of Gauss-Jordan Elimination (See reference 39.)
FABLIX (GIVEN, SPECS)	Determine linear scale for x-ordinate range
FABLIY (GIVEN, SPECS)	Determine linear scale for y-ordinate range
GDLILI (SPECS)	Construct rectangular grid having linear subdivisions of both axes
NODLIB (SPECS)	Construct linear numeric scale below plot
TITLEB*	Construct lines of text below plot
NODLIL (SPECS)	Construct linear numeric scale to left of plot
TITEL*	Construct lines of text to left of plot
TITLET*	Construct lines of text above plot
PSLILI*	Plot data with symbols in linear rectangular system
PFLILI*	Construct a trend curve through set of points in linear rectangular system
GDSEND (SPECS)	Terminate plotting

^{*} The arguments for these subroutines are either lengthy or vary throughout program. Note computation program listing for details.

Computation Program Listing

```
C
      THIS SUBROUTINE LOCATES COORDINATES OF BOUNDARY MARKS
      BOUNDARY MARKS ARE HOLES IN THE PILM WHICH REGISTER GRAY LEVELS
      OF ZERG. A COUNT IS MADE OF THE NUMBER OF ADJACENT ZERGES.
      COUNT OF LESS THAN FIVE IS CONSIDERED NOISE. THE AVERAGE VALUE OF
      THE X AND Y COORDINATES ARE STORED IN BOUNDY AND BOUNDY AS THE
      CENTER OF THE HOLE. THE REMAINING LOOPS IN THE PROGRAM INSURE THAT
      THE ENTIRE FRAME IS SEARCHED.
      SUBMOUTINE SEARCH( NS, ND, NBORD, NBUF, BOUNDY, BOUNDY, LL)
      CALL NTRAN(8, 24, 22)
      DIMENSION BOUNDX(100), BOUNDY(100), IWORD(750), NBUF(3000)
      WRITE(6,800)
  800 FORMAT(1H1 THE FOLLOWING VALUES INCLUDE X AND Y COORDINATES OF PUN
     1 CHED HOLES IN SAME ORDER AS FOUND BY THIS SUBROUTINE -1///)
      MA . ND
      M-1
      NAREA-1
      MRET-0
      LL-0
      LF .O
      MLIM-NS
      JEIN-1
      ND-ND/2
       JMAX -ND-NBGRD
       J-1
   10 CALL NTRAN(8,7,1)
       CALL NTRAN(8, 2, 750, IWORD, L, 22)
       CALL NTRAN(8,22)
       IF(L+1)12, 14, 14
   12 IF(L.EQ. -2)G6 T6 558
       STOP ERRORI
   14 M-X+1
       CALL SUNPAC( IWORD, NBUF, NW)
   15 IF(NBUF(J).LT.1) GO TO 20
   16 J-J-1
       IF(J.LT. JNAX )GO TO 15
       J-JHIN
   17 IF(M.LT.MLIM) GG TG 10
       IF( N. GE. NS ) GO TO 900
       WRITE(6,906)NAREA
   18 GG TG (900, 140, 150, 150), NAREA
  · 20 IF(J.LT.NBGRD) GG TG 16
       NCT-1
       NSCAN-M
       SUNX - J
       SUNY-M
       JMIN-J
    22 J-J-1
       IF(NBUF(J).GE.1) GO TO 25
       NCT-NCT-1
       SUNX -SUNX +J
       SUNY-SUNY .M
       GG TG 22
    25 JMAX-J
    26 KSW-0
    30 CALL NTRAN(8,7,1)
       CALL NTRAN(8, 2, 750, IWGRD, L, 22)
```

CALL NTRAN(8,22)

```
IF(L+1)32,33,33
32 IF( L. EQ. -2 )GO TO 998
   STOP ERRORI
33 M-M-1
   J-JMIN
   CALL SUNPAC( INGRD, NBUF, NW)
34 IF(NBUF(J).GE.1) Gd Td 35
   IF(J.LF.1) G6 T6 35
    J-J-1
    G6 T6 34
35 IF(JMIN. LE. J)G6 T6 36
    JHIN-J
36 J-J-1
    IF(NBUF(J).GE.1) G6 T6 38
    NCT-NCT-1
    SUMX -SUMX -J
    SUNY - SUNY - M
    KSW-1
    GØ TØ 36
 36 IF(J.LT. JNAX )G6 T6 36
     JKAX "J
 40 IF(KSW.NE. 1)GG TG 42
     G6 T6 26
 42 GO TO (45, 50, 60, 70), NAREA
  45 NB . NSCAN - M
     JMXR - JMIN-1
     JENR - NBORD
     MRET-NSCAN
     MXR = M
     MLIN . M
     JMIN - JMAX . 1
     JMAX - ND. - NBORD
     M - NSCAN -1
      NAREA . 2
      NB-2+NB
      CALL NTRAN(8,7,NB)
      G6 T6 100
   50 IF (MXR - M) 56,54,54
   54 NB-NSCAN-M-1
      NB-S-NB
      CALL NTRAN(8,7,NB)
       JMIN-JMAX-1
       JMAX = ND - NBGRD
       M-NSCAN -1
       NLIN-NXR
       NAREA"2
       G6 T6 100
    56 NB-NSCAN-N-1
       NB-2-NB
       CALL NTRAN(8,7,NB)
       MXR-M
       IF(JMIN .LT. JMXR) JMXR=JMIN-1
       JMIN-JMAX+1
       JMAX - ND - NBGRD
       MLIN-N
        M-NSCAN -1
        NAREA"2
        G6 T6 100
```

60 IF(WLIN - N) 66,64,62 62 NB-NSCAN-M -1 NB-2+NB CALL NTRAN(8,7,NB) JMAX - JMIN-1 JMIN-NBORD M-NSCAN -1 NAREA-3 G6 T6 100 64 NB-NSCAN-M-1 NB-2+NB CALL NTRAN(8,7,NB) JMAX-JMIN-1 JMIN-NBORD MLIN-M M-NSCAN -1 NAREA-3 GØ TØ 100 66 JMXR-JMIN-1 JKIN-JHAX-1 JMAX-ND-NBGRD NB-MLIM-M NB-2+NB CALL NTRAN(8,7,NB) JMNR-NBGRD MRET-NSC AN NAREA-2 MXR-M MXX-MLIM MLIM-M XXX°M G6 T6 100 70 IF (MLIM - M)76,74,72 72 NB-NSCAN-M-1 NB-2+NB CALL NTRAN(8,7,NB) JMIN-JMAX+1 JMAX-ND-NBGRD M-NSCAN -1 NAREA-4 G6 T6 100 74 NB-NSCAN-M -1 NB-2+NB CALL NTPAN(8,7,NB) JMIN-JMAX+1 JMAX-ND-NBORD MLIN-M M-NSCAN -1 NAREA-4 G6 T6 100 76 NB-NSCAN-N -1 NR-2+NB CALL NTRAN(8,7,NB) JMNR - NBORD JMXR-JMIN-1 MRET-MLIM MXR -N

JMIN-JMAX+1

```
JWAX - ND - NBGRD
   MLIN-M
    H-NSCAN -1
100 IF( NCT. LT. 10 ) G6 T6 120
110 LL-LL-1
     BOUNDX(LL) - SUNX/NCT
     BOUNDY(LL) - SUNY/NCT
     BOUNDX(LL)=2+BOUNDX(LL)
     BOUNDY(LL) = 2 + HOUNDY(LL)
     WRITE(6,903)BOUNDX(LL), ROUNDY(LL)
     WRITE(6,907)LL
      WRITE( 6, 906 )NAREA
      WRITE( 6, 908 )NSCAN
  120 J-JMIN
      G6 T6 17
  140 NAREA - 3
       JHIN - JHNR
       JNAX - JWXR
       M - MRET -1
       NB - MLIN - MRET *1
        NB-2+NB
        CALL NTRAN (8,7,-NB)
        G6 T6 10
    150 NAREA - 1
        J-NBORD
         WRITE(6, 906) NAREA
         JUIN - NBORD
         JMAX - ND - NBORD
     900 WFITE(6, 901 INS, ND
901 FORMAT(///1H THIS FRAME USED - 114, 1 SCANS EACH CONTAINING 114, 1
      $04 FORMAT(1H1 THE COORDINATES OF THE BOUNDARY MARKS BEFORE ORDERING A
          THE GIVEN BELOW -1///)
           SUNX-0.0
           SUMY . 0.0
           D6 202 J-1,IL
            SUNX -SUNX . BOUNDX(J)
      .202 SUMY SUMY BOUNDY(J)
            SUNX SUNX/LL
            SUNY SUNY/LL
        204 SUNR*SUNR*(BOUNDX(J)-SUNX)**2*(BOUNDY(J)-SUNY)**2
         205 RR SQRT((BOUNDX(J)-SUMX)++2+(BOUNDY(J)-SUMY)++2)
             SUMP SORT (SUMP/LL) +0.85
             IF(RR.LT.SUMR. GR. RR. GT. (1.4+SUMR))G6 T6 210
              GØ TØ 216
          210 Jd-J-1
              D6 212 K.Je.LL
               BOUNDX(K-1)-BOUNDX(K)
          212 BOUNDY(K-1)-BOUNDY(K)
               LL-LL-1
               WRITE(6, 214)
```

```
214 FdRMAT(1HO, 'PGINT DRGPPED')
GG TG 205
216 CGNTINUE
WRITE(6, 903)(BGUNDX(J), BGUNDY(J), J=1, LL)
903 FGRMAT(1H 'X = 'F8.2,10X'Y = 'F8.2/)
ND=NW
906 FGRMAT(1H 'NAREA = 'IA/) =
907 FGRMAT(1H 'NAREA = 'IA/)
908 FGRMAT(1H 'NSCAN = 'IA///)
GG TG 999
998 WRITE(6, 950)
950 FGRMAT(1X, 'THIS IS ERRGR NINE')
ND=M
GG TG 900
999 RETURN
END
```

```
THIS SUBROUTINE ORDERS THE BOUNDARY MARKS THEREBY ASSIGNING ORDER
      NUMBERS TO THE FRINCES. IT IS ASSUMED THAT ALL BOUNDARY MARKS ABOVE TH
Ç
      CENTER OF THE FRAME ARE AT THE BEGINNING OF A FRINGE AND THOSE IN THE
C
C
      BOTTOM BALF ARE AT THE END OF A FRINGE. BOUNDARY MARKS IN THE TOP
      AND BOTTOM RESPECTIVELY ARE ORDERED IN INCREASING VALUES OF X.
      SUBROUTINE SORT(NS. BOUNDY, BOUNDY, LL.J2)
      DIMENSION BOUNDX(100), BOUNDY(100)
      1-0
      THALF-0
      D6 2 K-1, LL
    2 YHALF .YHALF . BOUNDY (K)
      YHALF-YHALF/LL
    3 J-J-1
      IF(BOUNDX(J+1).LT.BOUNDX(J)) GO TO 12
    6 IF( BOUNDY( J.2 ). LT. YHALF ) GO TO 3
      G6 T6 20
   12 STOPE-BOUNDX(J-1)
      BOUNDX(J+1)=BOUNDX(J)
      BOUNDX(J) STORE
      STORE-BOUNDY(J-1)
      BOUNDY(J+1) - BOUNDY(J)
      BOUNDY( J ) - STORE
      IP(J.LE. 1 1G# T# 3
      K-J-1
   14 IF(BOUNDX(K+1).LT.BOUNDX(K))GO TO 15
      G6 T6 6
   15 STORE-ROUNDX(K-1)
      BOUNDX(K+1)=BOUNDX(K)
      BOUNDX(K)-STORE
      STORE-BOUNDY(K+1)
      BOUNDY(K+1)-BOUNDY(K)
      BOUNDY( K )- STORE
      IF(K.LE. 1) G# T# 6
      K-K-1
      GØ TØ 14
   20 J2 J+2
      J-J+1
   23 J-J-1
      IF(BdUNDX(J+1), LT. BdUNDX(J))G6 T6 32
   26 IF(J+1.LT.LL) GG TG 23
      G6 T6 40
   32 STORE BOUNDX(J+1)
       BOUNDX(J+1)-BOUNDX(J)
       BOUNDX(J)-STORE
       STORE - BOUNDY (J+1)
       BOUNDY(J+1) = BOUNDY(J)
       BOUNDY(J)-STORE
       IF(J.LE. J2)G6 T6 23
       K-J-1
   34 IF(BOUNDX(K+1), LT. BOUNDX(K))GO TO 35
       G6 T6 26
   35 STORE .BOUNDX(K.1)
       BOUNDX(K+1) BOUNDX(K)
       BOUNDX(K) STORE
       STOPE-BOUNDY(K-1)
       BOUNDY(K+1)=BOUNDY(K)
       BOUNDY ( K ) STORE
```

IF(K.LE.J2)Gd T6 26 K-K-1 GG T6 34 40 J2-J2-1 WRITE(6,50)J2

50 FORMAT(181 BOUNDARIES, OR COORDINATES OF PUNCHED HOLES, FOR "13,"

1 FRINGES ARE GIVEN BELOW - 1//3x BOUNDX(J) 6x BOUNDY(J) 41x BOUNDX(
2J+J2) 4x BOUNDY(J+J2) 1)

WRITE(6, 52)(ROUNDX(J), BOUNDY(J), BOUNDX(J+J2), BOUNDY(J+J2), J-1,J2)

52 FGRMAT(1HO, F7.2, 10X, F7.2, 45X, F7.2, 10X, F7.2)
RETURN
BND

```
THIS SUBROUTINE FINDS AND CHECKS FRINGE PEAKS
      USES AVERAGING OF 9 POINTS TO SMOOTH DATA
      SUBROUTINE PEAKS(ND, J2, IDELTA, PKS, NS, BOUNDX, BOUNDY, TEST1, TEST2,
     21FRAME)
      CALL NTRAN(8, 24, 22)
      DIMENSION NBUF1 (3000), NBUF2 (3000), NBUF3 (3000), AVG (3000), PKS (60,60)
      DIMENSION BOUNDX(50), BOUNDY(50), AUTO(200), NPK(50), I WORD(750)
      DIMENSION NCNT(50)
      DIMENSION FNC(50), YLY(50)
      DIMENSION SPECS(30), GIVEN(3)
      DIMENSION XIXI(50), XIX2(50)
      DIMENSION XC(2), YC(2), BUFX(500), BUFY(500), X1(122), Y1(122)
      DIMENSION AZ(3,4), V(4), JC(4)
      DIMENSION TEST1(6), TEST2(2)
      THE FOLLOWING INSTRUCTIONS DIVIDE THE INTERPEROGRAM INTO TWO ARCS
C
      AND COMPUTE THE CENTERS AND RADII OF EACH
      V(1)+5
      XC1 -0.0
      YC1 . 0. 0
      R1-0.0
      XC2-0.0
      YC2-0.0
      R2-0.0
      NZ-0
      NH-0
      IHALF=J2/2
      DØ 500 K-1,4
      DØ 500 J-1,3
  500 AZ(J,K)=0.0
      D6 8 I-1.J2
      J-1
      IF( 1.GT. THALF ) J * I * I HALF
    7 IF(BOUNDX(J) .LT. 0.0001) NZ-NZ-1
       IF(BOUNDX(J) .LT. 0.0001) GO TO 8
       AZ(1,1) = AZ(1,1) + BOUNDX(J)
       AZ(1,2)*AZ(1,2)*BGUNDY(J)
       AZ(1,3)*AZ(1,3)*1
       AZ(2,1) AZ(2,1) BOUNDX(J) +2
       AZ(2,2) * AZ(2,2) * BOUNDX(J) * BOUNDY(J)
       AZ(2,4)*AZ(2,4)*BOUNDX(J)**3*BOUNDX(J)*BOUNDY(J)**2
       AZ(3,2)*AZ(3,2)*BGUNDY(J)**2
       AZ(3,4)=AZ(3,4)+BdUNDX(J)++2+BdUNDY(J)+BdUNDY(J)++3
    8 CONTINUE
       A.Z.(1,4) - A.Z.(2,1) + A.Z.(3,2)
       AZ(2,3)=AZ(1,1)
       AZ(3,1) AZ(2,2)
       AZ(3,3)-AZ(1,2)
       CALL GJR(AZ, 4, 3, 3, 4, $998, JC, V)
       XC1 - AZ(1,4)/2.0
       YC1 - AZ(2,4)/2.0
       P1 * SORT( AZ(3, 4) * XC1 * + 2 * YC1 * + 2)
       XCIMN*XCI*.05
       YCIMM-YCI+.05
       R1 MM - R1 + . 05
       WRITE(6, 36) XC1, YC1, R1, XC1MM, YC1MM, R1MM
    36 FORMAT(1H1 COORDINATES FOR LEFT ARC ARE - 1//1X1 XCENTER = 1F10.4.
```

```
110X YCENTER - F10.4,10X RADIUS - F10.4//1X XCENTER - F10.4,4
   2MM 7X YCENTER - 'F10.4, ' MM 7X RADIUS - 'F10.4, ' MM' //)
    NH-J2 - IHALF
    NZ =0
    D6 510 K-1.4
    DO 510 J-1,3
510 AZ(J,K)=0.0
    V(1)*5
    D6 13 I-1, J2
    J-I . IHALF
    IF(I.GT. IHALF) J.I.J2
 11 IF(BOUNDX(J) .LT. 0.0001) NZ NZ . 1
    IF( ROUNDX( J) . LT. 0.0001 ) GO TO 13
    AZ(1,1) AZ(1,1) BOUNDX(J)
    AZ(1,2) AZ(1,2) BOUNDY(J)
    AZ(1,3)*AZ(1,3)*1
    AZ(2,1)*AZ(2,1)*BGUNDX(J)**2
    AZ(2,2) * AZ(2,2) * BOUNDX(J) * BOUNDY(J)
    AZ(2,4) * AZ(2,4) * BOUNDX(J) * * 3 * BOUNDX(J) * BOUNDY(J) * * 2
    AZ(3,2) AZ(3,2) BOUNDY(J) +2
    AZ(3,4)=AZ(3,4)+BOUNDX(J)++2+BOUNDY(J)+BOUNDY(J)++3
 13 CONTINUE
    AZ(1,4)-AZ(2,1)-AZ(3,2)
    AZ(2,3) AZ(1,1)
    AZ(3,1) AZ(2,2)
    AZ(3,3) AZ(1,2)
    CALL GJR(AZ, 4, 3, 3, 4, $998, JC, V)
    XC2 AZ(1,4)/2.0
    YC2-AZ(2,4)/2.0
    R2 * SQRT( AZ(3,4) * XC2 * * 2 * YC2 * * 2)
    XC2NN=XC2+.
    YCZNN-YC2+.05
    R2MM*R2*.05
    WRITE(6,37) XC2, YC2, R2, XC2NN, YC2NN, R2MN
 37 FORMAT(1HO COORDINATES FOR RIGHT ARC ARE -1//1X1 XCENTER - 1F10.4
   1,10X'YCENTER - 'F10.4,10X'RADIUS - 'F10.4//1X' XCENTER - 'F10.4,'
   2 MM 7X YCENTER - 'F10.4, ' MM 7X 'RADIUS - 'F10.4, ' MM 1//)
     SHEAR - ABS(XC1MM - XC2MM)
    DISPLT - ABS (YC1MM - YC2MM)
    WRITE(6, 38) SHEAR, DISPLT
 38 FORMAT(////1 H SHEAP - FIO. 4. 5X THIS VALUE SHOULD BE EQUAL OR CLO
   1 SE TO SHEAR VALUE AS MEASURED ON INTERPEROGRAM 1//1H IDISPLT - 1F10
   2.4,5X THIS VALUE SHOULD EQUAL OR BE CLOSE TO ZERO 1//)
     SUNXI = XCIMM . RIMM
     SUNX2ºXC2MM * R2MM
     SUNY1-YCIMM . RINN
     SUMY2ºYCZMM . RZMM
     AWAXX - ANAX1 (SUNX1, SUNX2)
     AMAXY - AMAX1 (SUMY1, SUMY2)
     De 300 J-1,J2
     BOUNDX(J) * 0.05 * BOUNDX(J)
     HOUNDY(J)=0.05# ROUNDY(J)
     BOUNDX(J+J2)=0.05+BOUNDX(J+J2)
     Rdundy(J+J2)=0.05# Bdundy(J+J2)
300 CONTINUE
     WRITE(6, 320)J2
320 FORNAT(1H1 BOUNDARIES, OR COURDINATES OF PUNCHED HOLES, IN MM FOR
```

```
1 13. FRINGES ARE GIVEN BELOW - 1//1X BOUNDX(J) 8X BOUNDY(J) 41X BO
   2UNDX(J*J2) 4X 1 ROUNDY(J*J2) 1)
    WRITE(6, 321)(BOUNDX(J), BOUNDY(J), BOUNDX(J*J2), BOUNDY(J*J2), J*1, J2)
321 FORMAT(1HO, F7.2, 10X, F7.2, 45X, F7.2, 10X, F7.2)
    GIVEN(1) AMAXX
    GIVEN(2)-0.0
    GIVEN(3)-20.0
    CALL FABLIX (GIVEN, SPECS)
    GIVEN(1) AMAXY
    GIVEN(2)=0.0
    GIVEN(3)-20.0
    CALL FABLIY(GIVEN, SPECS)
    SPECS( 1 ) -0.75
    SPECS(2)=0.5
    SPECS(8) 9.00
     SPECS(7) - SPECS(3)/(SPECS(5)/SPECS(8))
    SPECS( 11 )-1.0
     SPECS( 12 )-10.0
    CALL GDLILI(SPECS)
    SPECS( 17 )*0.10
     SPECS(18)-0.10
    SPECS( 19 )-0.0
     SPECS(21)-1.0
     SPECS( 24 )*0.1
     SPECS( 28 ) = 0.0
     CALL NODLIB( SPECS)
     SPECS( 24 )=0. 25
     CALL TITLEB(6HX (MM), SPECS)
     SPECS( 26 )-0.1
     CALL NODLIL(SPECS)
     SPECS(26).0.25
     CALL TITLEL(6HY (MM), SPECS)
     SPECS( 25 )*0.2
     IF(IFRANE .EQ. 2) GO TO 325
     CALL TITLET(7HX SHEAR, SPECS)
     GO TO 328
325 CALL TITLET(7HY SHEAR, SPECS)
328 CONTINUE
     SPECS( 25 )*0.6
     SPECS( 17 )-0.20
     SPECS(18)*0.20
     CALL TITLET(53HNAP OF WSI INTERFEROGRAM SCANNED BY AUTOMATIC SCANN
    1ER, SPECS)
     SPECS(13)-2.+J2
     SPECS( 14 )-1.0
     SPECS(15)-1.0
     SPECS( 16 )-1.0
     SPECS(17)-0.10
     SPECS( 18 )*0.10
     CALL PSLILI(BOUNDX, HOUNDY, SPECS)
     DO 330 J-1.J2
     BOUNDX(J)-BOUNDX(J)/0.05
     BOUNDY(J)-BOUNDY(J)/0.05
     BOUNDX(J+J2)-BOUNDX(J+J2)/0.05
```

330 BOUNDY(J.J2)-HOUNDY(J.J2)/0.05

```
PLOT CENTERS OF LEFT AND RIGHT ARCS WHICH HAVE BEEN PIT TO PUNCHED
C
      BOLES AND PLOT CIRCLES ABOUT EACH CENTER
C
      XC(1) -XCINM
      TC( 1 )-YCINH
      XC(2)-XC2MM
      AC( 5 ) - ACSMM
       SPECS( 13 )-2.0
       SPECS( 16 )-14.
       CALL PSLILI(XC, YC, SPECS)
       DY-(2.+#1MM/60.0)-0.001
       K-122
       D-YCINH-RINN
       D6 400 I-1.61
       Y1( I )-D
       Y1(K)-Y1(I)
       ARG - RIMM+2 + 2.+D+YC1MM - YC1MM++2 - D++2
       ARG1 - ABS( ARG )
       X1(I)=XC1MM + SORT(ARG1)
       X1(K)-XC1MM - SORT(ARG1)
       D. D. DY
   400 K-K-1
       SPECS( 13 )= 122
       CALL PFLILI(X1,Y1, BUFY, BUFY, SPECS)
       DY = ( 2. +R2MM/60.0)-0.001
        K-122
        D-ACSMR-BSMR
      . D6 401 I=1,61
        Y1(1)-D
        Y1(K)-Y1(I)
        ARG - R2MM++2 + 2.+D+YC2MM - YC2MM++2 - D++2
        ARG1 - ABS( ARG )
        X1(I)-XC2NN . SORT(ARG1)
        X1(K)-XC2NN - SORT(ARG1)
        D-D-DY
    401 K-K-1
         SPECS( 13 )= 122
        CALL PFLILI(X1,Y1, BUFX, BUFY, SPECS)
         COMPUTE STANDARD DEVIATION OF FIT RADIALLY
  C
         NZ-0
         IHALF-J2/2
         88-0.0
         De 77 I-1. IHALP
         J-1
       6 IF(BOUNDX(J) .LT. 0.0001) NZ-NZ * 1
         IF(BGUNDX(J) .LT. 0.0001) G6 T6 77
         CR = (BdUNDX(J) - XC1) + 2 + (BdUNDY(J) - YC1) + 2
         CR-SQRT( CR )
         H3 - ( CR - R1 )++2
         ss-ss . H3
         IF(J .GT. I) G6 T6 77
         J-I . J2
          GO TO 6
      77 CONTINUE
          IHALF - IHALF . 1
          D6 9 I . IHALF, J2
          J-I
        4 IF(Boundx(J) .LT. 0.0001) NZ-NZ + 1
```

```
IF( BOUNDX( J) .LT. 0.0001 ) GO TO 9
   CR = (BGUNDX(J) - XC2) + +2 = (BGUNDY(J) - YC1) + +2
   CR-SQRT( CR )
   H3 * ( CR - R2 ) ++ 2
   68-88- R3
   IF(J .GT. I) G6 T6 9
   J-1 . J2
   GO TO 4
 9 CONTINUE
   69-55/(2+J2 - NZ)
   ESMM - SS+0.05
   WRITE(6,2) SS, SSMM
 2 FORMAT(////1X THE STANDARD DEVIATION OF FITTING ALL THE PUNCHED
  1 HOLE COORDINATES TO TWO ARCS IS 'F8.3, GR 'F8.3, MM'//)
   IRAD*(R1 * R2)/2.0
    IDIFF-R1 . R2
    IK-(YC1 . YC2)/2.0
    IHALF-J2/2
    K-IDIFF/IDELTA
    NSKIP*(IDIFF-K*IDELTA)/2
    IDELT4 - I DELTA/4
    IF(NSKIP .LT. IDELT4) NSKIP*NSKIP * IDELTA
    LIWUP-IK-IRAD-NSKIP
    LIMLOW-IK-IRAD+NSKIP
    D6 5 J-1,60
    D6 5 K-1.60
 5 PKS(J, K)=0
    WRITE(6,71)
71 FORMAT(1H1)
    NEXT SMOOTH DATA BY AVERAGING
    NSKIP-LIMLOW-1
    CALL NTRAN(8,7,NSKIP)
    NSKIP-IDELTA-3
    NSS-0
    DO 200 LY-LINLOW, LINUP, IDELTA
    NSS-NSS-1
    IX1 =XC1 - SQRT((0.985 *R1) **2 -(LY-IK) **2)
    IX2*XC2*SQRT((0.985*R2)**2*(LY*IK)**2)
    WRITE( 6, 811 )NSS
811 FORMAT(////1X'SCAN NO. 12)
    WRITE(6,81) LY, IX1, IX2
 B1 FORMAT(//1X'Y - '15,8X'X1 - '15,8X'X2 - '15)
    XIX1(NSS)*0.05*IX1
    X1X2(NSS) *0.05 * IX2
    YLY( NSS) *0.05*LY
    WRITE(6, 82)YLY(NSS), XIX1(NSS), XIX2(NSS)
 82 FORMAT(/1X'Y - 1F7.2, MM13X'X1 - 1F7.2, MM13X'X2 - 1F7.2, MM1)
    WRITE(6,73)
 73 FORMAT(///1X PEAK ! . !
                               KO',
                                       CENTER!,
                                                    CENTER( MM ) 1)
 10 CALL NTRAN(8, 2, 750, IWGRD, L)
    CALL NTPAN(8,22)
    IF(L+1)12, 14, 14
 12 IF( L. EQ. -2 )GØ TØ 998
    STOP ERRORI
 14 M-M-1
    CALL UNPACK(IWORD, NBUFI, ND)
 20 CALL NTRAN(8, 2,750, IWORD, L, 22)
```

```
CALL NTRAN(8,22)
   IF( L+1 )22, 24, 24
22 IF(L.En. -2) G6 T6 998
   STOP ERRORI
24 M-W-1
   CALL UNPACK( IWGRD, NBUF2, ND)
30 CALL NTRAN(8,2,750, IWORD, L,22)-
   CALL NTRAN(8,22)
   IF(L-1)32,34,34
32 IF(L.EQ. -2)G6 T6 998
   STOP ERRORI
34 M-M-1
   CALL UNPACK(IWORD, NBUF3, ND)
   JFRWD-0
   KP-0
   NCCUNT-0
   JWAX - 0
   DØ 50 J-1X1, IX2
   AVG(J)=(NBUF1(J-1)+NBUF1(J)+NBUF1(J+1)+NBUF2(J-1)+NBUF2(J)+NBUF2(J)
  2+1) * NBUF3(J-1') * NBUF3(J) * NBUF3(J+1)]/9
   IP(J .LT. JFRWD) GO TO 50
   IF(JMAX .NE. 0) GG TG 42
 * IF(AVG(J) .LT. AVG(J-1)) JMAX-J-1
   G6 T6 50
42 IF(AVG(J) .LT. AVG(J-1)) NCGUNT-NCGUNT-1
   IF(NCCUNT .EQ. 5) GG TG 43
   IF(AVG(J) .GT. AVG(J-1)) G6 T6 44
   GØ TØ 50
43 KP*KP*1
   NPK(KP)-JMAX
   JFRWD-JMAX + I DELTA/2
44 NCGUNT-0
   JMAX - 0
50 CONTINUE
   DETERMINE POSITION OF PEAKS
   D6 80 1-1, KP
   JMIN-NPE(I)-(IDELTA/2)
   JMAX-NPK(I)+(IDELTA/2)
   IF(I .EQ. KP .AND. IX2 .LT. JMAX) JMAX=IX2
   IF(I .EO. 1 .AND. IX1 .GT. JMIN) JMIN *IX1
   LIN-2+(JMAX-JMIN)+1
   AWXX-0
   K0-0
   D6 75 11-1, LIN
   K-11-(JMAX-JMIN+1)
   IF(K .GT. 0) GG TG 60
   JL-JHIN
   JU-JNAX . K
   G6 T6 65
60 JL-JHIN-K
   JU -J MAX
65 A-0
   De 72 12-JL, JU
72 A-A.AVG( 12 )+AVG( JU-12-JL)
    AUTO( E1 )-A
    IF(AUTG(II) .GE. AMXX) KO-II
75 AMXX -AMAX1 (AUTO(II), AMXX)
    K-KO-(JMAX-JMIN-1)
```

C

```
NCNT(I)=(JMAX+JMIN)/2 +K
   FNC( I )=0.05*NCNT( I )
   WRITE(6,85) NPK(1), K, NCNT(1), FNC(1)
85 FORMAT(1X, 3(15, 2X), 2(F10.2))
   YLY( I ) -Y LY( NSS)
80 CONTINUE
   SPECS( 13 )-1.0+KP
   SPECS(16)-3.0
    SPECS( 17 )-0.1
    SPECS( 18 )-0.1
   CALL PSLILI(FNC, YLY, SPECS)
   CALL NTRAN(8,7,NSKIP)
   THE FOLLOWING INSTRUCTION DETERMINE THE FRINGE ORDER ASSOCIATED
   WITH EACH PEAK
   NB-J2-1
   D6 150 IJ-1, KP
   De 100 JY = 2, NB
   DIFF1 - ABS( BOUNDX(JY-1)-NCNT( J))
    IF(NSS .EQ. 1) G6 T6 87
    IF(PKS(JY, NSS-1) . NE. O)DIFF1-ABS(PKS(JY, NSS-1)-NCNT(IJ))
67 CONTINUE
    IF(DIFF1 .NE. ABS(PKS(JY,NSS-1)-NCNT(IJ)) .AND. DIFF1 .GT. IDELTA/
   12) GO TO 100
    IF(DIFF1 .GT. (IDELTA/2)) GO TO 100
   IF(PKS(JY, NSS) .EO. 0) GO TO 90
    IF( NSS . EQ. 1) DIFF2-ABS( BOUNDX( JY-1 )-PKS( JY, NSS))
    IF(NSS .GT. 1) DIFF2-ABS(PKS(JY,NSS-1)-PKS(JY,NSS))
    DIFF3 - ABS( DIFF2-DIFF1 )
    IF(DIFF1 .LT. DIFF3) G6 T6 90
    IF(DIFF2 .LT. DIFF3) G6 T6 100
    PKS(JY, NSS) - (PKS(JY, NSS) + NCNT(IJ))/2.0
    G6 T6 100
90 PKS(JY, NSS) NCNT(IJ)
    IF(PKS(JY-1, NSS) .NE. PKS(JY, NSS)) G6 T6 100
    IF(NSS . EO. 1 . 6R. PKS(JY-1, NSS-1) . EQ. 0) GO TO 98
    DIFF2 ABS(PKS(JY-1, NSS-1) -NCNT(IJ);
    GØ TØ 99
98 DIFF2 - ABS( BOUNDX(JY-2) -NCNT(IJ))
 99 CONTINUE
    IF( DIFF1 .LT. DIFF2 ) PKS(JY-1,NSS)-0
    IF(DIFF1 .GT. DIFF2) PKS(JY, NSS)=0
100 CONTINUE
150 CONTINUE
200 CONTINUE
    D6 170 I-1,NSS
    D6 168 J-2, NB
168 PKS(J, I) *PKS(J, I) *. 05
170 CONTINUE
    WRITE(6,71)
    CX - ( XC1 - IRAD )+0.05
    PMSX -( LIMLOW -( IK-IRAD) )+.05
    RAD* IRAD*. 05
    IF( IFRAME . EQ. 2) GO TO 225
WRITE(6,212) J2,NSS,CX,PGSX,RAD
212 FGRMAT(1H1 J2 (NF1) - 13//1 NSS (NSX) - 13//1 CX - 1P8.3//1 PGSX
   1 - 1F8.3//1 RADIUS - 1F8.3///////////
```

```
Of T6 226
225 WPITE(6, 224)J2, NSS, CX, PGSX, RAD
224 FGRMAT(1H1 J2 (NF2) - 13//1 NSS (NSY) - 13//1 CY - 1F8.3//1 PGSY
   1 • 'F8.3//' RADIUS • 'F8.3//////////
226 WRITE(6,213)
213 FORMAT(1H | FRINGE-PEAK POSITIONS PES(J.K) RESULTING FROM AUTOMATIC
   1 SCANNING ARE PRINTED BELOW - 1/1 J - FRINGE NUMBER 5X1K - SCAN NU
   2MBER 1//)
    WRITE(6, 214)
214 FORMAT(1H 3X1J13X1117X1217X1317X1417X1517X1617X1717X1817X1916X1101
   16X 111 16X 112 16X 113 16X 114 16X 115 16X 116 1/1 K1)
    D6 215 K-1,29
215 WRITE(6,216)K,(PKS(J,K),J=1,16)
216 FORMAT(1H 12,1X16F8.3)
    WRITE(6, 217)
217 FORNAT(//1H 3X'J'2X'17'6X'18'6X'19'6X'20'6X'21'6X'22'6X'23'6X'24'6
   1X12516X12616X12716X12816X1291/1 K1)
    D6 218 K-1,29
218 WRITE(6,216)K,(PKS(J,K),J-17,29)
    WRITE(1, 209)((PKS(J,K),J=1,8),K=1,NSS)
    WRITE(1, 209)((PKS(J,K), J=9,16), K=1, NSS)
    WRITE(1, 209)((PKS(J, K), J-17, 24), K-1, NSS)
    WRITE(1, 209)((PKS(J,K), J=25, 30), K=1, NSS)
220 FORMAT(7X,7F7.2)
209 FORMAT(8F7.2)
205 FORMAT(16F7.2)
203 FORMAT(2110, F10.2)
210 FGRNAT(2F10.2)
    CALL GDSEND( SPECS'
    PETURN
998 STOP ERRORS
    END
```

THE POLLOWING DATA WERE ORNERATED PROM AUTOMATIC BCANNING OF

T-SEEARED INTERFERENCEAN OF

P/8.7 COLLINATOR A

THE POLLOWING OUTSTITIES ARE IMPUT VALUES -

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	on • • • • • • • • • • • • • • • • • • •	7.72		89 ° 88	·
			; ;	6 •	
THE POLLOWING VALUES	N 1 1035.88 NAZEA - 2 NGCAN - 6	EL . 2 X - 1108.66 MAREA . 2 MBCAN . 8	LL • 3 X • 1184.68 MAREA • 2 MBCAN • 16	LL - 4 X - 1262.06 MAREA - 2	NGCAN 24

X - 955.63

NSCAN .

NAREA .

X - 877.63 MSCÁN - 16 HAREA - 3

11 - 11

X . 802.32 HAREA . 2 MACAN . 27

X - 1345.87 HANEA - 2 NECAN - 36

MAREA - 2

MAREA - 2 MBCAN - 44 X - 720.43

Tr - 10

T - 124.78

X - 1425.24 NAREA - 2 MBCAN - 56

T - 137.32				163.01		•			166.34							222.14					T - 247.68
				• >				,								• •					· ·
LL - 11 X - 642.61	MAREA . 2	NSCAN . 63	TT - 15	X . 1499.48	NAREA . 2	MSCAN - 75	HAREA . 2	11 - 13	X - 565.67	NAREA . 2	NSCAN . 88	HAREA . 2	NAPEA . 3	NAREA . 1	11 - 14	X = 1573,37	NAREA - 2	MSCAN . 105	NAREA . 2	LL • 15	400.79

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MAREA .	MSCAW - 118	HAREA	NAPEA .	NAREA .	91 - 77	X - 1653.	MAREA .	MECAN . 1	HAREA .	11 . 11	X - 411.	HAREA -	MECAN . 1	WAPEA .	MAREA .	NAREA .	11 - 10	X - 1726.	MAREA .	MSCAM . 1	HAREA -	LL • 19

X - 339.42 Y - 390.5

NSCAN - 189

MAREA - 3

NAREA .

WAREA . 1

LL - 20 X - 1810.92

MAREA . 2

MAREA . 2

LL • 21 X • 260.43

T - 519.91

NAREA - 254

MAREA .

MAREA .

LL - 22 X - 1665.62

T . 696.70

NSCAN - 342

NAREA - 2

NAREA .

MAREA " 3
LL " 23
T " 1051.00
T " MAREA " 2
MSCAN " 051

MAREA - 2

MAREA - 3

MAREA - 1

[L - 24

X - 266.34

T - 13

MAREA - 2

MSCAW - 674

MAREA - 2

MAREA - 3

MAREA - 1

LL - 25

X - 1779.80

Y - 1435.19

MAREA - 2

MSCAN - 712

X . 343.12

MAREA - 2 MAREA - 3 MAREA - 1 LL - 27 X - 1706.41

MAREA . 2

T - 1530.12

MARKA . 2

NECAN - 759

MAREA " 3 MAREA " 1 LL " 28 X " 417.47

MAREA . 2

T . 1588.29

LL * 29 X * 1630,42 NAREA * 2

T . 1610.12

NSCAN - 798

NAREA .

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MAREA	MSCAN
	MAREA - 2

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MSCAM - 860

MAREA . 3 . L. . 3 . L. . 3 .

MAREA -MAREA -MAREA -

N - 651.52 7 - 1763.74 NARBA - 2 NBCAN - 876

LL = 35 X = 1400.06 Y = 1772.35 NAREA = 2 NSCAN = 880 HAREA * 2

NAREA * 1

LL * 36

X * 725.00

Y * 1797.96

NAREA * 2

NACAN * 895

LL = 37 X = 1324.33 YAREA = 2 NSCAN = 896 MAREA " 3

MAREA " 1

LL = 30

X = 601.74

T = 1628.89

MAPEA - 2 MSCAN - 911 LL • 39 X • 1238.77 Y • 1836.51 MAREA • 2

MSCAM - 912

MAREA • 2 MAREA • 3 MAREA • 1

LL - 40 X - 948.97 MAREA - 2

MAREA - 2 MSCAM - 926 LL - 41 X - 1027,40

T - 1862.73

MAPEA . 2 MSCAN . 926 LL - 42 X - 1091.54 MAREA - 2

T . 1865.41

HBCAN . 926

T . 1859.60

X - 1164.58

NSCAN . 926 NAREA .

HAREA .

NAREA . NAMEA .

THIS FRAME URED . 1050 BCANS EACH CONTAINING 1050 DENBITY VALUES

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23.50	27.71	44.10	56.95	30.90	44.67	66.32		60.03	124.70	137,32	163.01	108.34	222.14	247.66	296.09	315.91	366.13	390.58	510.98	519.91	696.70	1314.53	1359.74	1435.19	1496.34	1530.12
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1860.35 T . 1859.60 Y = 1862.73 T. . 1865.41 1626.69 T - 1836.51 T . 1772.35 T - 1797.96 T .- 1805.50 1733.50 T - 1763.74 T - 1685.83 T - 1719.14 1610.12 T . 1665.82 T - 1566.29 901.74 X - 1091.54 X - 1164.58 X - 1027.40 X - 1238.77 948.97 651.52 X - 1324.33 X - 725.00 575.91 497.47 x - 1473.68 X - 1400.06 417.47 .X - 1545.69 X - 1630.42

BOW DARIES.	BRUNDARIES, OR CHORDINATES OF PUNCIED BOLES,	POR 22 PRIN	22 PRINGES ARE GIVEN BELOW -	
Betweek 5)	Bounds ()		BOUNDX(J-75)	BOUNDY(J-J2)
260.43	519.01		266.34	1350.74
339.42	99096		343.12	1496.34
411.14	315.01		417.47	1500.29
440.79	247.68		497.47	1665.82
565.67	100.34		575.91	1719.14
642.61	137.32		651.52	1763.74
720.43	F - 00		725.00	1757.96
802.32	66.32		801.74	1828.89
677.63	44.67		40.07	1860.35
955.63	30.90		1027.40	1662.73
1 034 .48	23.50		1091.54	1065.41
1108.66	. 27.71		1164.58	1859.60
1184.68			. 1230.77	1636.51
1262.06	. 50.05		1324.33	1805.50
1345.87	00.08		1 400.06	1772.35
1425.24	124.70		1473.68	1733.58
1499.48	163.01		1545.69	1685.83
1573.37	222.14		1630.42	1610.12
1653.04	296.09		1700.41	1530.12
1726.31	366.13		1779.80	1435.19
1810.92	510.00		1051.00	1314.53
1 865.62	696.70		00.	00.

RADIUS - 922.4545 RADIUS - 46.1227 MM	RADIUS - 923,8361 BADIUS - 46,1919 KM
RADI	PADI
<i>,</i>	3
946.5886 47,3294 ER	944.5528 47.2276 MM
TCENTER - 046.5004 4CENTER - 47.3294	TCBHTER - 944.5520 TCBHTER - 47.2276
	. 884 0
SCENTER • 1082-6129 SCENTER • 54-1306 MM	707 FOR RIGHT AR 996.0717
CCONTER . 1082.6129 ICENTER . 54.1306 MM	COGRDINATES FOR RIGHT ARC ARE " RCENTER " 996.0717

THIS VALUE SECULD BE EQUAL OR CLOSE TO SEEAR VALUE AS MEASURED ON INTERPRESORAL THIS VALUE REGULD BOWAL OR DE CLOSE TO ZERO .1018 4, 3271 DISPLT . SEEAR .

BOUNDARIES.	BOUNDARIES, OR COCRDINATES OF PUNCEED ROLES, IN MM POR	22 PRINCES ARE CIVEN BELOW	
BOUNDA(J)	BOUNDY(J)	B6070X(J-J2)	BOUNDY(J- J2)
13.02	26.00	13.32	64.00
. 16.97	19.53	17.10	74.62
20.56	15.60	20.67	79.41
24.54		24.67	83.29
28.28	5.42	28.80	96.50
32.13	6.87	32.58	•::•
36.02	90.4	36.28	00.60
40.12	3,3%	60.04	01.00
43.89	2.23	47.45	. 63.02
47.70	48.0	61.37	63.14
51.72	9:10	94.58	93.27
55.43	1.10	88. kg	92.90
59.23	2.21	96.19	61.63
63.10	0°6	66.22	90.20
67.29	4.48	70.00	88.62
71.26	6.24	73.68	96.00
74.97	0.15	77.28	84.29
78.67	11.11	81.52	80.51
92.65	14.60	85.42	76.51
86.32	16.31	66.00	71.76
90.55	25.55	92.55	65.73
64.28	34.84	00.	•

57	Ħ	•	066	2	•	X2 - 1194
2.85 100	Ħ	•	44.50 KM	2	•	59.7

CENTER NA	45.40	47.95	51.90	95.60	59.05
CENTER	800	989	1036	1112	1181
K0	•	•	0	0	0
PEAL	069	625	1038	1112	1196

		1402	70.
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8 8 8 9 9 9 9 9 9	•	678	33.90 KK
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		=	6.55 m
1112	SCAN HO.	131	
1112	5	-	-

EAK	4		
678	50	716	35.60
721	0	721	36.05
707	-	196	39.80
875	•	875	5.2
957	7	986	47.80
1040	ï	1039	51.95
1112	•	1112	55.60
1152	1	1188	59.40
1265	•	1269	63.45
1340	•	1349	67.45

1625	76.25 M	
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5.55	27.75 NK	CENTEM NE) 28.10 31.85
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	47.60			59.60			67.80		•				23.20 KK	CENTER KIK)	84.00		31.15		38.85	•	•					60.00		•	71.95	
	9.52		1113	-	•	m	1356	•	4					CENTER	0	553	623	100	111	962	. 246	086	1030	1112	1140	1200	1282	1361	1436	
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SCAF F6. 6

T - 427 II - 336 II - 1744 T - 21,35 IM II - 16,04 IM II - 87,20 III

336 -26 330 16.50
396 -2 354 10.70
462 -3 459 22.95
523 -4 525 26.45
608 -3 605 30.25
609 -6 604 34.20
1026 -1 1025 42.65
1119 -5 1114 55.70
1272 0 1372 66.60
1372 0 1452 72.60
1528 1 1525 76.45
1671 -1 1670 83.50
1732 2 3 1742 83.50

20 CENTER CE 50 M20 M20 M20 M20 M20 M20 M20 M20 M20 M2	CENTER ME)		•			26.05	•	34.10	•					•	•			•	•		87.10
000000000000000000000000000000000000000	8	327	323	380	451	521	869	289	763	946	635	1024	112	1208	1531	1376	1457	1534	1612	1678	1742
	2	0,7	?	5	0	••		~	-	~	m	ņ	•		•	•	n		•	0	ŗ

. 1827	• 91.35 KK	. ′																
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282	12.60 KM	CENTER KK)	12.35	15.60	ė	22,35	25.85	29.80	•	37.65	41.95	46.60	51.10	g,	9	•	68.95	0
		CENTER	247	312	375	447	517	296	673	753	639	¢ 32	1022	1115	1210	1256	1379	1461
575	26.75 104		-23	,	•	•	•			:	:	-	•	:	-5	:	-5	•
		PEAK	282	312	380	F. 4 4	517	598	676	757	843	931	1026	1116	21	1257	1361	1461

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SCAN N6. 10

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1676	63.80
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723	36.15
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CENTER CENTER(MM; 219 10.95

> PEAK 201

242 -2 240 12.00
299 3 302 15.10
290 1 367 15.10
369 -1 435 25.45
569 -1 587 20.35
568 -1 587 20.35
568 -1 741 37.05
742 -1 741 37.05
931 -7 924 50.85
1027 -4 1110 55.80
1120 -4 1110 55.80
11214 -3 1211 65.00
1391 -2 1389 65.00
1362 4 1626 86.80
1622 4 1626 86.80
1764 0 1764 98.20
1764 -1 1626 98.20

T = 797 XI = 106 XZ = 1803 Y = 39.05 MX XI = 9.30 MX XZ = 94.65 MX

PEAK EO CENTER CENTERNAM)

236 -1 237 11.05

236 -1 298 10.05

362 -1 361 10.05

362 -1 361 10.05

578 -1 505 25.25

578 1 579 28.95

578 -2 743 27.15

745 -2 743 37.15

1024 11 126 60.80

1125 1 1216 60.80

1364 11 1305 65.25

1448 -19 1457 77.55

1770 -2 1625 84.95

FEAK FO CENTER CENTER(HM)
173 -17 174 6.70
237 -2 235 11.75

297 -3 294 14.70
360 1 361 18.06
431 -2 429 25.10
571 4 575 25.10
571 4 575 26.75
744 -1 743 37.15
631 -3 626 37.15
631 -3 626 12.0
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1125 0 1124 55.20
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	1003	54.65 H																						
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	X	Ħ	_																					
	=	9.30 MM	CENTER KK)	0.0	8:3		21.00	25, 35	20.95	32.65	37.15	. 41. 45		26.00	60.65	65.10	69.50	73.45	77.30	80.02	8.8	96.10	91.10	
		•																						
	Ħ	Ħ	CENT	176	2 30		436	507	579	653	743	629	776	1120	1213	1302	1390	1469	1546	1619	1697	1762	1 822	1665
-	193	74.65 E	8	-28	•	0	• -	ņ	7	•	0	4	7	•	•	•	ņ	•				•	-	11
	1 . 10		PEAK	186	239	295	435	808	280	999	743	838	626	1021	1209	1256	1393	1473	1545	1629	1656	1762		•
	MCAT TO. 15	N6. 15 1093 XI - 186 XZ - 1	N6. 15 1093 XI = 186 XZ = 1 54.65 MM XI = 9.30 MM XZ =	N6. 15 1093 XI - 186 XZ - 1 54.65 MM XI - 9.30 MM XZ - KO CEMTER CENTER(MM)	No. 15 1093 X1 - 186 X2 - 1 54.65 MM X1 - 9.30 MM X2 - X0 CEPTER CENTER MM) 5 -26 176 6.80	NG. 15 1093 X1 = 186 X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 K0 CENTER CENTER(MM) 6 -26 176 6.80 9 0 239 11.95	No. 15 1093 X1 = 186 X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 K0 CENTER CENTER(MM) 5 -26 176 8.80 6 0 239 11.95 7 0 259 14.95	NG. 15 1093 XI = 186 XZ = 1 54.65 MM XI = 9.30 MM XZ = 1 KO CRUTER CENTER MM) 6 -28 176 8.80 9 0 2.39 11.95 6 0 259 14.95 7 -6 361 16.05	NG. 15 1093 X1 = 186 X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 K0 CRPTER CENTER(MM) 5 -28 176 8.80 6 0 259 11.95 7 -6 359 11.95 7 -6 359 21.90 9 -2 507 25.35	NG. 15 1093 X1 = 186 X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 K0 CRMTER CENTEN MM) 5 -28 176 8.80 6 0 239 11.95 7 -6 361 18.05 5 1 436 21.80 5 -2 507 25.35 6 -1 579 25.35	NG. 15 1093 XI = 186 XZ = 1 S4.65 NM XI = 9.30 NM XZ = 1 KO CRIMTER CENTER(MM) C 29 176 8.80 D 259 11.95 T -6 361 18.05 T -6 361 21.80 S -1 579 28.95 D -1 579 28.95	NG. 15 1093 X1 = 186 X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 KO CENTER CENTER MM) 5 -26 176 8.80 6 0 259 11.95 7 -6 361 18.05 7 -6 361 21.80 9 0 259 21.80 9 0 259 21.80 9 0 259 21.80 9 14.95 9 0 743 37.15	N6. 15 1093 X1 = 186 X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 KO CENTER CENTER MM KO CENTER CENTER MM FO 259 11.95 7 -6 361 18.05 7 -6 361 18.05 7 -6 361 21.80 8 -7 653 32.65 8 -6 629 41.45	NG. 15 1093 X1 = 186 X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 X0 CKMTRR CENTER(MM) 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 55.65 MM X1 = 9.30 MM X2 = 1 56.65 MM X1 = 9.30 MM X2 = 1 56.65 MM X1 = 9.30 MM X2 = 1 56.65 MM X1 = 9.30 MM X2 = 1 56.65 MM X1 = 9.30 MM X2 = 1 56.65 MM X1 = 9.30 MM X2 = 1 56.65 MM X1 = 9.30 MM X2 = 1 56.65 MM X1 = 9.30 MM X2 = 1 56.65 MM X1 = 9.30 MM X2 = 1 56.60 MM X1 =	NG. 15 1093 X1 = 186 X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 X0 CRMTRR CENTER(MM) 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 55.65 MM X1 = 9.30 MM X2 = 1 56.65 MM X1 = 1.00 MM X2 = 1 56.65 MM X1 = 1.00 MM X2 = 1 56.65 MM X1 = 1.00 MM X2 = 1 56.65 MM X1 = 1.00 MM X2 = 1 56.65 MM X1 = 1.00 MM X2 = 1 56.65 MM X1 = 1.00 MM X2 = 1 56.65 MM X1 = 1.00 MM X2 = 1 56.65 MM X1 = 1.00 MM X2 = 1 56.65 MM X1 = 1.00 MM X2 = 1 56.65 MM X1 = 1.00 MM X2 = 1 56.65 MM X1 = 1 56.65 MM X2 = 1 56.65 M	NG. 15 1093 X1 = 186 X2 = 1 S4.65 MM X1 = 9.30 MM X2 = 1 X0 CENTER CENTER UNI B -26 176 8.80 C 259 11.95 T 659 14.95 T 659 25.35 T 7 659 32.65 T 659 32.65 T 659 32.65 T 659 32.65 T 7 659 35.65 T 7 659 56.06 T 7 659 56.06	N6. 15 1093 X1 = 186 X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 K0 CRMTER CENTER(MM) 6 -26 176 8.80 7 -6 361 11.95 7 -6 361 11.95 7 -6 361 21.96 8 -2 507 22.35 0 -7 43 37.15 0 -7 653 32.65 0 -7 653 32.65 0 -7 653 37.15 1 922 46.10 1 -4 1017 50.65 6 4 1213 66.65	NG. 15 1093 X1 = 186 X2 = 1 S4.65 NM X1 = 9.30 NM X2 = 1 K0 CRMTER CENTEM NM) 0 239 11.95 0 259 14.95 1 436 22.35 0 -1 579 22.35 0 -1 579 22.35 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95 0 -1 579 26.95	NG. 15 1093 XI = 186 XZ = 1 S4.65 NM XI = 9.30 NM XZ = 1 XO CRUTER CENTER(NM) C 29	N6. 15 1093 X1 = 186 X2 = 1 54.65 MM X1 = 9.30 MM X2 = 1 KO CRWTER CENTER UM) 54.65 MM X1 = 9.30 MM X2 = 1 C 259 11.95 7 -6 391 14.95 7 -6 391 14.95 7 -6 391 22.65 9 -7 659 22.95 9 -7 659 22.95 9 -7 659 25.95 9 -1 579 26.95 9 -1 120 56.00 9 -1 120 56.00 9 -1 120 56.00 9 -1 120 56.00 9 -1 120 56.00 9 -1 120 56.00 9 -1 150 60.65 9 -1 150 60.65	1003 X1 = 100 X2 = 1 1003 X1 = 100 X2 = 1 X	N6. 15 1093 XI = 186 XZ = 1 54.65 MM XI = 9.30 MM XZ = 1 XO CRMTER CENTER MM 0 259 11.95 1 436 Z2 16.95 0 -1 579 Z2 35 0 743 Z2 50.95 0 743 Z2 65.00 1 1213 66.65 0 4 1302 65.10 1 1546 77.30 1 1546 77.30	N6. 15 1093 XI = 186 XZ = 1 S4.65 NM XI = 9.30 NM XZ = 1 XO CRUTER CENTER(MM) 2.2 176 8.80 0 259 11.95 0 259 14.95 1 436 25.05 0 743 32.65 0 743 37.15 0 743 37.15 0 743 65.00 1 120 65.00 1 1546 77.30 2 11619 80.95	N6. 15 1093 XI = 186 XZ = 1 54.65 MM XI = 9.30 MM XZ = 1 XO CRUTER CENTER(MM) 50. 259 11.95 7 .6 351 11.95 7 .6 351 11.95 7 .6 351 12.95 7 .6 351 12.95 8 .7 653 32.65 9 .7 653 32.65 9 .7 653 32.65 9 .1 576 69.50 9 .1 120 69.50 9 .1 1546 77.30 9 .1 1697 86.10 1 1697 86.10 1 1697 86.10 1 1697 86.10 1 1697 86.10 1 1697 86.10 1 1697 86.10 1 1697 86.10 1 1697 86.10 1 1697 86.10 1 1697 86.10 1 1697 86.10 1 1697 86.10

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CENTER ME) 10,95

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55	304	367	011	510	563	658	745	635	\$23	1018	1111	1209	1301	1384	1466	1543	1616	1689	1757	1015	1991	
ņ	-		-	•	•	Ą	٠,	•	ę		m•	-		1	-	•	-		-	•	56	
•	0	•	439	210	587	•	•	831	N	N	1117	•	0	1366	1465	1543	1617	1691	1756	1018	1965	

1056	92.80																						
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223	11.15 NK		13.1	12.55	4	9.0	2.1	5.6	4.0	3.3	7.5	۲.	6.2	1.0	5.7		4.8	9.0	3.0	6.9	0.5	4.2	7.5
. IX	H		262	251	309	372	442	513	589	999	750	835	954	1020	~	N	N	m	1461	S.	•	•	
	2.05 MM		2 2		ņ	F	ě.	Ŷ	-	e.	-	-	•	1	7	-10	٠,	•	7	•	~	-	~
T - 12	•	•	FEAL	259	312	E.	447	519	568	599	751	836	933	0	1115	N	W	•	1462	S	•	1685	-

SCAM MG. 18

T = 1315 X1 * 252 X2 * 1627 T = 65.75 MX X1 * 12.60 MX X2 * 91.35 MX

257 -25 246 12.40
319 -4 315 15.75
381 -2 379 18.95
384 -1 448 22.40
596 -2 379 18.95
596 -2 379 22.40
574 1 755 31.60
677 -5 672 31.60
677 -5 672 31.60
677 -5 672 31.60
1114 -3 1111 35.55
1264 0 1294 66.55
1165 -6 1290 64.50
1371 5 1290 64.50
1454 -2 1452 72.60
1607 -1 1606 80.30
1607 -1 1606 80.30
1609 -4 1736 66.90

SCAN N6. 19

T - 1389 X1 - 289 X2 - 1790 T - 69,45 MM X1 - 14,45 MM X2 - 69,50 M

33.00	36.10	42.20	46.25	51.00	55.45	29.90	64.15	68.30	72.25	76.15	79.85	83.25	86.35	89.50
•7•	762	944	928	1020	1100	1150	1283	1266	1445	1523	1597	1665	1727	1 790
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9	765	1	639	1018	1111	1200	1283	1366.	1448	1526	1557	1666	1727	1779

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300	16.60 MK
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T - 1463	73.15
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CENTER NE	16.45	20.02	23.25	26.70	30.35	34.30	38.45	42.50	46.70	51.00	55.30	59.65	63.75	67.95	71.90	76.00	•	82.65	65.50
CENTER	200	101	465	534	607	989	769	950	934	1020	1106	1151	1275	1359	1438	1520	1552	1653	1710
2	97-	7	•	7	7	ņ	•	m	0	~	7	ņ	1 0	7		0	0	0	•
PEAK	338	402	465	535	809	689	771	847	934	1018	1107	1193	1280	1360	1441	1520	1592	n	-

SCAN NG. 21

r - 1537 X1 - 393

76.85 MM XI * 19.65 MM X2 * 84.35 MM

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CENTER(NK)	20.55	20.05	23.65	27.15	30.05	34.55	38.60		46.75	51.05	55.25	59.45	ñ	67.70	71.65	75.35	78.60	61.95	
CENTER		107	**	543	617	159	277	855	935	1021	1105	1169	1271	1354	1433	1507	1572	1639	
2	•	-28	•	-	0	~	~	m	•	~	*	•		•	ç	~	•	-	
PEAK	393	429	477	344	617	693	776	652	935	1023	1106	1189	1273	1354		1505	1579	4	

 PEAK
 KO
 CENTER MAN

 464
 0
 402
 24-10

 500
 -11
 469
 24-45

 555
 0
 527
 31-35

 627
 0
 627
 31-35

 776
 -2
 776
 38-60

 856
 0
 856
 42-80

 940
 -3
 937
 46-85

 102
 2
 1022
 51-10

 1165
 -4
 1162
 55-15

 1265
 -1
 1166
 67-30

 1425
 -1
 1264
 67-30

 1491
 0
 1451
 74-55

 1560
 -1
 1559
 77-95

1625	76.25 KH															•			
2	2																		
255	27.75 IN	CENTER NR.)	.70	31.95		•						06.			•				
•	•																		
Ħ	ĸ	CENT	554	639	106	704	962	538	1021	660	1180	1256	1336	1413	1479				
	25 XX		-24	•	7	0	7	-									•	*	
1685	84.25			_	_	_		_	_		_		_					9	
•	•	PEAK	565	639	709	784	863	939	1020	1101	1180	1260	1335	1413	1479			BCAN.	
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R CENTER(MM)	34.80	36.20	39.65	43.15	47.10	51.05	54.80	58.70	62.40	44.40	
CENTER	96.9	724	793	863	942	1021	1096	1174	1248	1326	
2	•	-	•	~	•	•	-	0	•	0	
PEAK	678	725	793	865	246	1024	1095	1174	1251	1328	

SCAN MG, 25 T = 1833 XI = 890

T - 67.95 10f X1 - 33.90 10f

10		- FRINCE NUMBER	MOKBER	.	- SCAN NUMBER			•				
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.000 .000 .000 24.000 27.650 31.150 35.450 39.200 .000 .000 .000 22.550 26.450 30.700 34.200 38.850 .000 .000 16.500 19.000 22.950 26.450 30.700 34.200 38.850 .000 16.500 19.000 22.550 26.450 30.700 34.200 38.850 .000 16.500 19.000 22.550 26.450 30.700 34.200 38.150 .000 16.500 19.700 22.550 26.450 34.200 34.200 38.150 .000 15.150 18.400 22.550 26.450 37.450 37.450 .000 18.000 18.750 21.400 22.650 26.450 37.450 37.450 .000 18.000 17.950 21.400 25.250 26.450 37.450 37.150 .000 18.750 17.950 21.400 25.250 26.450 37.450 37.150 .000 18.750 18.500 21.400 25.250 28.450 32.450 37.150 .000 18.750 18.500 21.400 25.250 28.450 32.450 37.150 .000 18.750 18.500 21.400 25.250 28.450 37.450 37.150 .000 18.750 18.500 27.450 27.150 37.150 .000 18.750 18.500 27.150 26.150 37.250 .000 18.750 18.750 27.150 27.150 37.150 .000 18.750 18.750 27.150 37.150 .000 18.750 18.750 27.150 37.150 .000 .000 .000 .000 .000 .000 .000		000	000	000	000	000	000	000	36.050	39.800	43.750	
. 000 . 000 19.000 22.550 26.950 30.700 34.850 38.850 . 000 16.500 19.000 22.550 26.950 30.700 34.150 38.100 38.150 . 000 16.500 19.000 22.550 26.050 30.700 34.150 38.160 . 000 16.500 19.000 22.550 26.050 30.200 34.100 38.150 12.250 15.100 18.750 22.350 25.650 37.350 37.650 11.850 14.950 18.050 21.450 25.250 26.950 32.950 37.150 11.750 14.750 17.950 21.450 25.250 28.550 37.150 11.750 14.750 18.050 21.450 25.250 28.550 37.150 11.750 14.750 18.050 21.450 25.250 28.550 37.150 11.750 14.750 18.050 21.450 25.250 28.950 32.450 37.150 11.750 14.750 18.050 21.450 25.250 28.950 32.450 37.150 11.750 15.200 18.050 21.450 25.250 20.450 32.450 37.150 11.750 15.200 18.500 22.100 25.250 20.450 37.150 37.150 11.250 15.200 18.500 22.100 25.250 20.450 37.450 37.250 12.400 15.200 18.500 22.100 25.500 37.450 37.500 12.250 15.200 18.500 22.100 25.500 37.450 37.500 12.250 15.200 18.500 22.100 25.200 20.450 37.450 37.500 12.250 15.200 16.500 27.150 37.450 37.500 12.200 10.000 20.000 20.000 35.400 39.200 30.450		000	000	000	000	000	26.100	31.850	35.450	39.200	43.500	
. 000 16.500 19.900 22.950 26.950 30.700 34.550 38.700 10.300 16.500 19.700 22.950 26.450 34.250 34.200 38.400 12.350 15.350 19.000 22.550 25.850 26.850 34.100 37.150 12.350 15.100 16.350 22.950 25.850 26.850 37.300 37.150 11.750 14.900 16.350 21.750 25.650 26.550 32.950 37.150 11.750 14.750 17.950 21.400 25.250 28.850 32.950 37.150 11.750 14.750 14.750 12.200 21.450 25.250 28.800 32.650 37.150 11.950 16.350 21.400 25.250 28.800 32.650 37.150 11.950 15.200 18.350 22.100 28.550 29.950 37.150 11.950 15.200 18.350 22.100 25.250 28.800 32.650 37.150 11.950 15.200 18.350 22.100 25.500 29.950 37.500 37.500 12.250 15.200 18.350 22.100 25.500 32.600 37.500 12.250 15.200 18.350 22.100 25.500 29.950 33.900 37.500 12.250 15.200 18.350 22.100 25.500 33.900 37.500 12.250 15.200 18.350 22.100 25.500 33.900 37.500 12.250 15.200 18.350 22.100 25.500 33.900 37.500 12.250 15.200 18.350 22.100 25.500 33.900 33.900 37.500 12.250 16.450 22.100 25.500 33.900 33.900 39.200 .000 .000 .000 35.900 35.900 39.200 .000 .000 .000 .000 .000 .000 .000		000	000	000	000	24.000	27.650	31.150	35.000	36.850	43.100	
.000 16.500 19.700 22.550 26.650 34.200 38.400 31.2350 19.000 16.350 19.000 22.550 26.050 29.800 34.600 39.150 12.250 15.600 18.750 22.650 29.800 34.650 37.650 12.250 15.600 18.350 21.750 25.650 29.850 37.300 37.150 11.850 14.750 18.050 21.600 25.250 32.950 37.050 37.150 11.750 14.750 18.050 21.600 25.250 28.550 32.950 37.150 11.750 14.750 18.050 21.600 25.250 28.650 32.650 37.150 11.750 14.750 18.050 21.600 25.250 28.650 32.650 37.150 11.750 14.750 18.050 21.600 25.250 28.950 32.650 37.150 11.500 18.750 18.050 21.800 25.250 28.950 32.650 37.150 11.500 18.750 18.050 22.100 25.250 28.950 32.650 37.250 12.250 15.200 18.050 22.100 25.250 28.950 33.300 37.250 12.250 15.250 18.050 22.100 25.500 29.200 33.900 37.250 12.250 15.250 18.550 22.100 25.250 29.950 33.900 37.250 12.250 15.250 18.550 22.150 20.250 29.950 33.900 37.250 12.250 16.500 22.100 25.250 29.950 33.900 37.250 12.250 16.500 22.100 25.250 29.950 33.900 37.250 12.250 16.250 22.150 25.250 29.950 33.900 37.250 12.250 16.250 22.150 25.250 29.950 33.900 37.250 12.250 16.250 22.150 25.250 29.950 33.900 37.250 12.250 16.250 22.150 25.250 29.950 33.900 37.250 10.000 16.450 20.050 23.250 26.700 30.350 34.300 39.450 10.000 16.450 20.050 23.250 29.950 33.950 39.450 10.000 10.		000	000	000	19.900	23.550	26.950	30.700	34.550	36.700	42.850	
12.350 15.150 18.750 22.350 26.050 33.650 34.100 38.150 12.350 15.150 18.750 22.350 25.850 33.650 37.650 12.250 15.150 18.750 22.350 25.850 33.950 37.550 12.250 15.150 18.350 21.750 25.250 26.550 37.300 37.150 11.750 14.750 17.950 21.400 25.250 28.550 32.950 37.150 11.750 14.750 18.050 21.400 25.250 28.950 32.950 37.150 11.750 14.750 18.050 21.400 25.350 28.950 32.650 37.150 11.750 14.750 18.050 21.400 25.350 28.950 32.650 37.150 11.750 14.750 18.050 21.400 25.350 28.950 32.650 37.150 11.750 15.450 18.500 22.100 25.350 28.950 32.650 37.250 12.250 15.450 15.450 22.100 25.350 29.450 37.250 12.250 15.450 22.100 25.500 29.450 37.250 12.400 15.450 22.100 25.500 29.450 37.250 12.400 15.450 22.100 25.450 29.450 37.250 12.400 15.450 22.100 25.500 29.450 37.250 12.400 15.450 22.100 25.500 29.450 37.250 12.400 15.450 22.100 27.750 37.400 37.250 12.400 15.450 22.100 27.750 37.400 37.250 12.400 15.450 22.100 27.750 37.400 37.250 12.400 15.450 22.100 27.750 37.400 37.250 12.400 15.450 22.100 27.750 37.400 37.500 37.200 10.400 10		000	000	16.500	19.700	22.950	26.450	30.250	34.200		42.650	
12.350 15.600 18.750 22.350 25.650 33.650 37.650 12.250 15.150 18.400 22.050 25.650 26.550 37.900 37.650 11.200 16.100 18.350 21.400 25.250 28.950 37.900 37.150 11.750 14.700 18.050 21.400 25.250 28.650 32.950 37.150 11.950 14.700 18.050 21.400 25.250 28.750 37.150 11.950 14.750 18.050 21.400 25.250 28.750 37.150 11.950 14.750 18.050 21.400 25.250 28.750 37.150 11.950 14.950 22.100 25.250 22.500 37.250 37.250 12.400 15.450 18.600 22.100 25.250 32.400 37.500 12.400 18.500 22.100 25.250 32.400 37.250 12.400 18.500 22.100 25.450 33.400 <td></td> <td>000</td> <td>000</td> <td>16.350</td> <td>19.000</td> <td>22.550</td> <td>26.050</td> <td>29.950</td> <td>34.100</td> <td>36.150</td> <td>45.300</td> <td></td>		000	000	16.350	19.000	22.550	26.050	29.950	34.100	36.150	45.300	
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FRINCE-PEAK POSITIONS PES(J,K) RESULTING FROM AUTOMATIC SCANNI) J + FRINCE NUMBER K = SCAN NUMBER 2

NSS (NST) - 25

CT -

RADIOS

J2 (MF2) -

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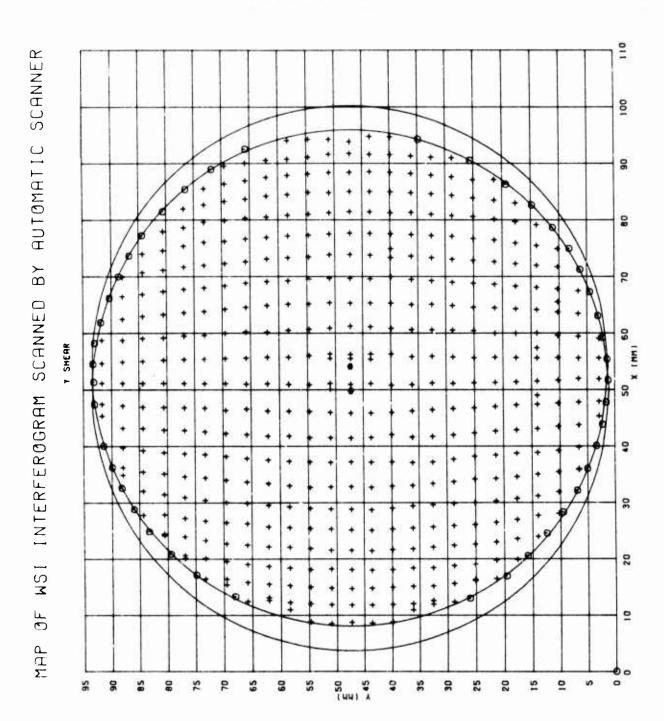
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Printer Plot

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CALCOMP Plot



APPENDIX D

REGISTRATION OF INTERFEROGRAMS

The registration of the fringe-peak data obtained from scanning a pair of x and y-sheared interferograms is equivalent to the coordinate transformation of these two sets of fringe data to a common coordinate system. Fiducial marks placed in an interferometric test system are generally used to identify coordinates of the test lens, thereby permitting subsequent registration of fringe data from two or more scanned interferograms. However, such an approach usually results in the partial obscuration of fringes and, in addition, requires that the scanning system, or operator, distinguish between fiducial marks and fringes. The present approach for registering interferograms from the WSI uses such fiducual marks, but owing to the inherent stability of the WSI, a second set of interferograms identical to an earlier set except for the absence of fiducial marks within the aperture is taken and used for scanning.

The main data-reduction computer program performs the registration of the x and y-sheared interferograms provided that the fringe-peak data from the scanner are in a required format. The data-reduction program assumes the following: (1) shear directions were along the positive x and negative y axes for the x and y-sheared interferograms, respectively; and (2) the y-sheared interferogram was obtained by rotating either the test lens 90° clockwise or the cube interferometer 90° counterclockwise as viewed from the back of the cube. A left-hand cartesian coordinate system chosen to ensure that the fringe data will satisfy both conditions for registration is illustrated in Figure 36.

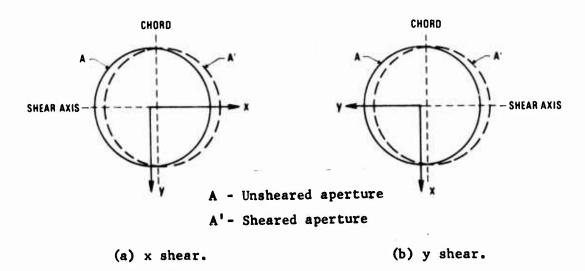


Figure 36. - Coordinate system for WSI interferograms.

As shown in figure 36, the shear direction, or shear axis, is perpendicular to an imaginary chord connecting the two points of intersection of the original and sheared aperture boundaries. Since the interferogram is scanned parallel to the shear axis, it is necessary to locate this axis on both the x and y-sheared interferograms. The simple construction of the shear axis by drawing line perpendicular to the chord connecting the two points of intersection of the original and sheared aperture boundaries is generally not an accurate method; these points of intersection are not very distinct in the resulting interferograms since the shear distance is typically only a few percent of the test-lens diameter. The approach used for locating the shear axis is based on the following property of a lateral-shearing interferometer with a fixed shear angle such as the WSI: the number of fringes in the fringe pattern of a test lens can be increased until all the fringes eventually appear straight and parallel to the shear axis even for a lens with large aberrations. As the cube interferometer is moved along the testsystem optical axis and away from the test-lens focus, the tilt between the unsheared and sheared wavefronts is increased, thereby increasing the number of fringes.

The test and scanning procedures used to ensure the proper registration of the fringe data from the s and y-sheared interferograms are outlined in the following steps and illustrations. It is assumed that the test lens and cube interferometer have been aligned using cross hairs as discussed in section 11.3 and that a fringe pattern is visible in the film plane.

(1) Place right-angle cross hairs near test lens so that a sharp image of these cross hairs is formed in film plane; place a small and different pattern on each cross hair at bottom and right side near aperture edge; mark test-lens edge or mounting collar at bottom and right side so that these fiducial marks conicide with shadows of cross hairs as shown in figure 37.

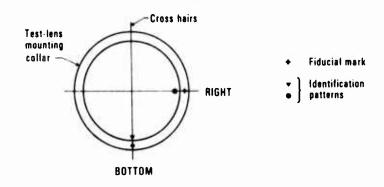


Figure 37.- Schematic of test lens with cross hairs, fiducial marks, and identification patterns as viewed from cube interferometer.

(2) Move cube interferometer along test-system optical axis and away from test-lens focus until fringes are so numerous (typically 75 to 100 fringes) that they all appear straight; rotate the cube interferometer about test-system optical axis until these fringes are parallel to one of the cross hairs as shown in figure 38.

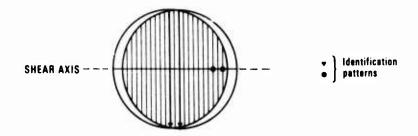
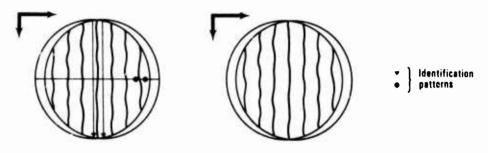


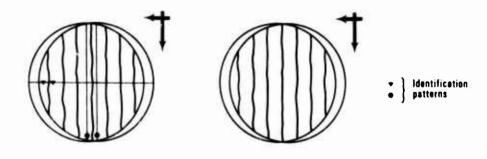
Figure 38. - Schematic of WSI fringe pattern with cross hairs and identification patterns.

- (3) Move cube interferometer back along test-system optical axis and towards test-lens focus to selected test position (£ setting); photograph resulting fringe pattern (x-sheared interferogram) with and without cross hairs.
- (4) Replace cross hairs and rotate either cube interferometer 90° counterclockwise or test lens 90° clockwise as viewed from back of cube interferometer; photograph resulting fringe pattern (y-sheared interferogram) with and without cross hairs. Note if test lens is rotated, the small patterns on the cross hairs will have to be removed and also rotated 90° clockwise.
- (5) Mark each of the resulting four interferograms with left-handed Cartesian-coordinate axes outside of fringe pattern; for automatic scanning, these axes should also be outside region of scanning; positive direction of these axes is in direction of small patterns on cross

hairs, i.e., towards bottom and right side of lens; x-axis is roughly parallel to shear axis in x-sheared interferogram, and y-axis is roughly parallel to shear axis in y-sheared interferogram; x-axis is longer than y-axis, and these axes terminate at origin in x-sheared interferogram and extend through origin in y-sheared interferogram as shown in figure 39. Note - if strip film is not used for photographing fringe patterns, the original orientation among the interferograms will have to be preserved until coordinate axes can be applied.



- (i) With cross hairs.
- (ii) Without cross hairs.
- (a) x shear.



- (i) With cross hairs.
- (ii) Without cross hairs.

(b) y shear.

Figure 39. - Schematic of WSI interferograms marked with coordinate axes to preserve relative orientation.

(6) Make photographic transparencies of both interferogram pairs using same magnification; these transparencies must have a size and fringe contrast ratio suitable for scanning and must be free of distortion; superimpose the two transparencies in each pair until aperture and fringes conincide; punch small holes (approximately 0.5 mm diameter) through each matched pair of interferograms at both ends of cross hairs as shown in figure 40.

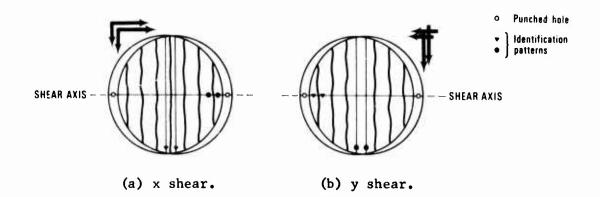


Figure 40. - Schematic of superimposed WSI interferograms with punched holes for manual-scanning alignment.

(7) Place interferogram without cross hairs on scanner with emulsion side facing pick-up optics (efflux side); scanning direction should be parallel to shear axis or imaginary line through centers of punched holes; orient x-sheared interferogram so that scan coordinates are increasing in directions of positive x and y-axes and orient y-sheared interferogram so that scan coordinates are increasing in directions of positive x-axis and negative y-axis as shown in figure 41. Note - the computer software should be modified to translate and interpolate fringe data if interferograms cannot be oriented so that automatic scanner scans parallel to shear axis.

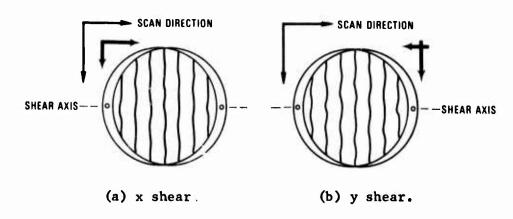


Figure 41. - Schematic of placement of WSI interferograms for scanning.

APPENDIX E

SPECIFICATIONS AND ASSEMBLY OF WSI CUBES

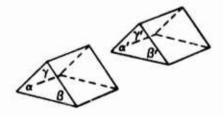
The parameters of the eight cubes assembled for the sponsor are given in table 2(b). The shear angles Φ are selected on the bases of the f-numbers of the optical systems expected to be tested and approximately twenty-five fringes in the interference pattern for a well-corrected optical system. The cube parameters ℓ and the minimum working distance are defined in figure 7.

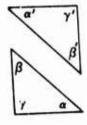
The prisms used to make the cube interferometers are high-purity synthetic fused silica (Suprasil 1-T19) with a high degree of optical homogeneity and uniform transmittance over the visible spectrum. The pair of prisms used for each cube is cut from the same original prism to assure that the two pairs of adjacent angles, α/α' and β/β' shown in figure 42, are equal. Therefore, the cube interferometer can be adjusted during assembly to provide equal optical paths for the two light beams. The tolerance on the 90° prism angle is \pm 1 minute, whereas the tolerance of \pm 30 minutes on the 45° angles is less stringent because the two prism for each cube are cut from the same original prism. If the prism angles are not within the specified tolerances, additional tilt may be introduced into the cube interferometer. However, this is not a serious problem for angular deviation less than about 1/2°.

$$\alpha = \alpha' = 45^{\circ}$$

$$R = R' = 45^\circ$$

$$\gamma = \gamma' = 90^{\circ}$$





(a) General view.

(b) End view.

Figure 42. - Schematic of pair of 45° - 90° - 45° prisms for WSI cube.

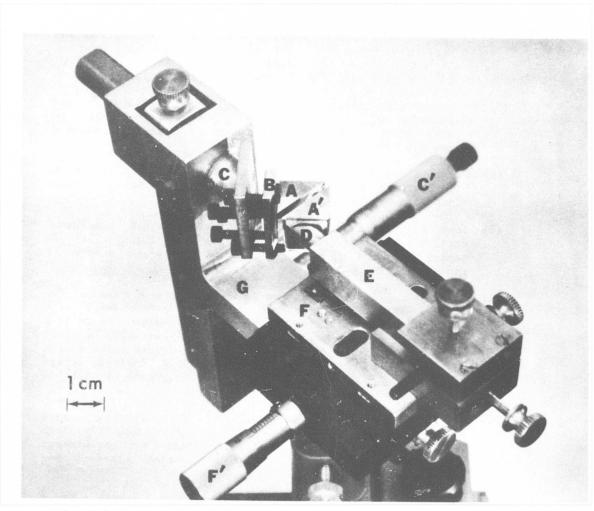
The sides of the prism, except the hypotenuse or base, are 13 mm in length. Thus, the assembled cube interferometer also measures 13 mm on a side. This choice for the cube dimension exceeds the minimum thickness required for testing relatively low f-number systems, as discussed in section VI.1, and provides cube surfaces which are not difficult to polish optically flat. All prism surfaces used to transmit or to reflect light are polished flat to $\lambda/10$ for λ = 546.1 nm. One surface on each prism has a vapor-deposited aluminum which is totally reflective for visible radiation and overcoated with silicon monoxide for protection. The hypotenuse face on one prism from each pair also has a bare vapor-deposited aluminum coating to provide the beam-dividing surface. It is unnecessary that this coating exhibit equal transmittance and reflectance; the two beams emerging from the cube interferometer will have traveled equal optical paths, and the resultant intensity of each beam will be the product of the transmittance and reflectance of the beam-dividing coating (neglecting minor absorption and scattering losses).

A 1.0-mm-thick glass plate is attached to the totally-reflective prism surface. This thin plate allows the prism to be mounted rigidly during assembly without directly damaging the reflective coating or the prism surface. After assembly of the cube, these plates could be removed or left in place provided their adhesion does not introduce stresses in the cube. In the present instance, no stresses are evident, and it has been decided that the removal of the glass plates is unnecessary.

The primary requirements for assembly of the cube interferometer are the following: (1) a mount for each prism; (2) controls for the independent movement of each prism in order to produce the fringe pattern and to adjust it for chromatic compensation; and (3) a control to rotate one prism about an axis perpendicular to its hypotenuse face in order to set the desired shear angle. For assembly of the present cube set, a special device was built and is shown in figure 43 with a pair of prisms mounted. This assembly rig consists basically of two separable parts or sub-assemblies - a prism mounting plate (B) attached to a shaft (C) and a prism mounting rod (D) housed in a block (E) attached to a translation stage (F); the two sub-assemblies are mounted in a frame (G). The differential micrometers (C' and F') provide very fine adjustments of the prisms. The steps required for assembling the cube interferometer from a pair of prisms with attached glass plates are as follows:

- (1) Prism A with partially aluminized base is attached to mounting plate B by fastening prism side (with glass plate) with hot wax.
- (2) Shaft C with attached plate B and prism A is secured in frame G; with a laser beam incident on the reflective prism base, the prism mounting plate B is adjusted until laser beam reflected from base does not shift while rotating shaft C.

After steps (1) and (2), the prism has effectively been adjusted so that its axis of rotation is now perpendicular to its reflective base.



A - Prism

A'- Prism

B - Mounting plate

C - Rotating shaft

C'- Micrometer

D - Mounting shaft

E - Housing block

F - Translation stage

F'- Micrometer

G - Frame

Figure 43.- Photograph of device for assembling WSI cube.

- (3) Frame G is tilted so that base of prism A is horizontal; other prism A' is placed on prism A with their bases congruent; other sub-assembly is placed in frame and prism A' is fastened to mounting shaft D with adhesive.
- (4) Prisms are then separated by withdrawing mounting shaft D and Translating stage F; cement for attaching two prisms together is poured onto base of prism A, and prism A' is repositioned so that prism bases are nearly parallel and touching.

After steps (3) and (4), the cube is ready for fringe adjustments.

- (5) Monochromatic light (Hg-arc lamp with 546.1-nm filter) illuminates cube, and prism A' is adjusted by controls on housing block E until cube images projected onto viewing screen are congruent.
- (6) Prism A' is moved very slowly with translation stage F until high-contrast fringes appear; controls on housing block E are adjusted until fringes are horizontal.
- (7) Lamp filter is removed and translation stage F is adjusted until black fringe (zero order for white light) lies in center of cube image on screen; mercury-arc source is replaced by He-Ne laser.
- (8) Laser beam is incident on entrance face of cube and two sheared beams emerge from exit face; prism A is rotated with shaft C until measured separation of emergent beams at a known distance yields the desired shear angle; alternatively for small shear angles (about 6 mrad or less), a point source is used and prism A is adjusted until a desired fringe spacing at a known distance is obtained; prisms are left in this position until cement sets.
- (9) Mounting plate B is separated from cube by slight pressure required to break wax bond; cube is freed from mounting shaft D by a means which depends on choice of adhesive (for present cubes, a firm mechanical blow to housing block E was satisfactory).

After steps (5) through (9), the cube interferometer with a fixed value of shear is complete.

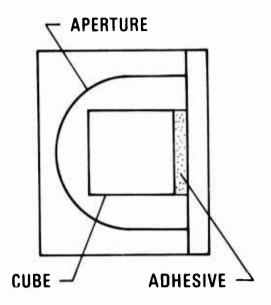
Complete assembly of each cube interferometer required two to three days; the cube was allowed to set for two days before being separated from the assembly rig.

The cement used to seal the two prisms together is a silicone resin (Sylgard 184) which is a low-viscosity liquid during application. After setting, this material is clear with a index of refraction (1.430) in the visible region close to that of the prisms (1.460), thereby permitting nearly perfect chromatic compensation for a very thin layer between the prisms. In addition, Sylgard 184 is

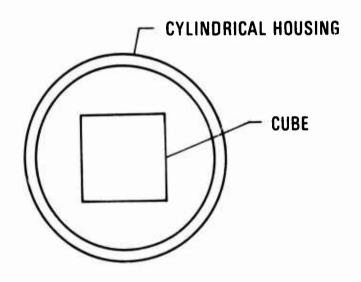
noncorrosive to both glass and aluminum and has a potting life of over two hours at 25°C so that sufficient time is available to adjust the prisms. Also, Sylgard is readily soluble in trichloroethylene, thereby allowing the prisms to be cleaned easily without damage whenever the assembly must be redone or excess Sylgard oozes out onto the cube faces. However, it is necessary to put the Sylgard in a vacuum (70 mm Hg) to outgas air bubbles trapped during mixing of the base and curing agent. Sylgard is also used to attach the glass plates to the prisms. Since this resin has low shrinkage during cure and 100 percent elongation, there should be very little, if any, stresses induced in the prisms by the resin. On a cautionary note, it should be added that the linear coefficient of thermal expansion of Sylgard is about 500 times higher than the prism fused silica at room temperature (22°C); therefore, the cube interferometers should not be subjected to large thermal gradients during use.

The adhesive used to attach prism A' to the mounting shaft D is an extremely fast drying (a few seconds) liquid (Eastman Kodak 910). The drying speed of this adhesive allowed assembly of the prisms to proceed without delay, and the high strength provided a very secure bond for one prism. Eastman 910 could be been used for mounting both prisms, but separation of the finished cube from the assembly rig would have been very difficult. However, the rapid drying introduces stresses into the attached prism, and these are evidenced by distorted fringes which appear during assembly; they vanish when the cube is removed from the assembly rig.

The cube should be mounted in a holder to facilitate laboratory use; a suggested holder is shown in figure 44. A commercial two-part epoxy adhesive was used to fasten the present cubes in the holders. A final inspection of the cube mounted in the holde: should be made to determine if the cube is free of aberrations. For this test, a point source is placed close to the cube entrance face, and the resulting interference pattern is examined. Deviations of these fringes from straight parallel lines indicate surface imperfections. fringes are rotated with respect to the intended shear direction, additional tilt is present. This method of inspecting the cube may reveal a relatively large cumulative error across the cube. Since only a small part of the cube is usually used for lens testing, particularly for high f-number lenses, another approach is suggested for determining local aberrations. In this method, a near diffraction-limited lens is stopped down to essentially diffractionlimited conditions, and after aligning the front surface of the cube normal to the optical axis of the lens, the cube is placed near the focal plane of the lens as shown in figure 2 or 3. With only a few fringes in the field, this method can be very sensitive to small aberrations (less than $\lambda/20$) in the cube. The cube can be moved laterally and, therefore, inspected over most of its surface. The fringe patterns can also be photographed and scanned to provide a quantitative analysis of any aberrations present.



(a) Side view.



(b) End view.

Figure 44. - Schematic of cylindrical holder for WSI cube.

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